

1 Article

2 Mitigation Effect of Seismic Acceleration of Nuclear 3 Power Plant Electric Cabinet Using Tuned Mass 4 Damper under Earthquakes

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11 **Abstract:** In this study, a tuned mass damper is proposed as a seismic acceleration mitigating
12 technique of an electrical cabinet inside the nuclear power plant. In order to know the mitigation
13 performance, the electrical cabinet and the tuned mass damper were modeled using SAP2000. The
14 sine sweep wave was used to confirm the vibration characteristics of the cabinet over a wide
15 frequency range, and the several various earthquakes were applied to the cabinet to verify the
16 control performance of the tuned mass damper. After analyzing the numerical results, it is
17 summarized that the application of the proposed technique can reduce the acceleration response of
18 the cabinet.

19 **Keywords:** nuclear power plant; electric cabinet; tuned mass damper; earthquake; vibration control
20

21 1. Introduction

22 Containment of nuclear power plants (NPP) occupies a very important place in terms of their
23 necessity and safety requirements. This is because of the large ripple effect when damaged by the
24 external force (earthquake, etc.). Therefore, the containment of NPPs needs careful attention from the
25 design stage and its safety should be reviewed during operation. To fulfill these requirements, the
26 containment of NPPs is carried out in seismic design with the highest safety allowance compared to
27 other structures.

28 Nevertheless, if the equipment inside the containment is damaged during an earthquake, it can
29 affect the core and, as a result, may cause fatal harm to the containment. Many electrical control
30 devices are installed and operated at NPPs cabinet type equipment. Before installing the cabinet in
31 the field, it should be seismically qualified at such level, that it can maintain its performance in
32 vibrations in the design earthquake level.

33 As because of the recently happened earthquakes in Korea, whose magnitudes are more than
34 5.0, the seismic demand performance for internal equipment of NPPs is increasing. As a result,
35 seismic reinforcement is required for the devices that do not satisfy the seismic demand performance
36 in existing internal NPPs.

37 The seismic reinforcement method to improve the seismic performance of the internal electrical
38 cabinet of NPPs includes a seismic restraint method, seismic isolation system and vibration control
39 device. The seismic restraint method fixes the bottom or top of the cabinet using strut bolts or external
40 angle brackets [1].

41 As a seismic isolation method, the seismic force from the floor is prevented from being
42 transmitted to the upper structure, such as a friction pendulum system (FPS). Kim et al. [2] attempted
43 to introduce the FPS to improve the seismic performance of the main control room of NPP and
44 showed that the acceleration of the superstructure was reduced through the shaking table test. Kim

45 et al. [3] also tried to apply the FPS to the main control room of NPP and showed the applicability of
46 the FPS using shaking table test and analytical method. Jeon et al. [4] developed the cone-type friction
47 pendulum bearing system (CFPBS) to prevent the damage of communication equipment during an
48 earthquake, and verify the performance of the CFPBS by numerical analysis and by the shaking table
49 test. However, the FPS shows a difference in performance according to the frictional force, and the
50 frictional force changes depending on the mass of the superstructure. Low frictional forces may
51 require additional dampers to control displacement [2]. Cho et al. [5] performed shaking table test on
52 telecommunication facility using LM guide and spring isolation table and displayed the effect of
53 reducing response acceleration.

54 Finally, the method of improving the seismic performance using the vibration control device is
55 to install a system consisting of additional mass, damping and stiffness in the structure or the cabinet,
56 and absorb the vibration energy which is generated from the device by the additional mass. This
57 vibration control device was proposed for a single degree of freedom subjected to harmonic vibration
58 by Den Hartog [6]. Warburton [7] proposed the optimum frequency and optimal damping ratio of
59 TMD for random vibration. Since then, many researchers have been conducted as a way to reduce
60 the wind induced vibration of the building [8, 9, 10, 11, and 12].

61 Recently, some of the researches have been done to reduce the vibration of structures against
62 earthquakes. Domizio et al. [13] showed a vibration reduction effect using TMDs on a four-story steel
63 frame against strong earthquakes. After that, Rahman et al. [14] proposed a method of using part of
64 a wall of a building as the mass of TMD as a method to reduce the vibration of building structures
65 against earthquakes. Then, Salvi et al. [15] studied the effects of soil-structure interaction on low
66 frequency and high frequency multi-story frame structures. In addition, Bagheri and Vahid Rahmani
67 [16] proposed an inelastic tuned mass damper as a way to reduce the seismic response and showed
68 the effect of reducing the seismic response to various structures and earthquakes. Lu et al. [17]
69 proposed an optimal TMD design method to reduce the dynamic displacement of a nonlinear
70 building under unknown earthquake excitations.

71 Chang et al. [18] proposed the Stockbridge damper as a method to reduce the vibration of the
72 pipe system inside the NPP, and analytically showed the effect of reducing the acceleration of the
73 pipe during earthquakes. Kwag et al. [19] studied the effects of multiple TMD to improve the seismic
74 performance of a nuclear piping system subjected to an earthquake load. However, research on
75 reducing vibration by installing the TMD in a cabinet in an NPP has not been conducted.

76 In this study, the TMD has been proposed as a way to mitigate the acceleration response of the
77 internal electrical cabinet in NPP. The TMD was designed by the eigenvalue analysis results of the
78 electrical cabinet, and the TMD and the cabinet were modeled using SAP2000 software, a finite
79 element analysis program. The sine sweep wave was used as the input load to confirm the dynamic
80 behavior of the cabinet according to the frequency change and the control effect by the TMD. In order
81 to confirm the control effects of the TMD under earthquakes, the seven recorded earthquakes in Korea
82 and California were used in this investigation. The results manifest that the TMD provides a
83 significant control on the seismic response of cabinet facility under different earthquakes.

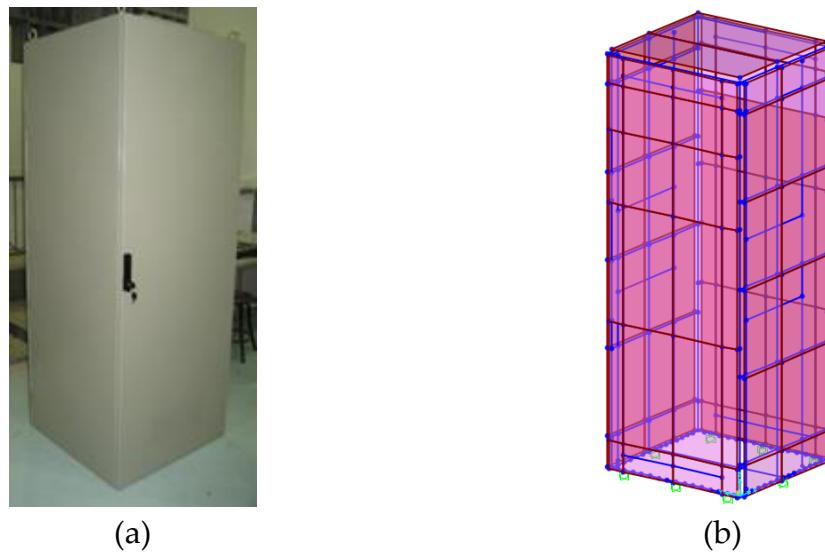
84 2. Numerical Modeling of the Electric Cabinet in NPP

85 2.1. Description of the Electric Cabinet

86 NPP consist of many electrical cabinet facilities that vary in size and mass and are used for the
87 power distribution system. In order to confirm the seismic performance of the electrical cabinet inside
88 the NPP, shaking table tests or impact hammer test should be carried out. However, shaking table
89 testing of the cabinet during NPP operation is practically impossible. Therefore, the seismic
90 performance of the internal electrical cabinet of NPP is mainly conducted by the analytical method.

91 In this study, the cabinet as shown in Figure. 1 was used to confirm the acceleration response of
92 the electrical cabinet inside NPP under earthquakes and was modeled in SAP2000 software. The
93 dimensions of the cabinet are 0.8m×0.8m×2.1m and the total mass is 259kg. The base of the cabinet is

94 restrained using 8 connection as shown in Figure. 1. Material properties of the cabinet are shown in
 95 Table 1.



96 **Figure 1.** Model of the electric cabinet: (a) Prototype of the cabinet; (b) Finite element model

97 **Table 1.** Material properties

Item	Value	Unit
Young's modulus	2.14e+5	MPa
Poisson's ratio	0.30	-
Steel density	7,851	kg/m ³

98 *2.2. Eigenvalue Analysis*

99 In order to design a vibration control device to reduce the acceleration of the cabinet, the
 100 dynamic properties of the cabinet need to consider. The dynamic properties of the cabinet are
 101 obtained using the eigenvalue analysis. One hundred modes were used for the eigenvalue analysis.
 102 However, the third mode showed global behavior as shown in Figure 2, while the remaining modes
 103 represented the local mode. Therefore, the third mode was selected to be controlled by a vibration
 104 control device. The frequency for control mode is 15 Hz and the modal mass is calculated using the
 105 following equation.

$$modal\ mass = \sum_{i=1}^n m_i \times \delta_{ij}^2 \quad (1)$$

106 where n is the number of nodes, m_i is a mass of i th node, δ_{ij} is an eigenvector of i th node of
 107 j th mode. Structural damping of 5% was assumed for the earthquake analysis. The dynamic
 108 properties for the cabinet are shown in Table 2

109 **Table 2.** Dynamic properties

	Value	Unit
3rd frequency	15.13	Hz
Modal mass	133	Kg
Structural damping	5.0	%

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Figure 2. Dominant global mode of the cabinet112 *2.3. Design of the Tuned Mass Damper (TMD)*

113 The design variables of the TMD are function of the mass ratio. Warburton [7] proposed the
 114 optimum frequency and optimal damping ratio of TMD for random vibration, and are expressed as
 115 equation (2) and (3).

$$f_{opt} = \frac{\sqrt{1 + \mu/2}}{1 + \mu} \quad (2)$$

$$\xi_{opt} = \sqrt{\frac{\mu(1 + 3\mu/4)}{4(1 + \mu)(1 + \mu/2)}} \quad (3)$$

116 where μ is a mass ratio of the TMD, f_{opt} is an optimal frequency ratio, ξ_{opt} is an optimal
 117 damping ratio. Table 3 shows the parameters of the designed TMD.

118

Table 3. Properties of TMD

Parameters	TMD	Unit
Mass	6	kg
Mass ratio	0.0450	-
Frequency ratio	0.968	-
Stiffness	50,736	N/m
Damping ratio	10.5	%
Damping	115.3	N/m·sec

119 *2.4. Numerical Model*

120 Figure 3(a) shows the electrical cabinet without TMD and Figure 3(b) shows the cabinet with
 121 TMD. In Figure 3(b), the green line in a circle represents the TMD. The TMD and cabinet were
 122 modeled using SAP2000. Two points link was used for modeling of the TMD in SAP2000. The initial
 123 point is attached to the top of the cabinet. And mass of the TMD was added to the end point. Using
 124 the TMD design parameters in Table 3, the stiffness of the link (50,736N/m), the damping coefficient
 125 (115.3N/m · sec), and the mass (6kg) were applied.

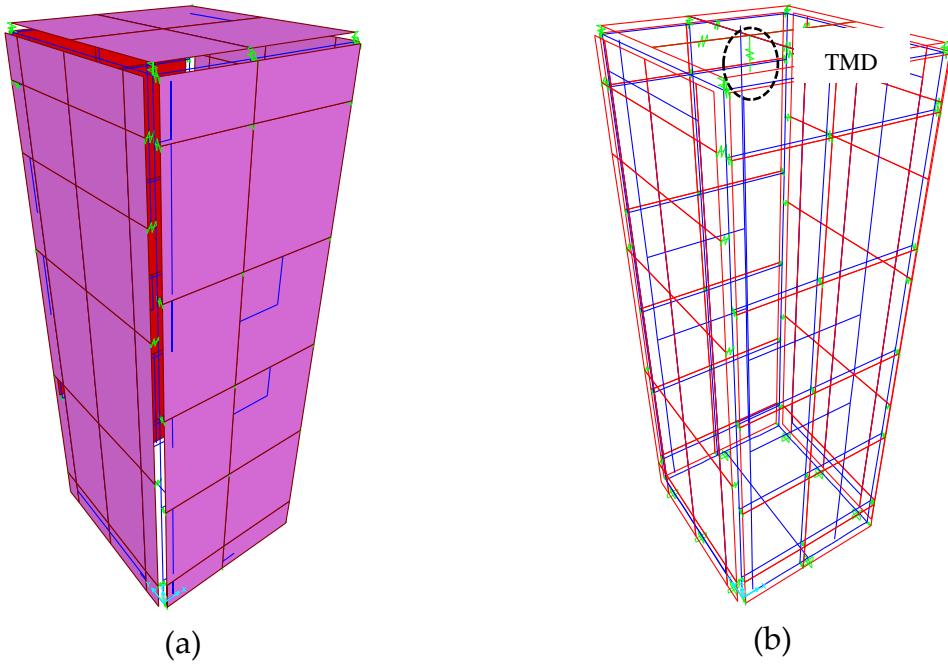


Figure 3. Analytical models without and with controller: (a) Electric cabinet without TMD; (b) Electric cabinet with TMD

128 3. Base Excitation

129 3.1. Sine Sweep Wave

130 In this study, TMD was applied to reduce the acceleration of the electrical cabinet inside NPP
131 under earthquakes. A sine sweep wave was used to confirm the response properties of the cabinet
132 according to the frequency range of the cabinet and vibration control performance of the TMD. The
133 time history of the sweep wave and its fast Fourier transform (FFT) are showed in Figure 4. The
134 maximum acceleration magnitude of the sine sweep wave is 0.01m/sec^2 and the frequency range is
135 0.1Hz to 250Hz.

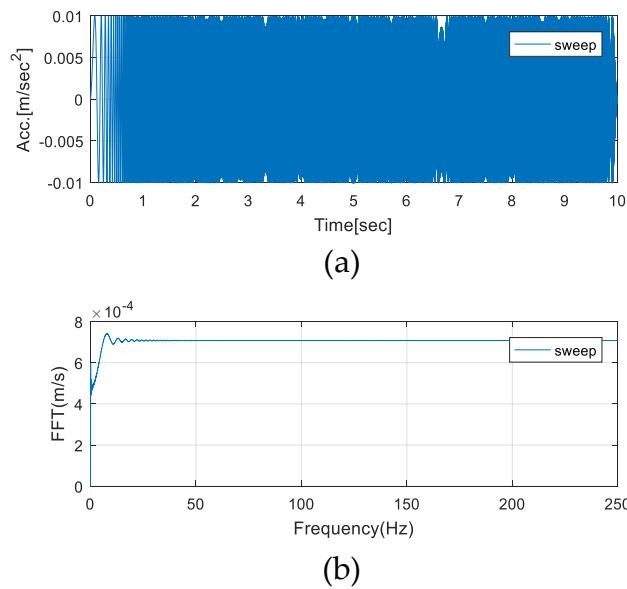
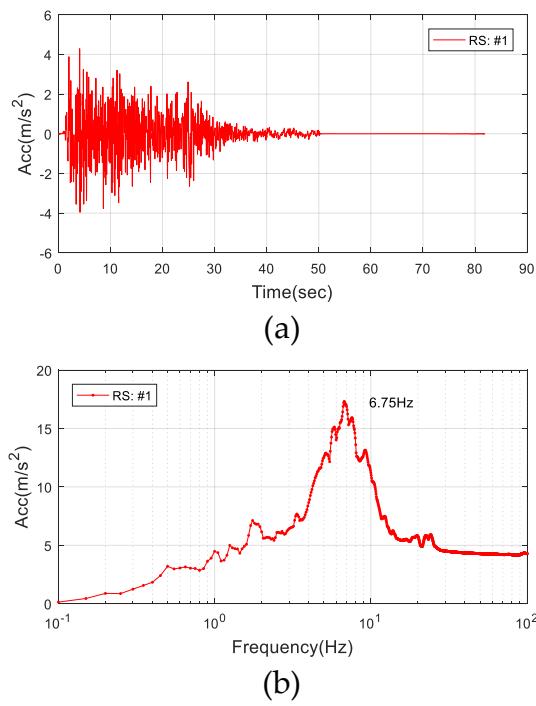
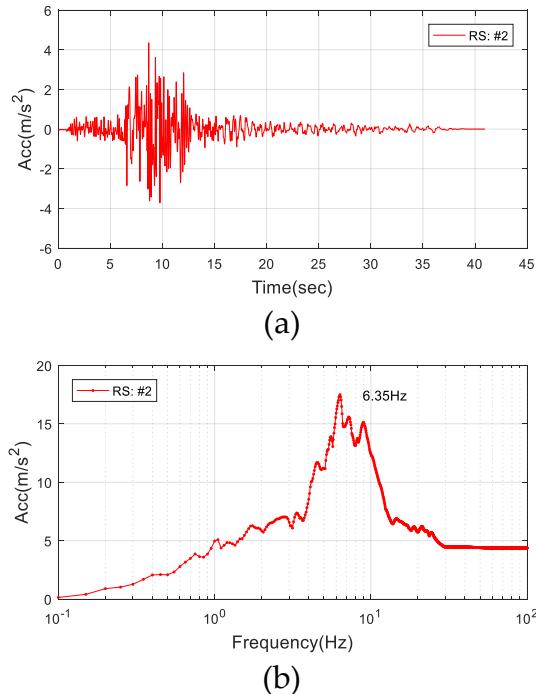


Figure 4. Sine sweep wave and its FFT: (a) Sweep wave; (b) FFT

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138 *3.2. Earthquake Ground Motion*

139 Seven ground motions recorded in Korea were used to confirm the vibration control
 140 performance and applicability of TMD. California earthquake was also applied to take into account
 141 low frequency. The time history and response spectrum of the earthquakes are shown in Figures 5 to
 142 12, and the characteristics of each earthquake are summarized in Table 4.

143 **Figure 5.** Earthquake no.1: (a) time history; (b) response spectrum144 **Figure 6.** Earthquake no.2: (a) time history; (b) response spectrum

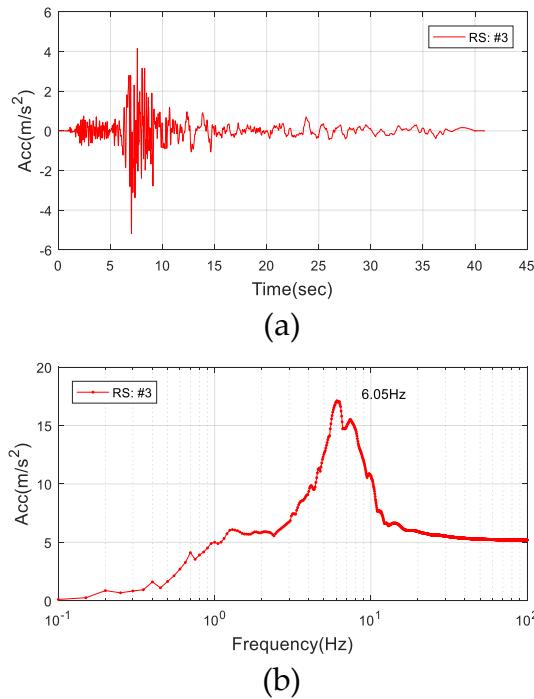
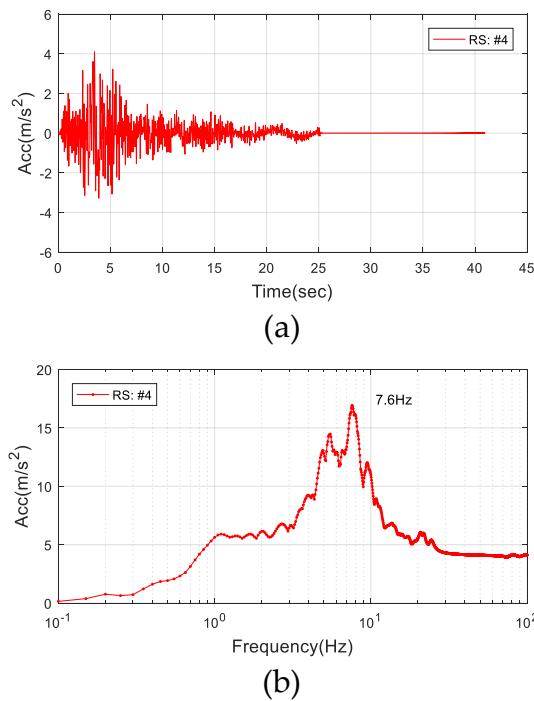
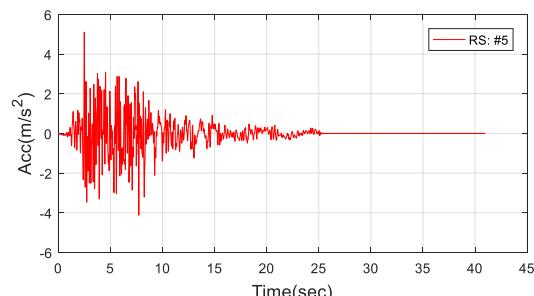


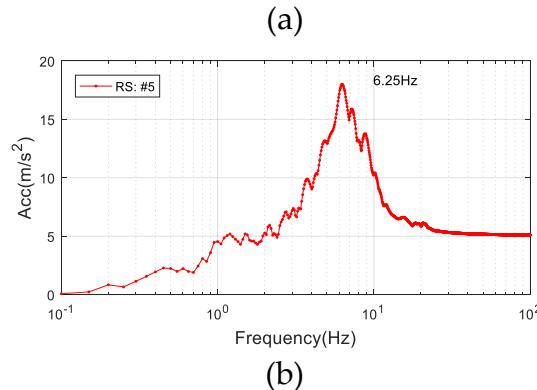
Figure 7. Earthquake no.3: (a) time history; (b) response spectrum



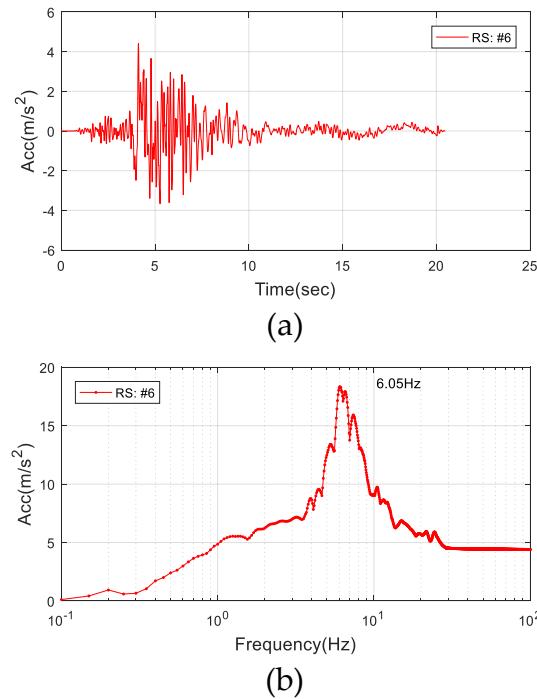
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Figure 8. Earthquake no.4: (a) time history; (b) response spectrum

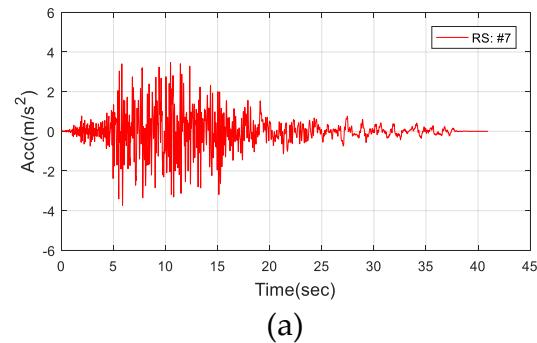


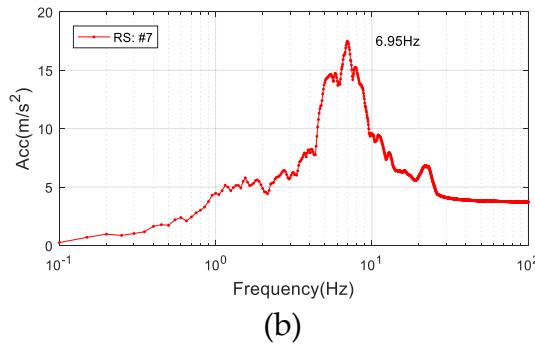


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Figure 9. Earthquake no.5: (a) time history; (b) response spectrum

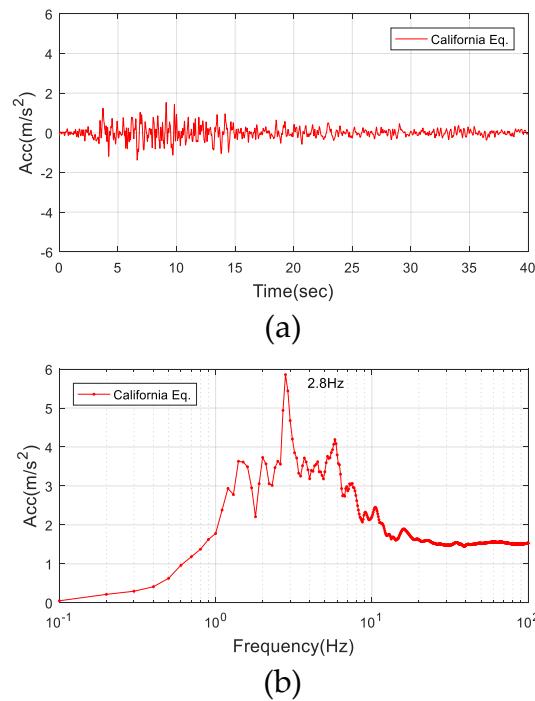
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Figure 10. Earthquake no.6: (a) time history; (b) response spectrum



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Figure 11. Earthquake no.7: (a) time history; (b) response spectrum



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Figure 12. California earthquake: (a) time history; (b) response spectrum

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Table 4. Characteristic of Earthquakes

Earthquakes	PGA(g)	Sampling time(sec)	Frequency
EQ. 01	0.437	0.010	6.75
EQ. 02	0.443	0.005	6.35
EQ. 03	0.529	0.005	6.05
EQ. 04	0.418	0.010	7.60
EQ. 05	0.521	0.005	6.25
EQ. 06	0.449	0.005	6.05
EQ. 07	0.380	0.005	6.95
California	0.156	0.020	2.80

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The recorded ground motions consist the PGA ranges from 0.38 g to 0.529 g and the main frequency range is in the 4 to 9 Hz range. In case of California earthquake, the PGA is 0.156 g, with a wide frequency range from 1 Hz to 10 Hz, with the largest energy at 2.8 Hz.

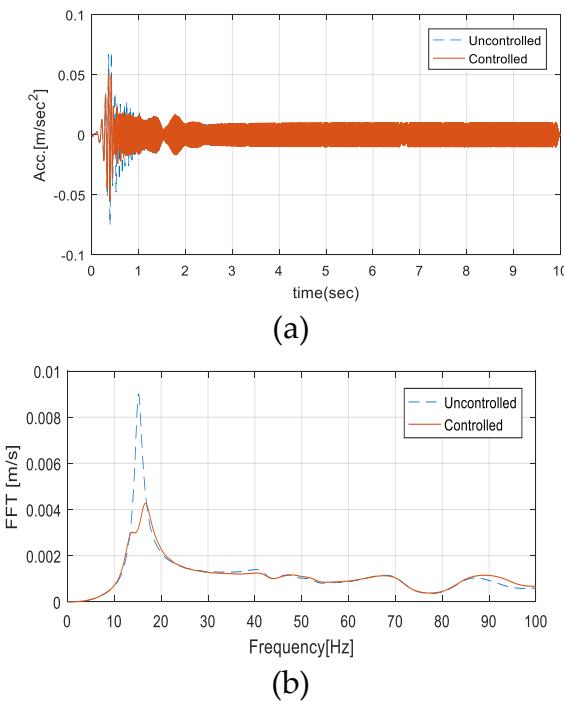
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4. Results and Discussion

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4.1. Acceleration Response of electric cabinet

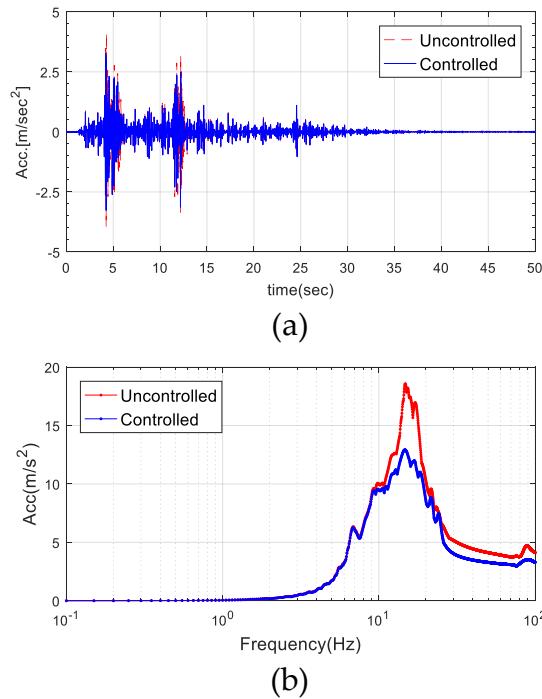
157 Sine sweep is used for the excitation of the cabinet facility for the following reason.
 158 1. To confirm the frequency characteristic of the cabinet before and after the installation of TMD.
 159 2. To investigate the reduction in the acceleration response.
 160 Figure 13 shows the time history graph and FFT of the acceleration on the top of the cabinet due
 161 to the sine sweep wave. The blue dotted line represents the acceleration response of the cabinet
 162 without the TMD, and the solid red line represents the acceleration response of the cabinet where the
 163 TMD is installed (Figure 13(a)). The acceleration response (uncontrolled) of the cabinet without TMD
 164 shows the highest energy at about 15.0 Hz, but the peaks of acceleration response (controlled) of
 165 cabinet with TMD were divided into 13.8 Hz and 16.6 Hz, and the acceleration response of the cabinet
 166 was reduced.



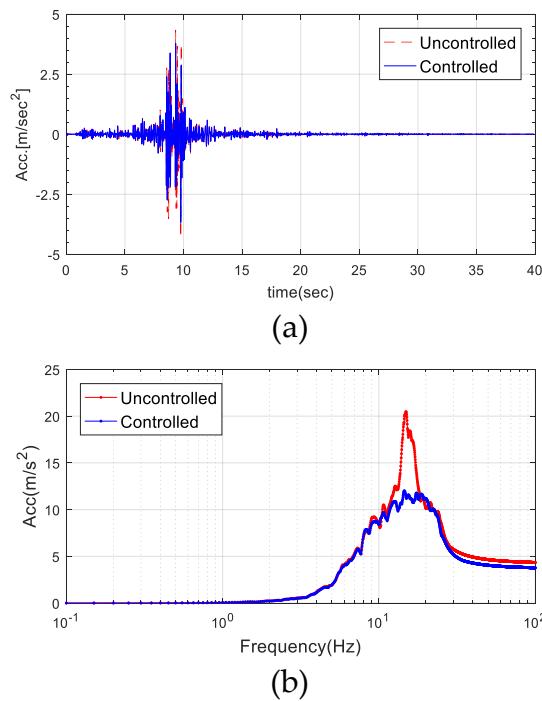
167 **Figure 13.** Acceleration response of cabinet on the top subjected to sine sweep wave: (a) time
 168 history; (b) FFT

169 *4.2. Response of Electric Cabinet Subjected to earthquakes*

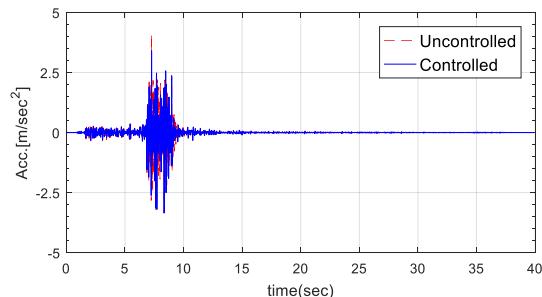
170 In Figure 14 (a), the dashed red line shows the acceleration at the top of the cabinet without the
 171 TMD, and the blue solid line shows the acceleration response at the top of the cabinet with the TMD.
 172 Similarly, in Figure 14 (b), the red line shows the acceleration response spectrum on the top of the
 173 cabinet without the TMD, and the blue line shows the acceleration response spectrum on the top of
 174 the cabinet after the TMD is installed. In Figure 14 (a), the maximum acceleration response of the
 175 cabinet with the TMD under the EQ.01 earthquake is decreased from 4.11 m/sec^2 to 3.28 m/sec^2 ,
 176 and the decreasing ratio is about 20 %. Root mean square (RMS) of the acceleration is reduced by
 177 about 14 %. It can be seen that the response spectrum is significantly reduced between 10 Hz and 20
 178 Hz in Figure 14(b). In the case of EQ. 02 earthquake, the maximum acceleration response was
 179 decreased from 4.34 m/sec^2 to 3.78 m/sec^2 , and the decreasing ratio is about 13 % (Figure 15(a)).
 180 The maximum acceleration and RMS acceleration results for each earthquake are summarized in
 181 Table 5. For the EQ. 06 earthquake, the maximum acceleration was increased by about 3%, but the
 182 RMS acceleration is decreased by about 17% (Figure 19). In the case of the California earthquake in
 183 Figure 21(a), the maximum acceleration was reduced by about 32% and the response spectrum is
 184 decreased by 50% from the peak.

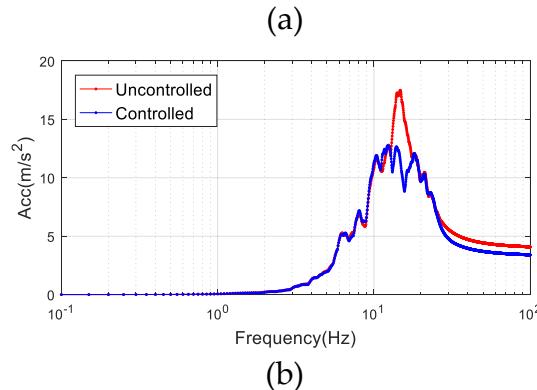


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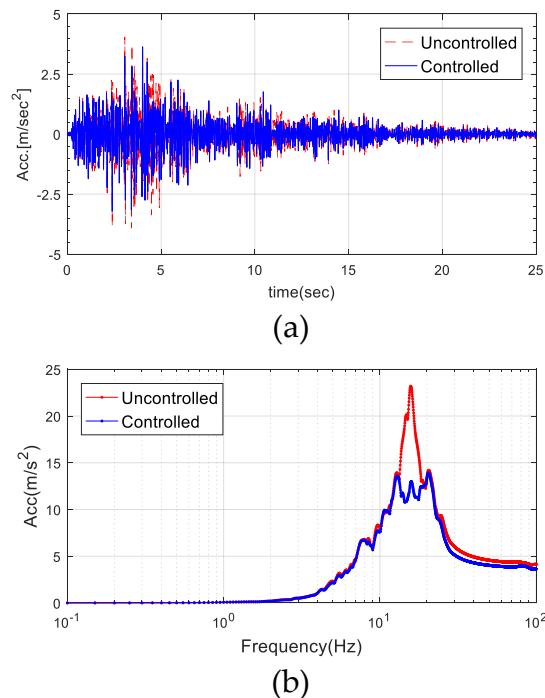
Figure 14. Response of cabinet subjected to earthquake no.1: (a) time history; (b) response spectrum

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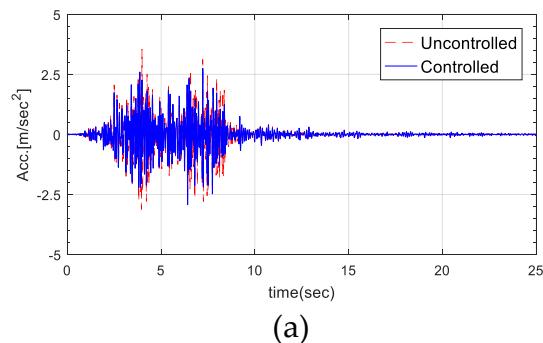
Figure 15. Response of cabinet subjected to earthquake no.2: (a) time history; (b) response spectrum

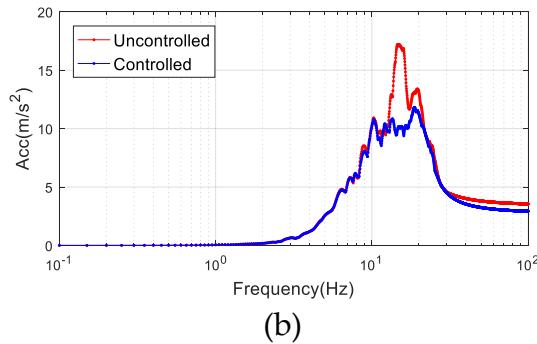


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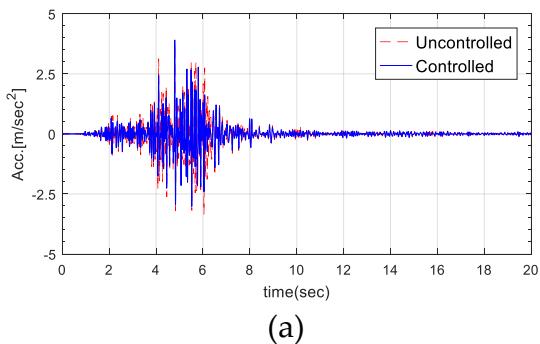
Figure 16. Response of cabinet subjected to earthquake no.3: (a) time history; (b) response spectrum

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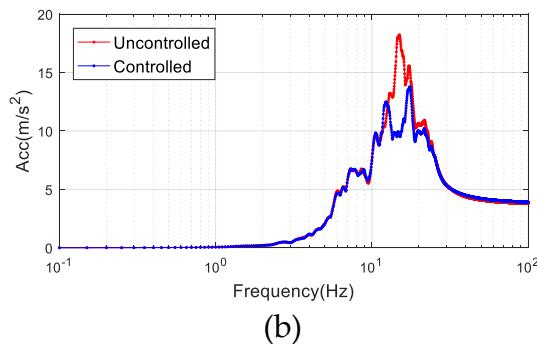
Figure 17. Response of cabinet subjected to earthquake no.4: (a) time history; (b) response spectrum



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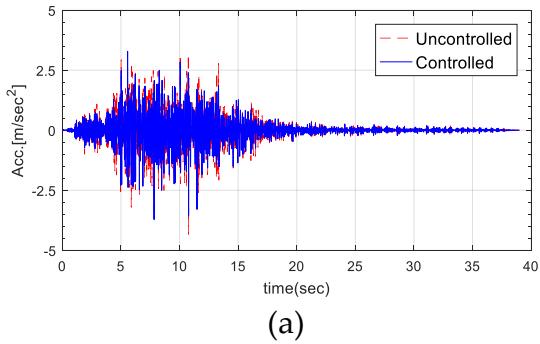
Figure 18. Response of cabinet subjected to earthquake no.5: (a) time history; (b) response spectrum

(a)

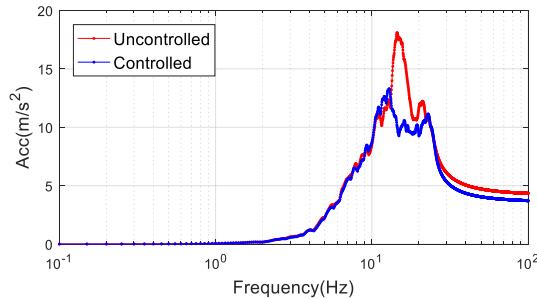


(b)

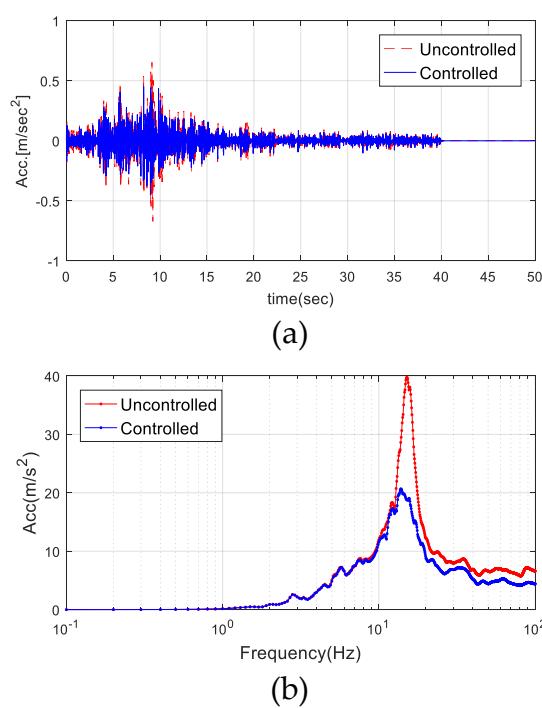
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Figure 19. Response of cabinet subjected to earthquake no.6: (a) time history; (b) response spectrum

(a)



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Figure 20. Response of cabinet subjected to earthquake no.7: (a) time history; (b) response spectrum192
193**Figure 21.** Response of cabinet subjected to California earthquake: (a) time history; (b) response spectrum

Direction	Maximum acceleration (m/sec ²)			RMS acceleration(m/sec ²)		
	Uncontrolled	Controlled	decreasing ratio(%)	Uncontrolled	Controlled	decreasing ratio(%)
EQ. 01	4.11	3.28	20.23	0.38	0.32	14.59
EQ. 02	4.34	3.78	12.96	0.31	0.25	18.34
EQ. 03	4.09	3.41	16.69	0.31	0.27	12.51
EQ. 04	4.04	3.63	10.18	0.66	0.55	17.34
EQ. 05	3.55	2.92	17.68	0.52	0.43	16.88
EQ. 06	3.79	3.91	-3.16	0.48	0.40	17.41
EQ. 07	4.34	3.72	14.29	0.56	0.48	15.23
California	0.67	0.45	32.86	0.08	0.06	22.62

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In the results of the dynamic analysis of the electrical cabinet, the acceleration response of the cabinet for the sine sweep wave, the low-frequency earthquake (California earthquake) and the high-frequency earthquake (seven ground motions) were compared. At most dynamic loads, it was found that the acceleration response of the cabinet with TMD was reduced. It has been shown that the proposed TMD can be sufficiently applied as a device to reduce the acceleration response of the cabinet to earthquakes.

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5. Conclusions

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In this study, TMD was proposed as a method to mitigate the acceleration response of the electrical cabinet inside NPP. A sine sweep wave, seven recorded earthquakes, and the California earthquake were used to simulate the control effects of the response of the cabinet under earthquakes.

204 The acceleration response before and after the control of the cabinet using the TMD was compared
205 using the time domain and the frequency domain.

206 The results of the sine sweep wave confirmed that the electrical cabinet is mainly dominated by
207 the first global mode, and the TMD can reduce the acceleration response of the cabinet. It is also
208 confirmed that the TMD can be sufficiently applied to the cabinets inside a nuclear power plant under
209 earthquakes. Therefore, this study analytically proves that TMD could be considered as a method for
210 improving the seismic performance of cabinets.

211 Further research on the experimental verification of the cabinet with TMD and the evaluation of
212 seismic performance are considered necessary.

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