

1 Article

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# Three-dimensional laser printing of macro-scale glass

  
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## objects at a micro-scale resolution

4 Peng Wang<sup>1,2,3</sup>, Wei Chu<sup>2,6,8</sup>, Wenbo Li<sup>2,4</sup>, Yuanxin Tan<sup>2,3</sup>, Fang Liu<sup>4</sup>, Min Wang<sup>5,6</sup>, Jia Qi<sup>2,3</sup>, Jintian  
5 Lin<sup>2</sup>, Fangbo Zhang<sup>2,3</sup>, Zhanshan Wang<sup>1</sup>, Ya Cheng<sup>2,5,6,7,9</sup>6 <sup>1</sup> School of Physics Science and Engineering, Tongji University, Shanghai 200092, China;  
7 wangpeng2015@siom.ac.cn (P. W.); wangzs@tongji.edu.cn (Z. W.)8 <sup>2</sup> State Key Laboratory of High Field Laser Physics, Shanghai Institute of Optics and Fine Mechanics,  
9 Chinese Academy of Sciences, Shanghai 201800, China; liwb@shanghaitech.edu.cn (W. L.);  
10 tanyx@siom.ac.cn (Y. T.); qijia@siom.ac.cn (J. Q.); jintianlin@siom.ac.cn (J. L.); fbzhang@siom.ac.cn (F. Z.)11 <sup>3</sup> University of Chinese Academy of Sciences, Beijing 100049, China12 <sup>4</sup> School of Physical Science and Technology, ShanghaiTech University, Shanghai 200031, China;  
13 liufang@shanghaitech.edu.cn (F. L.)14 <sup>5</sup> State Key Laboratory of Precision Spectroscopy, East China Normal University, Shanghai 200062, China;  
15 mwang@phy.ecnu.edu.cn (M.W.)16 <sup>6</sup> XXL—The Extreme Optoelectromechanics Laboratory, School of Physics and Materials Science, East China  
17 Normal University, Shanghai 200241, China18 <sup>7</sup> Collaborative Innovation Center of Extreme Optics, Shanxi University, Taiyuan 030006, Shanxi, China19 <sup>8</sup> Correspondence: chuwei@siom.ac.cn20 <sup>9</sup> Correspondence: ya.cheng@siom.ac.cn

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22 **Abstract:** Three-dimensional (3D) printing has allowed for production of geometrically complex 3D  
23 objects with extreme flexibility, which is currently undergoing rapid expansions in terms of  
24 materials, functionalities, as well as areas of application. When attempting to print 3D  
25 microstructures in glass, femtosecond laser induced chemical etching (FLICE) – which is a  
26 subtractive 3D printing technique – has proved itself a powerful approach. Here, we demonstrate  
27 fabrication of macro-scale 3D glass objects of large heights up to ~3.8 cm with an identical lateral  
28 and longitudinal spatial resolution of ~20  $\mu$ m. The remarkable accomplishment is achieved by  
29 revealing an unexplored regime in the interaction of ultrafast laser pulses with fused silica which  
30 results in aberration-free focusing of the laser pulses deeply inside fused silica.31 **Keywords:** ultrafast laser microfabrication; 3D glass printing; light field manipulation

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### 1. Introduction

34 Thanks to the ultrashort pulse durations ranging from femtosecond to tens of picoseconds and  
35 the ultrahigh repetition rates enabling the efficient and high throughput machining of materials,  
36 ultrafast lasers nowadays have been widely adopted in fabricating three-dimensional (3D)  
37 microstructures in various transparent materials[1-7]. In particular, ultrafast lasers have enabled  
38 fabrication of geometrically complex 3D microstructures in glass for a variety of applications ranging  
39 from microfluidics and microoptics to micromechanics. Generally speaking, ultrafast laser pulses  
40 with sub-ps durations are considered more advantageous than the picosecond laser pulses in terms  
41 of the highest achievable spatial resolution as well as energy deposition efficiency as the shorter the  
42 laser pulse durations, the less significant the thermal diffusion and the stronger the interaction of the  
43 laser pulses with the materials owing to the enhanced peak intensities[8]. For instance, when  
44 combining the focusing power of high numerical aperture (NA) lenses and the extreme sensitivity in  
45 the response of large bandgap glass materials to the laser intensity, the femtosecond laser pulses have  
46 enabled to achieve nanoscale resolution in both surface and in-volume structuring of glass[9,10]. The

47 facts seemingly encourage to choose only high-NA objectives for high resolution 3D structuring of  
48 glass owing to a rapid degradation of the axial resolution with the decrease of the NA. With the  
49 diffraction of light waves, the axial resolution is inversely proportional to the NA of the focal lens in  
50 the linear interaction regime, and the resolution can be further spoiled when the nonlinear self-  
51 focusing of the pulses is taken into account[11].

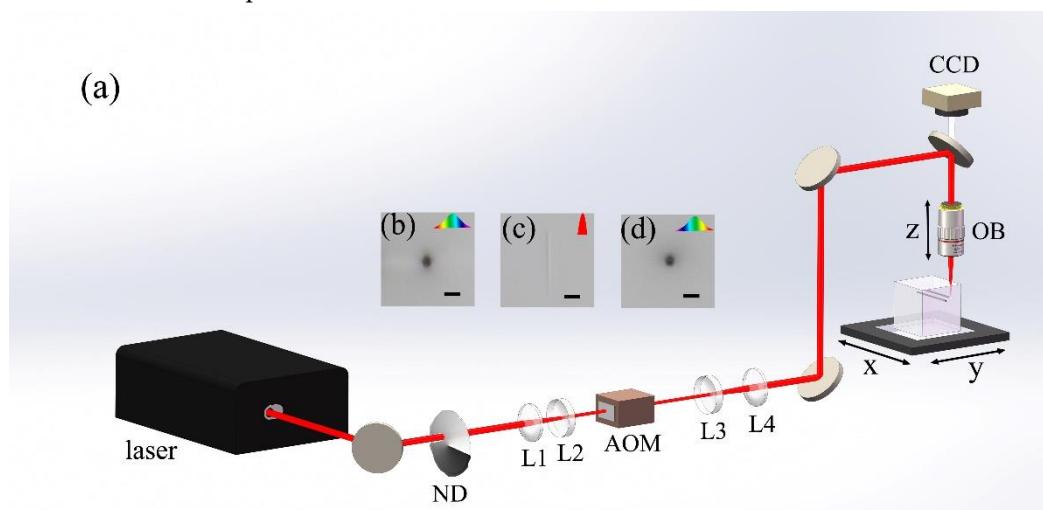
52 Unfortunately, the high-NA focal systems are inherently of short working distances. Thus, the  
53 depth of focal position in the glass allowed by the high-NA lens is typically limited to a few  
54 millimeters, which is often desirable to be significantly extended. Previously, a simultaneous  
55 spatiotemporal focusing (SSTF) scheme was proposed to tackle this problem, which is able to  
56 maintain a reasonable axial resolution even with low-NA focal lenses[12,13]. Recently, this scheme  
57 has enabled 3D micro-printing of fine-featured objects in polymer with heights up to 1.3 cm[14,15].  
58 Nevertheless, implementation of the SSTF scheme adds extra complexity and cost in femtosecond  
59 laser 3D micromachining. Here, we show an amazing and unexpected finding that a nearly spherical  
60 modification volume can be produced at arbitrary depths within fused silica with a low-NA focal  
61 lens by properly chirping the femtosecond laser pulses into picosecond laser pulses. In other words,  
62 one can now achieve aberration-free focusing using long working distance focal lenses regardless of  
63 the focal position within fused silica. This unique characteristic provides an opportunity to  
64 accomplish laser printing of macro-scale 3D objects in glass at a micro-scale resolution in an easy and  
65 flexible manner, which has never been achieved in FLICE despite the great effort spent on it over the  
66 past two decades.

## 67 2. Materials and Methods

68 The experimental setup is schematically illustrated in Figure 1. A Yb: KGW femtosecond laser  
69 (Pharos PH1-SP, Light Conversion) generated short pulses at 1030 nm wavelength with the highest  
70 single pulse energy at 1 mJ. The pulse duration can be continuously tuned from 0.19 to 10 ps with  
71 either a positive or a negative chirp. The repetition rate of the laser source can be adjusted between 1  
72 kHz and 1 MHz. When performing the glass 3D micro-printing, the laser power was controlled using  
73 an attenuator. The laser beam diameter was first reduced to 2 mm in diameter using a telescopic  
74 system, and then passed through an acousto-optical modulator (AOM). The AOM was triggered by  
75 a radio frequency signal from the controller of the transition stage to offer a fast shutter speed less  
76 than 100  $\mu$ s. Afterwards, the laser beam was expanded using a beam expander, and focused into the  
77 sample (i.e., a 55 mm-thick cube of fused silica) using a 5  $\times$  objective lens (M Plan Apo NIR,  
78 Mitutoyo Corporation) with a numerical aperture (NA) of 0.14. The objective lens features a long  
79 working distance of 37.5 mm, enabling the fabrication of structures with heights up to 5 cm in fused  
80 silica. A 1D stage (ANT130-110-L-ZS, Aerotech Inc.) was used to translate the objective lens along Z  
81 direction to control the depth of the focus position in the glass. The glass sample was mounted on an  
82 XY motion stage (ABL15020WB and ABL15020, Aerotech Inc.) which controls the lateral motion of  
83 the sample with a scan speed up to 30 mm/s at a sub-500 nm positioning precision. Both the  
84 translation stages were controlled by the machine controller (A3200, Aerotech Inc.) and synthesized  
85 with the AOM. The combination of the high scan speed and the high positioning precision facilitates  
86 the rapid 3D micro-printing of large structures in glass as will be shown below.

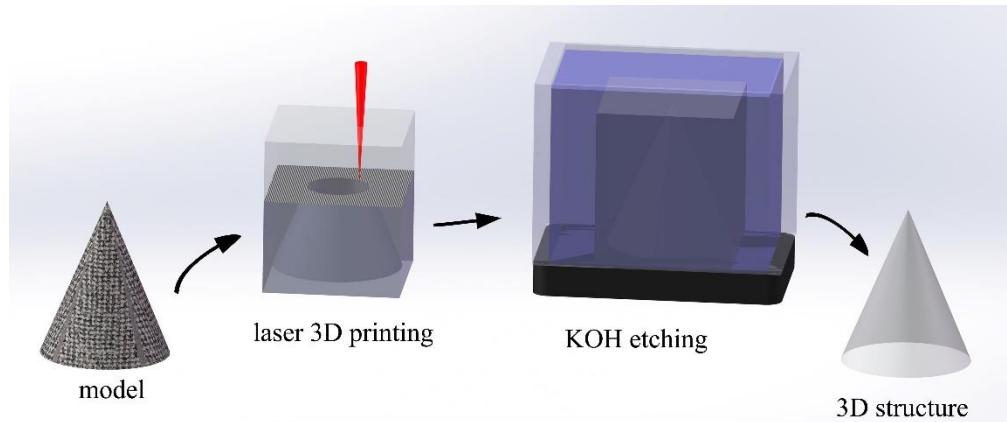
87 The models used for 3D glass micro-printing were originally generated as stereolithography  
88 (STL) files. The STL were firstly covered by a cuboid frame, and then underwent a subtraction  
89 operation. Afterwards, the 3D models were sliced into horizontal planes with a fixed slice thickness.  
90 We scanned the laser focal spot in the sliced planes along the pre-designed paths layer by layer to  
91 produce the 3D structures. The scan process was performed from the bottom to the top of the glass.  
92 Typically, there are two scan strategies in the stereo lithography fabrication: the raster scan and the  
93 contour scan. In the former strategy, the whole volume of the structure should be scanned; whereas  
94 for the later one, the laser focal spot only scans along the contour profile of the 3D structure. In our  
95 experiment, since the irradiated part of the glass should be removed after wet etching to get the  
96 structure, the raster scan had been chosen.

97 After the fused silica samples were selectively irradiated by the focused laser pulses as  
 98 illustrated in the first two panels of Figure 2, the samples were polished to remove the outer areas.  
 99 The outer areas near the vertical sidewalls of the cubic sample cannot be sufficiently modified by the  
 100 laser irradiation because of the distortion of the focal spot caused by the air-glass interface at the  
 101 sidewalls. The polished samples were then immersed in a wet-etching bath of potassium hydroxide  
 102 (KOH) with a concentration of 10 mol/L at a temperature of 90 °C for tens of hours as shown in the  
 103 last two panels of Figure 2. For example, it took in total ~72 hrs in the etching process to produce the  
 104 3.8 cm-tall Confucius sculpture as will be shown below.



105

106 **Figure 1.** (a) Schematic of the experimental setup. ND, variable neutral density filter; L1, L2, L3, L4, 107 convex lens; AOM, acousto-optical modulator; CCD, charge coupled device; OB, objective lens. Cross-sectional 108 view of optical micrographs of lines inscribed in fused silica with (b) positively chirped 10 ps laser pulses, 109 (c) transform-limited 190 fs laser pulses and (d) negatively 110 chirped 10 ps laser pulses. Scale bar, 25  $\mu$ m.



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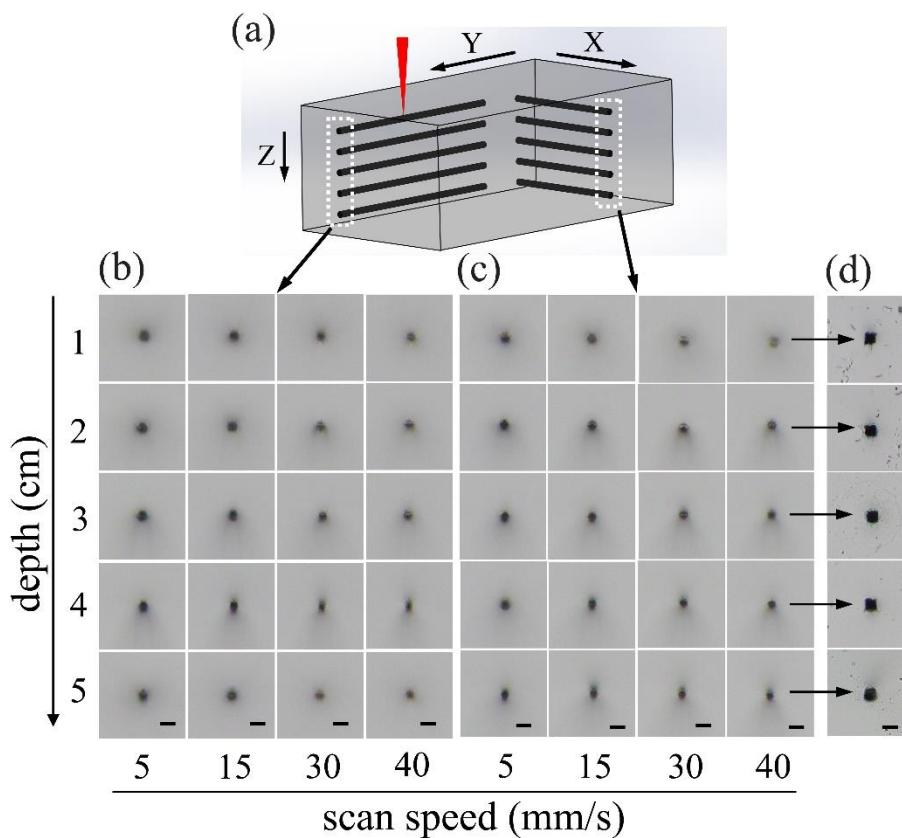
112 **Figure 2.** The three major steps in the 3D glass micro-printing: Digitalization of the 3D model (first  
 113 panel), scan of the laser beam along the predesigned paths to selectively modify the areas surrounding  
 114 the 3D objects (second panel), removal of the irradiated materials with the chemical wet etching (third  
 115 panel). The printed 3D structure is illustrated in the last panel.

### 116 3. Results and discussion

#### 117 3.1. Aberration-free focusing in fused silica with loosely-focused picosecond laser pulses

118 To examine the fabrication resolutions offered by loosely focusing the picosecond laser pulses  
 119 into fused silica as a function of focal position along the propagation direction, we first inscribe  
 120 multiple lines as schematically illustrated in Figure 3(a). The lines, which are inscribed at the different

121 scan speeds and depths within fused silica, are organized into two grid arrays oriented in X and Y  
 122 directions, as shown in Figure 3(b) and (c), respectively. The scan speed and the depth of the focal  
 123 position can be identified for each inscribed line as indicated in Figure 3(b) and (c). The average laser  
 124 power is fixed at 1.65 W in the writing of the lines in both of the two arrays, corresponding to an  
 125 intensity[16] of  $3.13 \times 10^{12} \text{ W/cm}^2$ , and the laser pulses are always polarized along Y direction. The  
 126 results in Figure 3 are obtained using laser pulses negatively chirped to 10 ps. However, as shown in  
 127 Figure 1, the same results can also be obtained if one chooses to use positively chirped pulses as long  
 128 as the pulse duration is properly chosen.



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**Figure 3.** The fabrication resolution offered by loosely focusing the picosecond laser pulses into fused silica. (a) Schematic illustration of inscribing lines within a cube of fused silica along X and Y direction. Cross-sectional optical micrographs of the lines written along (b) Y and (c) X directions. (d) Cross-sectional micrographs of the hollow channels produced by chemically etching the inscribed sample in the last column of (c). Scale bar: 25  $\mu\text{m}$ .

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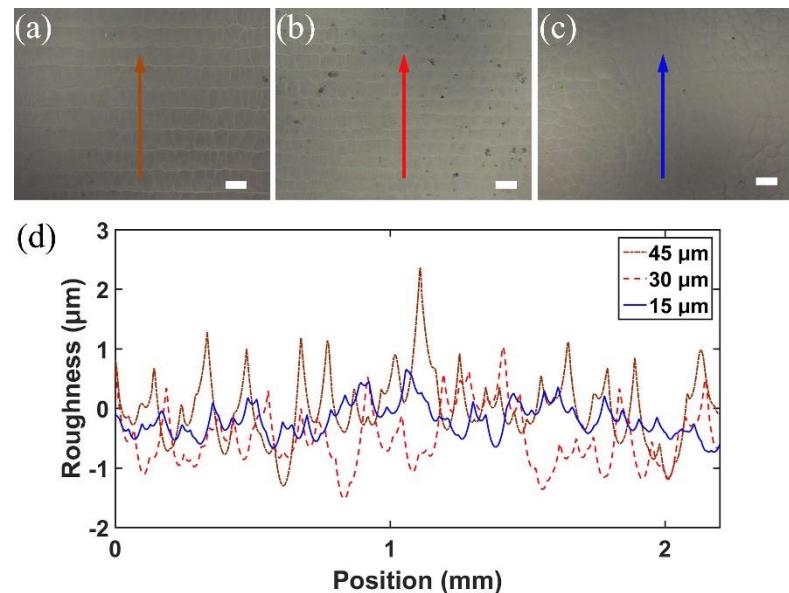
We notice that the cross section of all the inscribed lines shows a similar geometry of nearly circular shape, which are insensitive to the scan speed, depth of focal position as well as the direction of laser writing. The difference is that with an increasing scan speed, the color in the cross section captured under the microscope in a reflective mode becomes lighter, indicating that a weaker modification of fused silica will be generated with the decrease of the irradiation dose at the increasing scan speed. Since in the 3D glass printing with the FLICE, a chemical wet etching must be carried out for selectively removal of the modified fused silica by the laser pulses, it is important to examine the cross section of hollow channels produced after the chemical wet etching in KOH solution, as shown in Figure 3(d). The lateral and axial resolutions revealed by all the cross-sectional micrographs in Figure 3(d) are  $\sim 20 \mu\text{m}$ , despite the fact that the lines are inscribed at various depths across a range of 5 cm. A high scan speed of 40 mm/s is chosen for inscribing the lines in Figure 3(d), indicating that the aberration-free focusing of picosecond pulses is suitable for high throughput manufacturing of 3D objects in glass.

148 Another unexpected observation in the FLICE with the laser pulses of ~10 ps is that nanograting  
149 formation can be avoided as we have discussed in another recent publication[17]. It is well known  
150 that under the femtosecond laser irradiation, nanogratings tend to form inside various transparent  
151 materials including glass materials such as fused silica as well as several crystals[18,19]. The  
152 mechanism is still under debate whilst this effect has been identified to play significant roles in the  
153 applications of microfluidics and photonics[20,21]. Nevertheless, the nanograting leads to an etching  
154 selectivity sensitively depending on the orientation of the polarization of the writing laser beam,  
155 which increases the complexity of the beam steering system due to the requirement on the dynamic  
156 control of the polarization orientation in the 3D glass printing. Because we can eliminate the  
157 formation of nanogratings in fused silica with the picosecond pulses whilst still maintain the highly  
158 selective etching as shown in Ref. 17, we are able to perform 3D laser printing without the need of  
159 manipulating the polarization of the writing laser beam in real time. This greatly simplifies the beam  
160 steering in the printing system, making the whole printing process more robust and easier to put into  
161 practice.

162 *3.2 Optimization of the slice thickness and characterization of the surface quality*

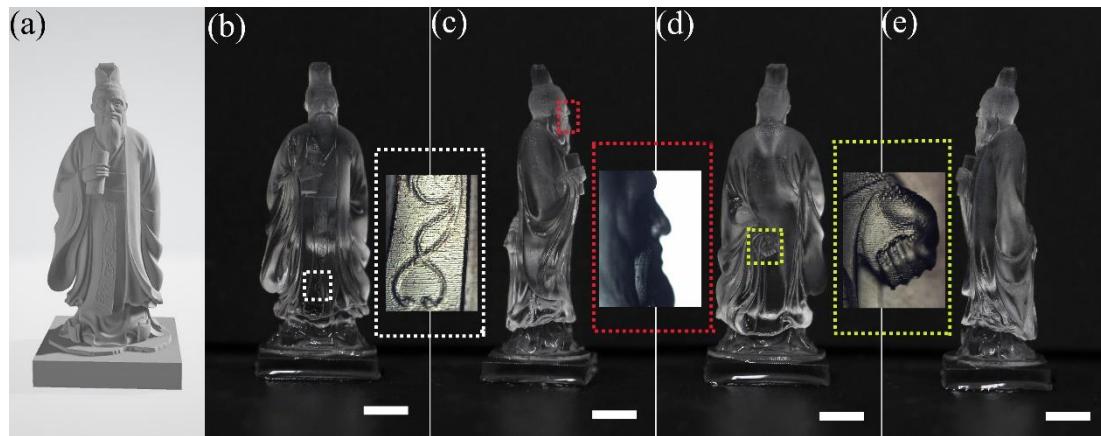
163 It is shown in Figure 3 that an isotropic spatial resolution on the level of ~20  $\mu\text{m}$  which is  
164 independent of the depth of the focal position can be obtained by loosely focusing the picosecond  
165 laser pulses into fused silica. However, for fabricating the 3D objects, chemical wet etching must be  
166 used, which leads to the degradation of the fabrication resolution. To determine the limit on the  
167 fabrication resolution along the longitudinal direction, we scanned the focused picosecond laser  
168 pulses in glass with different slice thicknesses and etched the samples in KOH to reveal the surface  
169 morphologies. As shown in Figure 4(a-c), the surfaces produced with the slice thicknesses set at 45  
170  $\mu\text{m}$  and 30  $\mu\text{m}$  show a clear laminar feature, owing to the fact that the thickness of each modification  
171 layer is less than both the slice thicknesses. When the slice thickness is reduced to 15  $\mu\text{m}$ , the laminar  
172 feature disappears, leaving behind a uniform surface with a typical morphology given rise to by the  
173 FLICE. It is also shown in the 1D surface profiles of the samples measured with a surface profiler, as  
174 shown in Figure 4(d), that periodic ripples oriented along the horizontal direction with a height  
175 between 1  $\mu\text{m}$  and 2  $\mu\text{m}$  and a height around 1  $\mu\text{m}$  appear for the surfaces produced at the slice  
176 thicknesses of 45  $\mu\text{m}$  and 30  $\mu\text{m}$ , which agrees well with the observations in Figure 4(a) and (b).  
177 However, when the slice thickness is reduced to 15  $\mu\text{m}$ , the 1D profile along the cutting lines in Figure  
178 4(d) only shows random peaks without a significant periodicity.

179 In principle, the results in Figure 4 indicates that a longitudinal resolution between 15  $\mu\text{m}$  and  
180 30  $\mu\text{m}$  had been achieved with the picosecond laser 3D printing in glass, which agrees with the ~20  
181  $\mu\text{m}$  resolution as shown in Figure 3(d). Unfortunately, there is a physical limit so far in choosing such  
182 a small slice thickness in printing large 3D structures in thick fused silica. The problem is that when  
183 ultrafast laser pulses are focused into glass, the modified material will have a volume expansion  
184 which build up stress inside glass. For large-scale internal modifications, the stress will be high and  
185 can give rise to multiple cracks which spoil the printed 3D objects. To solve this issue, we need to  
186 reduce the filling ratio in performing the laser writing. This results in a lower fabrication resolution  
187 than that allowed by the voxel size of 3D laser writing. In the current experiment, the slice thickness  
188 is finally set at 50  $\mu\text{m}$  to enable 3D printing of objects with heights up to 3.8 cm as shown in Figure 5.



189

190 **Figure 4.** Surface morphologies measured on samples written with the slice thicknesses set at (a) 45  
 191 μm; (b) 30 μm; and (c) 15 μm. (d) The measured 1D surface profiles of the samples in (a), (b) and (c)  
 192 are shown by the green dotted, red dashed, and blue solid lines, respectively. Scale bar: 50 μm.



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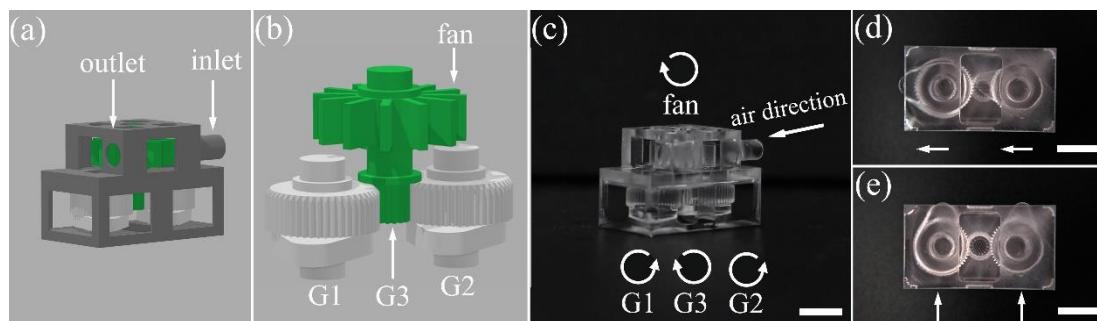
194 **Figure 5.** A laser printed sculpture of Confucius in fused silica. (a) The model and the (b) front, (c)  
 195 left, (d) back, and (e) right sides of the sculpture. The details of the decorative pattern on the cloth, the  
 196 right side of his face, and the left hand hanging behind his body are shown in the insets on the right-  
 197 hand side of the images in (b), (c) and (d), respectively. Scale bar: 5 mm.

### 198 3.3 3D printing of macro-scale objects in glass

199 The optimum inscription condition determined in Figure 3 allows us to print macro-scale 3D  
 200 objects at micro-scale resolutions. Figure 5 shows a 3.8 cm high sculpture, which is a statue of  
 201 Confucius. The model of the sculpture is shown in Figure 5(a), and the printed sculpture is presented  
 202 from the different angles of view in Figure 5(b-e) in the order of (b) front, (c) left, (d) back, and (e)  
 203 right sides. The details of the decorative pattern on the cloth, the right side of his face, and the left  
 204 hand hanging behind his body are shown in the insets on the right-hand side of the images in Figure  
 205 5(b), (c) and (d), respectively. It proves that the entire sculpture is printed with a decent fabrication  
 206 resolution from top to the bottom. The surface of the whole sculpture appears smooth although it  
 207 does not reach the level of the mirror-like surface quality typically produced with mechanical  
 208 polishing. Improvement on the surface quality is possible with elaborated post-annealing or CO<sub>2</sub> laser  
 209 polishing, which requires much effort to optimize and will be investigated in the future.

210 Besides, we demonstrate an air turbine with movable parts directly fabricated within glass  
 211 without any assembling process. The model of the air turbine is illustrated in Figure 6(a) and (b). As

212 shown by Figure 6(b), the micromachine is composed of an air fan, one driving gear and two driven  
 213 gears, as well as two cams. The driving gear is fabricated with the turbine fan as an integral  
 214 component to ensure a robust physical connection between the gear and the turbine fan. The two  
 215 driven gears can be wound by the driving gear when air flow drives the fan to rotate. Each of the  
 216 driven gears is connected with a cam. The laser printed air turbine is presented in Figure 6(c). The  
 217 micro-machine is functional as we can rotate the cams by injecting an air flow from the inlet. The  
 218 synchronized motion of the two cams are evidenced by the images in Figure 6(d) and (e), in which  
 219 the orientations of the cams are changed as indicated by the white arrows. Thanks to the capability  
 220 of fabricating large objects at the high resolution, the demonstrated technique offers potential for  
 221 manufacturing precision instruments, tools and machines in various research and application fields.



222

223 **Figure 6.** A laser printed air turbine in fused silica. (a) The whole air turbine model. Inlet and outlet  
 224 for air injection are indicated. (b) The interior of the turbine including turbine fan, a driving gear (G3)  
 225 and two driven gears (G1 and G2). Each of G1 and G2 is connected with a cam. (c) Digital-camera  
 226 captured image of the fabricated turbine. The air direction and the rotation direction of the fan, as  
 227 well as the rotation directions of G1, G2 and G3 from a top view are all indicated by the curved arrows  
 228 in (c). (d) The initial position of the two cams is pointing to the left as indicated by the two arrows. (e)  
 229 Both the cams are rotated in a clockwise direction by 90° as a result of the injected air flow. Scale bar:  
 230 5 mm.

#### 231 4. Conclusion

232 To conclude, we demonstrate 3D laser printing of glass-based macro-scale objects with heights  
 233 up to ~4 cm at a resolution of a few tens of micrometers. With the scan speed reaching 40 mm/s and  
 234 the layer spacing being set at 50  $\mu$ m as we demonstrate in the current experiments, the fabrication  
 235 efficiency can be determined to be 0.16 mm<sup>3</sup>/s or 38200 voxels/s[22]. Further improvement on the  
 236 printing efficiency will be done in the near future by combining a 2D galvo scanner with the 2D  
 237 motion stage. This design will allow both a high printing speed and a large printing area. The novel  
 238 3D glass printing technique is established based on two unconventional characteristics in the  
 239 interaction of loosely focused picosecond laser pulses with fused silica, namely, the depth-  
 240 independent aberration-free focusing and the elimination of the self-organized nanograting. The  
 241 physical mechanisms behind these interesting effects have not yet been clarified. We stress that the  
 242 interaction of ultrafast laser pulses with transparent media under the loose focusing condition is a  
 243 largely unexplored area of research, which shall inspire significant interest for further investigations.  
 244 The high-resolution 3D printing of macro-scale objects in glass is expected to have implications in the  
 245 fields of photonics, microfluidics, and high-precision mechanics.

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 247 P. W.; validation, P. W.; formal analysis, P. W.; investigation, P. W., W. L., and Y. T.; resources, P. W., W. C., M.  
 248 W., J. Q., J. L. and Z. W.; data curation, P. W. and W. C.; writing—original draft preparation, Y. C., W. C. and P.  
 249 W.; writing—review and editing, Y. C., W. C. and P. W.; visualization, P. W. and F. Z.; supervision, Y. C. and Z.  
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