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Defining the Most Generalized, Natural Extension of the Expected Value on Measurable Functions

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Article

Defining The Most Generalized, Natural Extension of the Expected Value

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Abstract: In this paper, we will extend the expected value of the function w.r.t the uniform probability measure on sets measurable in the Carathéodory sense to be finite for a larger class of functions, since the set of all measurable functions with infinite or undefined expected values may form a prevalent subset of the set of all measurable functions. This means "almost all" measurable functions have infinite or undefined expected values. Before we define the specific problem in Section 2, with a unique solution that allows "more" functions to have finite expected values, we'll outline some preliminary definitions. We'll then define the specific problem in Section 2 (with a partial solution in Section 3) to visualize the complete solution to the problem. Along the way, we will ask a series of questions to clarify our understanding of the paper.

Keywords: prevalence; expected value; uniform measure; measure theory; uniform cover; entropy; sample; linear; superlinear; choice function; Bernard's Paradox; pseudo-random

1. Background

I am an undergraduate from Indiana University despite being the age of a grad student. I should have graduated by now, but my obsession with research prevents me from moving forward. There is a chance that I might have a learning disability since writing isn't very easy for me.

As I've been in and out of college, I never got the chance to rigorously learn the subjects I'm researching. Most of what I learned was from Wikipedia, blogs and random research articles. I know little of what I read but learn what I can from asking questions on math stack exchange.

What I truly want, however; is for someone to take my ideas and publish them.

I warn that the definitions may not be rigorous so try to go easy on me. (I recommend using programming such as Mathematica, Python, JavaScript or Matlab to understand Sections 3 and 4).

2. Preliminaries

Suppose A is a set measurable in the [Carathéodory sense](#) [7], such for $n \in \mathbb{N}$, $A \subseteq \mathbb{R}^n$, and function $f : A \rightarrow \mathbb{R}$.

2.1. Motivation

It seems the set of measurable functions with infinite or undefined expected values (Definition 1), using the [uniform measure](#) (pp. 32-37 [18]), may be a [prevalent subset](#) [11,15] of the set of all measurable functions, meaning "almost every" measurable function has infinite or undefined expected values. Furthermore, when the Lebesgue measure of A , measurable in the Carathéodory sense, has zero or infinite volume (or undefined measure), there may be multiple, conflicting ways of defining a "natural" uniform measure on A .

Below I will attempt to define a question regarding an extension of the expected value (when it's undefined or infinite) which allows finite values instead.

Note the reason the question will be so long is there are plenty of "meaningless" extensions of the expected value (e.g. if the expected value is infinite or undefined we can just replace it with zero).

Therefore we must be more specific about what is meant by "meaningful" extension but there are some preliminary definitions we must clarify.

2.2. Preliminary Definitions

Definition 1 (Expected value w.r.t the Uniform Probability Measure). From an answer to [a question in cross validated](#) (a website for statistical questions) [10], let $\mathbf{X} \sim \text{Uniform}(A)$ denote a uniform random variable on set $A \subseteq \mathbb{R}^n$ and $p_{\mathbf{X}}$ denote the probability density function from the [radon-nikodym derivative](#) (pp. 419-427 [2]) of the [uniform probability measure](#) on A measurable in the Carathéodory sense. If $\mathbb{I}(x \in A)$ denotes the indicator function on $x \in A$:

$$\mathbb{I}(x \in A) = \begin{cases} 1 & x \in A \\ 0 & x \notin A \end{cases}$$

then the [radon-nikodym derivative](#) of [uniform probability measure](#) must have the form $\mathbb{I}(x \in A)/U'(A)$. (Note U' is not the derivative of U in the sense of calculus but rather the denominator of the probability density function derived from the uniform probability measure defined as U .)

Therefore, using the law of the unconscious statistician, we should get

$$\begin{aligned} \mathbb{E}[f(\mathbf{X})] &= \int_{\mathbb{R}^n} f(x) \cdot p_{\mathbf{X}}(x) \, d\mathbf{x} & (2.2.1) \\ &= \int_{\mathbb{R}^n} f(\mathbf{x}) \cdot \frac{\mathbb{I}(x \in A)}{U'(A)} \, d\mathbf{x} \\ &= \frac{1}{U'(A)} \int_A f(x) \, d\mathbf{x} & (P1) \\ &= \mathbb{E}_{U'}[f(\mathbf{X})] \end{aligned}$$

such the expected value is undefined when A does not have a uniform probability distribution or f is not integrable w.r.t the measure U' .

Definition 2 (Defining the pre-structure). Since there's a chance that $\mathbf{X} \sim \text{Uniform}(A)$ does not exist or f is not integrable w.r.t to U' , using Definition 1 we define a sequence of sets $\{F_r\}_{r \in \mathbb{N}}$ where if:

$$\begin{aligned} (a) \quad \liminf_{r \rightarrow \infty} F_r &= \bigcup_{r \geq 1} \bigcap_{q \geq r} F_q \\ (b) \quad \limsup_{r \rightarrow \infty} F_r &= \bigcap_{r \geq 1} \bigcup_{q \geq r} F_q \end{aligned}$$

then we have:

1. $\liminf_{r \rightarrow \infty} F_r = \limsup_{r \rightarrow \infty} F_r = A$
2. For all $r \in \mathbb{N}$, $\mathbf{X}_r \sim \text{Uniform}(F_r)$ exists (when A is countable infinite then for every $r \in \mathbb{N}$, F_r must be a finite set since \mathbf{X}_r would be a discrete uniform distribution of F_r ; otherwise, when A is uncountable, then \mathbf{X}_r is the normalized Lebesgue measure or [some other uniform measure](#) on F_r (e.g. [8]) such for every $r \in \mathbb{N}$ the Lebesgue measure or some other uniform measure on F_r exists and is finite.
3. For all $r \in \mathbb{N}$, $U'(F_r)$ is positive and finite such that U' is intrinsic. (For countably infinite A , U' would be the counting measure where $U'(F_r)$ is positive and finite since F_r is finite. For uncountable A , U' would either be the Lebesgue measure or the radon-nikodym derivative on [some other uniform measure](#) on F_r (e.g. [8]), where either of the measures on F_r are positive and finite.)

where $\{F_r\}_{r \in \mathbb{N}}$ is a **pre-structure** of A , since for every $r \in \mathbb{N}$ the sequence does not equal A , but "converges" to A as r increases (see (a) & (b) of this definition).

Example 1. Suppose $A = \mathbb{Q}$. One pre-structure of \mathbb{Q} is $\{F_r\}_{r \in \mathbb{N}} = \{\{c/r! : c \in \mathbb{Z}, -r \cdot r! \leq c \leq r \cdot r!\}\}_{r \in \mathbb{N}}$ since:

$$1. \quad \liminf_{r \rightarrow \infty} F_r = \limsup_{r \rightarrow \infty} F_r = A \implies$$

$$\bigcup_{r \geq 1} \bigcap_{q \geq r} \{c/q! : c \in \mathbb{Z}, -q \cdot q! \leq c \leq -q \cdot q\} = \bigcap_{r \geq 1} \bigcup_{q \geq r} \{c/q! : c \in \mathbb{Z}, -q \cdot q! \leq c \leq -q \cdot q\} = \mathbb{Q}$$

2. For every $r \in \mathbb{N}$, set $F_r = \{c/r! : c \in \mathbb{Z}, -r \cdot r! \leq c \leq r \cdot r!\}$ is finite, meaning each term of the pre-structure has a discrete uniform distribution. Therefore, $\mathbf{X}_r \sim \text{Uniform}(F_r)$ exists.
3. For every $r \in \mathbb{N}$, F_r is finite; meaning U' is the counting measure. Furthermore, since $U'(F_r) = 2r \cdot r! + 1$ and for all $r \in \mathbb{N}$, $2r \cdot r! + 1$ is positive and finite, criteria (3) of Definition 2 is satisfied.

Example 2. Suppose $A = \mathbb{Q}$. Another pre-structure of \mathbb{Q} is

$$\{F_r\}_{r \in \mathbb{N}} = \left\{ \bigcup_{t=1}^r \{c/d : c \in \mathbb{Z}, d \in \mathbb{N}, d \leq t, -dt \leq c \leq dt\} \right\}_{r \in \mathbb{N}}$$

where an union is added, since without the union

$$\liminf_{r \rightarrow \infty} \{c/d : c \in \mathbb{Z}, d \in \mathbb{N}, d \leq r, -dr \leq c \leq dr\} = \bigcup_{r \geq 1} \bigcap_{q \geq r} \{c/d : c \in \mathbb{Z}, d \in \mathbb{N}, d \leq q, -dq \leq c \leq dq\} \neq \mathbb{Q}$$

Note that:

$$1. \quad \liminf_{r \rightarrow \infty} F_r = \limsup_{r \rightarrow \infty} F_r = A \implies$$

$$\bigcup_{r \geq 1} \bigcap_{q \geq r} \bigcup_{t=1}^q \{c/d : c \in \mathbb{Z}, d \in \mathbb{N}, d \leq t, -dt \leq c \leq dt\} = \bigcap_{r \geq 1} \bigcup_{q \geq r} \bigcup_{t=1}^q \{c/d : c \in \mathbb{Z}, d \in \mathbb{N}, d \leq t, -dt \leq c \leq dt\} = \mathbb{Q}$$

2. For every $r \in \mathbb{N}$, set $F_r = \bigcup_{t=1}^r \{c/d : c \in \mathbb{Z}, d \in \mathbb{N}, d \leq t, -dt \leq c \leq dt\}$ is finite, meaning each term of the pre-structure has a discrete uniform distribution. Therefore, $\mathbf{X}_r \sim \text{Uniform}(F_r)$ exists.
3. For every $r \in \mathbb{N}$, F_r is finite; meaning U' is the counting measure, since (when $\phi(\cdot)$ is the [Euler's totient function](#) (pp. 239-249 [16])) we have $U'(F_r) = \sum_{t=1}^r |\{c/d : c \in \mathbb{Z}, d \in \mathbb{N}, d \leq t, -dt \leq c \leq dt\}| = \sum_{t=1}^r 2t\phi(t)$, and if correct, $\sum_{t=1}^r 2t\phi(t)$ is greater than zero and positive for all $r \in \mathbb{N}$. Therefore, criteria (3) of Definition 2 is satisfied.

There are plenty of pre-structures of \mathbb{Q} . Infact, there may be countably infinite many of these pre-structures.

Example 3. We need additional examples, where U' is not the counting measure. Perhaps one example of $\{F_r\}_{r \in \mathbb{N}}$ (where A is the [Liouville numbers](#) [6]) is:

$$\{F_r\}_{r \in \mathbb{N}} = \left\{ \bigcap_{n \in \mathbb{N} \cap [1, r]} \bigcup_{q \geq 2} \bigcup_{p \in \mathbb{Z}} \left(\left(\frac{p}{q} - \frac{1}{q^n}, \frac{p}{q} + \frac{1}{q^n} \right) \setminus \left\{ \frac{p}{q} \right\} \right) \right\}_{r \in \mathbb{N}} \quad (2.2.2)$$

Note we can show

$$\liminf_{r \rightarrow \infty} F_r = \limsup_{r \rightarrow \infty} F_r = A$$

However, we must also show for every $r \in \mathbb{N}$, there is a uniform measure on F_r . We assume this uniform measure is the normalized h -Hausdorff measure where h is the [\(exact\) dimension function](#) of A [14].

If the h -Hausdorff measure is positive and finite for every $r \in \mathbb{N}$, then U' must be the h -Hausdorff measure which, again, is positive and finite. Therefore $\{F_r\}_{r \in \mathbb{N}}$ or Equation (2.2.2) is a pre-structure.

Definition 3 (Expected value of Pre-Structure). If $\{F_r\}_{r \in \mathbb{N}}$ is a pre-structure of A (Definition 2), then for $r \in \mathbb{N}$, if

$$\mathbb{E}_{U'}[f(\mathbf{X}_r)] = \frac{1}{U'(F_r)} \int_{F_r} f d\mathbf{x} \quad (2.2.3)$$

we then have that the expected value of the pre-structure could be described as $\mathbb{E}_{U'}[f(\mathbf{X}_r)] \rightarrow \mathbb{E}_{U'}^*[f]$ (Definition 1) where:

$$\forall(\epsilon > 0) \exists(N \in \mathbb{N}) \forall(r \in \mathbb{N}) \left(r \geq N \Rightarrow |\mathbb{E}_{U'}[f(\mathbf{X}_r)] - \mathbb{E}_{U'}^*[f]| < \epsilon \right) \implies \quad (2.2.4)$$

$$\forall(\epsilon > 0) \exists(N \in \mathbb{N}) \forall(r \in \mathbb{N}) \left(r \geq N \Rightarrow \left| \frac{1}{U'(F_r)} \int_{F_r} f d\mathbf{x} - \mathbb{E}_{U'}^*[f] \right| < \epsilon \right) \quad (2.2.5)$$

Example 4. Suppose $A = \mathbb{Q}$ where $f : A \rightarrow \mathbb{R}$ such that:

$$f(x) = \begin{cases} 1 & x \in \{(2n+1)/2m : n \in \mathbb{Z}, m \in \mathbb{N}\} \\ 0 & x \in \{j/(2k+1) : j \in \mathbb{Z}, k \in \mathbb{N}\} \end{cases}$$

Using the pre-structure in Example 1 or $\{F_r\}_{r \in \mathbb{N}} = \{ \{c/r! : c \in \mathbb{Z}, -r \cdot r! \leq c \leq -r \cdot r!\} \}_{r \in \mathbb{N}}$, we presume (and prove) $\mathbb{E}_{U'}^*[f]$ using Definition 3 is 1. And using the pre-structure in Example 2 or

$$\{F_r\}_{r \in \mathbb{N}} = \left\{ \bigcup_{t=1}^r \{c/d : c \in \mathbb{Z}, d \in \mathbb{N}, d \leq t, -dt \leq c \leq dt\} \right\}_{r \in \mathbb{N}}$$

we presume (but must prove) $\mathbb{E}_{U'}^*[f]$, using Definition 3 is 1/3.

This shows different pre-structures give different expected values; therefore, we must choose a unique set of equivalent pre-structures (Definition 8) which gives the same & finite expected value.

Definition 4 (Uniform ϵ coverings of each term of the pre-structure). We define the uniform ϵ coverings of each term of the pre-structure $\{F_r\}_{r \in \mathbb{N}}$ (i.e., F_r) as a group of pair-wise disjoint sets that cover F_r for every $r \in \mathbb{N}$, such the measure U' of each of the sets that cover F_r have the same value of $\epsilon \in \text{range}(U')$, where $\epsilon > \inf(\text{range}(U'))$ and the total sum of U' of the coverings is minimized. In shorter notation, if

- The element $t \in \mathbb{N}$
- The set $T \supset \mathbb{N}$ is arbitrary and uncountable.

and set Ω is defined as:

$$\Omega = \begin{cases} \{1, \dots, t\} & \text{if there are } t \text{ ways of writing uniform } \epsilon \text{ coverings of } F_r \\ \mathbb{N} & \text{if there are countably infinite ways of writing uniform } \epsilon \text{ coverings of } F_r \\ T & \text{if there are uncountable ways of writing uniform } \epsilon \text{ coverings of } F_r \end{cases} \quad (2.2.6)$$

then for every $\omega \in \Omega$, the set of uniform ϵ coverings is defined using $\mathcal{U}(\epsilon, F_r, \omega)$ where ω “enumerates” all possible uniform ϵ coverings of F_r for every $r \in \mathbb{N}$.

Definition 5 (Sample of the uniform ϵ coverings of each term of the pre-structure). The sample of uniform ϵ coverings of each term of the pre-structure $\{F_r\}_{r \in \mathbb{N}}$ or F_r is the set of points, such for every $\epsilon \in \text{range}(U')$ and $r \in \mathbb{N}$, we take a point from each pair-wise disjoint set in the uniform ϵ coverings of F_r (Definition 4). In shorter notation, if

- The element $k \in \mathbb{N}$

- The set $\mathcal{K} \supset \mathbb{N}$ is arbitrary and uncountable.

and set Ψ_ω is defined as:

$$\Psi_\omega = \begin{cases} \{1, \dots, k\} & \text{if there are } k \text{ ways of writing the sample of uniform } \epsilon \text{ coverings of } F_r \\ \mathbb{N} & \text{if there are countably infinite ways of writing the sample of uniform } \epsilon \text{ coverings of } F_r \\ \mathcal{K} & \text{if there are uncountable ways of writing the sample of uniform } \epsilon \text{ coverings of } F_r \end{cases} \quad (2.2.7)$$

then for every $\psi \in \Psi_\omega$, the set of all samples of the set of uniform ϵ coverings is defined using $\mathcal{S}(\mathcal{U}(\epsilon, F_r, \omega), \psi)$, where ψ “enumerates” all possible samples of $\mathcal{U}(\epsilon, F_r, \omega)$.

Definition 6 (Entropy on the sample of uniform coverings of each term of the pre-structure). Since there are finitely many points in the sample of the uniform ϵ coverings of each term of pre-structure $\{F_r\}_{r \in \mathbb{N}}$ (Definition 5), we:

1. Arrange the x -value of the points in the sample of uniform ϵ coverings from least to greatest. This is defined as:

$$\text{Ord}(\mathcal{S}(\mathcal{U}(\epsilon, F_r, \omega), \psi))$$

2. Take the multi-set of the absolute differences between all consecutive pairs of elements in (1). This is defined as:

$$\text{Ord}(\mathcal{S}(\mathcal{U}(\epsilon, F_r, \omega), \psi))$$

3. Normalize (2) into a probability distribution, where for multi-set X , we have $|X|$ as the cardinality of all elements in the multi-set, including repeated ones. This is defined as:

$$\mathbb{P}(\mathcal{S}(\mathcal{U}(\epsilon, F_r, \omega), \psi)) = \{y / |\text{Ord}(\mathcal{S}(\mathcal{U}(\epsilon, F_r, \omega), \psi))| : y \in \text{Ord}(\mathcal{S}(\mathcal{U}(\epsilon, F_r, \omega), \psi))\}$$

4. Take the [entropy](#) of (3), (for further reading, see [12, p.61-95]). This is defined as:

$$E(\mathcal{S}(\mathcal{U}(\epsilon, F_r, \omega), \psi)) = - \sum_{x \in \mathbb{P}(\mathcal{S}(\mathcal{U}(\epsilon, F_r, \omega), \psi))} x \log_2 x$$

where (4) is the entropy on the sample of uniform coverings of F_r .

Definition 7 (Pre-Structure Converging Uniformly to A). For every $r \in \mathbb{N}$ (using Definitions 4–6) if set A is finite:

$$\lim_{\epsilon \rightarrow \inf(\text{range}(U'))} \sup_{r \in \mathbb{N}} \sup_{\omega \in \Omega} \sup_{\psi \in \Psi_\omega} E(\mathcal{S}(\mathcal{U}(\epsilon, F_r, \omega), \psi)) \geq E(F_r)$$

and if set A is non-finite:

$$\lim_{\epsilon \rightarrow \inf(\text{range}(U'))} \sup_{r \in \mathbb{N}} \sup_{\omega \in \Omega} \sup_{\psi \in \Psi_\omega} E(\mathcal{S}(\mathcal{U}(\epsilon, F_r, \omega), \psi)) = +\infty$$

we say the pre-structure $\{F_r\}_{r \in \mathbb{N}}$ **converges uniformly** to A (or in shorter notation):

$$F_r \xrightarrow{r \in \mathbb{N}} A \quad (2.2.8)$$

(Note we wish to define a uniform convergence of a sequence of sets to A since the definition is analogous to a uniform measure.)

Definition 8 (Equivalent Pre-Structures). The pre-structures $\{F_r\}_{r \in \mathbb{N}}$ and $\{F'_j\}_{j \in \mathbb{N}}$ of A are **equivalent** if, from Definition 3, where $\mathbb{E}_{U'}[f(\mathbf{X}_r)] \rightarrow \mathbb{E}_{U'}^*[f]$ and $\mathbb{E}_{U'}[f(\mathbf{X}'_j)] \rightarrow \mathbb{E}_{U'}^{**}[f]$:

$$\forall (f \in \mathbb{R}^A) \left(\mathbb{E}_{U'}^*[f] = \mathbb{E}_{U'}^{**}[f] \right)$$

Definition 9 (Non-Equivalent Pre-Structures). The pre-structures $\{F_r\}_{r \in \mathbb{N}}$ and $\{F'_j\}_{j \in \mathbb{N}}$ of A are **non-equivalent** if, from Definition 3, where $\mathbb{E}_{U'}[f(\mathbf{X}_r)] \rightarrow \mathbb{E}_{U'}^*[f]$ and $\mathbb{E}_{U'}[f(\mathbf{X}'_j)] \rightarrow \mathbb{E}_{U'}^{**}[f]$:

$$\exists (f \in \mathbb{R}^A) \left(\mathbb{E}_{U'}^*[f] \neq \mathbb{E}_{U'}^{**}[f] \right)$$

Definition 10 (Pre-Structures converging Sublinearly, Linearly, or Superlinearly to A compared to that of another Sequence). Suppose pre-structures $\{F_r\}_{r \in \mathbb{N}}$ and $\{F'_j\}_{j \in \mathbb{N}}$ are non-equivalent and converge uniformly to A ; and suppose for every $\varepsilon \in \text{range}(U')$, where $\varepsilon > \inf(\text{range}(U'))$ and $r \in \mathbb{N}$:

(a) From Definition 5 and 6, suppose we have:

$$\begin{aligned} |\mathcal{S}(\mathcal{U}(\varepsilon, F_r, \omega), \psi)| &= \\ \inf \left\{ |\mathcal{S}(\mathcal{U}(\varepsilon, F'_j, \omega'), \psi')| : j \in \mathbb{N}, \omega' \in \Omega, \psi' \in \Psi_\omega, E(\mathcal{S}(\mathcal{U}(\varepsilon, F'_j, \omega'), \psi')) \geq E(\mathcal{S}(\mathcal{U}(\varepsilon, F_r, \omega), \psi)) \right\} \end{aligned} \quad (2.2.9)$$

then (using 2.2.9) we have

$$\bar{\alpha}(\varepsilon, r, \omega, \psi) = |\mathcal{S}(\mathcal{U}(\varepsilon, F_r, \omega), \psi)| / \overline{|\mathcal{S}(\mathcal{U}(\varepsilon, F_r, \omega), \psi)|} \quad (2.2.10)$$

(b) From Definitions 5 and 6, suppose we have:

$$\begin{aligned} |\mathcal{S}(\mathcal{U}(\varepsilon, F_r, \omega), \psi)| &= \\ \sup \left\{ |\mathcal{S}(\mathcal{U}(\varepsilon, F'_j, \omega'), \psi')| : j \in \mathbb{N}, \omega' \in \Omega, \psi' \in \Psi_\omega, E(\mathcal{S}(\mathcal{U}(\varepsilon, F'_j, \omega'), \psi')) \leq E(\mathcal{S}(\mathcal{U}(\varepsilon, F_r, \omega), \psi)) \right\} \end{aligned} \quad (2.2.11)$$

then (using 2.2.11) we get

$$\underline{\alpha}(\varepsilon, r, \omega, \psi) = |\mathcal{S}(\mathcal{U}(\varepsilon, F_r, \omega), \psi)| / \underline{|\mathcal{S}(\mathcal{U}(\varepsilon, F_r, \omega), \psi)|} \quad (2.2.12)$$

1. If using Equations (2.2.10) and (2.2.12) we have that:

$$\lim_{\varepsilon \rightarrow \inf(\text{range}(U'))} \sup_{r \in \mathbb{N}} \sup_{\omega \in \Omega} \sup_{\psi \in \Psi_\omega} \bar{\alpha}(\varepsilon, r, \omega, \psi) = \lim_{\varepsilon \rightarrow \inf(\text{range}(U'))} \sup_{r \in \mathbb{N}} \sup_{\omega \in \Omega} \sup_{\psi \in \Psi_\omega} \underline{\alpha}(\varepsilon, r, \omega, \psi) = 0$$

then we say $\{F_r\}_{r \in \mathbb{N}}$ converges uniformly to A at a **superlinear rate** to that of $\{F'_j\}_{j \in \mathbb{N}}$.

2. If using Equations (2.2.10) and (2.2.12) we have that:

$$0 < \lim_{\varepsilon \rightarrow \inf(\text{range}(U'))} \sup_{r \in \mathbb{N}} \sup_{\omega \in \Omega} \sup_{\psi \in \Psi_\omega} \bar{\alpha}(\varepsilon, r, \omega, \psi) = \lim_{\varepsilon \rightarrow \inf(\text{range}(U'))} \sup_{r \in \mathbb{N}} \sup_{\omega \in \Omega} \sup_{\psi \in \Psi_\omega} \underline{\alpha}(\varepsilon, r, \omega, \psi) < +\infty$$

then we say $\{F_r\}_{r \in \mathbb{N}}$ converges uniformly to A at a **linear rate** to that of $\{F'_j\}_{j \in \mathbb{N}}$.

3. If using Equations (2.2.10) and (2.2.12) we have that:

$$\lim_{\varepsilon \rightarrow \inf(\text{range}(U'))} \sup_{r \in \mathbb{N}} \sup_{\omega \in \Omega} \sup_{\psi \in \Psi_\omega} \bar{\alpha}(\varepsilon, r, \omega, \psi) = \lim_{\varepsilon \rightarrow \inf(\text{range}(U'))} \sup_{r \in \mathbb{N}} \sup_{\omega \in \Omega} \sup_{\psi \in \Psi_\omega} \underline{\alpha}(\varepsilon, r, \omega, \psi) = +\infty$$

we say $\{F_r\}_{r \in \mathbb{N}}$ converges uniformly to A at a **sublinear rate** to that of $\{F'_j\}_{j \in \mathbb{N}}$.

[leftmargin=*,labelsep=4.9mm] I assume $\bar{\alpha}$ and $\underline{\alpha}$ are always equal but I'm not sure how to prove this.

2.3. Question on Preliminary Definitions

1. Are there "simpler" alternatives to either of the preliminary definitions? (Keep this in mind as we continue reading).

3. Main Question

Does there exist a unique extension (or a method that constructively defines a unique extension) of the expected value of f when the value's finite, using the [uniform probability measure](#) (pp. 32-37 [18]) on sets measurable in the Carathéodory sense, such we replace f with infinite or undefined expected values with f defined on a *chosen* pre-structure which depends on A where:

1. The expected value of f on each term of the pre-structure is finite
2. The pre-structure *converges uniformly* to A
3. The pre-structure *converges uniformly* to A at a *linear or superlinear* rate to that of other non-equivalent pre-structures of A which satisfies (1) and (2).
4. The *generalized expected value* of f on a pre-structure (i.e. an extension of Definition 3 to answer the full question) has a unique & finite value, such the pre-structure satisfies (1), (2), and (3).
5. A choice function is defined which chooses a pre-structure from A where the following satisfies (1), (2), (3), and (4) for the largest *possible* subset of \mathbb{R}^A .
6. If there is more than one choice function that satisfies (1), (2), (3), (4) and (5), we choose the choice function with the "simplest form", meaning for a general pre-structure of A , when each choice function is fully expanded, we take the choice function with the fewest variables/numbers (excluding those with quantifiers).

How do we answer this question? (See Sections 4.1, 4.2 and 4.4 for a partial answer.)

4. Informal Attempt to Answer Main Question

(I advise using computer programmings such as Mathematica, Python, JavaScript, or Matlab to understand the definitions of the answer below.)

4.1. Generalized Expected Values

If the image of f under A is $f[A] := \{f(x) : x \in A\}$, such from Definition 2 and 7, we take the pre-structure of $f[A]$ where:

$$F_r \xrightarrow{r \in \mathbb{N}} f[A]$$

and take the pre-image under f of F_r (defined as $f^{-1}[F_r] := \{x \in A : f(x) \in F_r\}$) such that:

$$f^{-1}[F_r] \xrightarrow{r \in \mathbb{N}} A$$

However, note the expected value of $f^{-1}[F_r]$ (Definition 3) may be infinite (e.g. unbounded f). Hence, for every $r \in \mathbb{N}$, we take $\left\{ \{F_{r,t_r}\}_{t_r \in \mathbb{N}} \right\}_{r \in \mathbb{N}}$ where:

$$\forall (r \in \mathbb{N}) \left(F_{r,t_r} \xrightarrow{t_r \in \mathbb{N}} F_r \right)$$

Thus, the *generalized expected value* or $\ddot{\mathbb{E}}_{U'}[f]$ is:

$$\begin{aligned} & \forall (\epsilon > 0) \exists (N \in \mathbb{N}) \forall (r \in \mathbb{N}) \forall (t_r \in \mathbb{N}) \\ & \left(r \geq N, t_r \geq N \Rightarrow \frac{1}{U'(F_{r,t_r})} \int_{F_{r,t_r}} f \, d\mathbf{x} - \ddot{\mathbb{E}}_{U'}[f] < \epsilon \right) \end{aligned} \quad (4.1.1)$$

and (similar to Definitions 2 & 3) if

$$\mathbb{E}_{U'}[f(\mathbf{X}_{r,t_r})] = \frac{1}{U'(F_{r,t_r})} \int_{F_{r,t_r}} f \, d\mathbf{x} \quad (4.1.2)$$

we describe the process of the *generalized expected value* as $\mathbb{E}_{U'} [f(\mathbf{X}_{r,t_r})] \rightarrow \mathbb{E}_{U'} [f]$.

4.2. Choice Function

Suppose $\mathbb{S}'(A)$ is the set of all pre-structures of A which satisfies criteria (1) and (2) of the main question where the *generalized expected value* of the pre-structures, as they converge uniformly to A , is unique and finite such the pre-structure $\{F''_r\}_{r \in \mathbb{N}} \in \mathbb{S}'(A)$ should be a sequence of sets that satisfies criteria (1), (2), (3) and (4) of the main question where (using the end of Section 4.1):

$$\mathbb{E}_{U'} [f(\mathbf{X}_{r,t_r}'')] \rightarrow \mathbb{E}_{U'} [f] \quad (4.2.1)$$

and pre-structure $\{F'_j\}_{j \in \mathbb{N}}$ is an element of $\mathbb{S}'(A)$ such (using the end of Section 4.1):

$$\mathbb{E}_{U'} [f(\mathbf{X}_{j,t_j}')] \rightarrow \mathbb{E}_{U'} [f] \quad (4.2.2)$$

but is not an element of the set of equivalent pre-structures of $\{F''_r\}_{r \in \mathbb{N}}$ (i.e. Definition 8).

Further note from (a), with Equation (2.2.9) in Definition 10, if we take:

$$\begin{aligned} \overline{|\mathcal{S}(\mathcal{U}(\epsilon, F''_r, \omega), \psi)|} = \\ \inf \left\{ |\mathcal{S}(\mathcal{U}(\epsilon, F'_j, \omega'), \psi')| : j \in \mathbb{N}, \omega' \in \Omega, \psi' \in \Psi_\omega, E(\mathcal{S}(\mathcal{U}(\epsilon, F'_j, \omega'), \psi')) \geq E(\mathcal{S}(\mathcal{U}(\epsilon, F''_r, \omega), \psi)) \right\} \end{aligned} \quad (4.2.3)$$

and from (b), with Equation (2.2.11) in Definition 10, we take:

$$\begin{aligned} |\mathcal{S}(\mathcal{U}(\epsilon, F''_r, \omega), \psi)| = \\ \sup \left\{ |\mathcal{S}(\mathcal{U}(\epsilon, F'_j, \omega'), \psi')| : j \in \mathbb{N}, \omega' \in \Omega, \psi' \in \Psi_\omega, E(\mathcal{S}(\mathcal{U}(\epsilon, F'_j, \omega'), \psi')) \leq E(\mathcal{S}(\mathcal{U}(\epsilon, F''_r, \omega), \psi)) \right\} \end{aligned} \quad (4.2.4)$$

Then, using Definition 5 with Equations (4.2.3) and (4.2.4), if:

$$\sup_{\omega \in \Omega} \sup_{\psi \in \Psi_\omega} \mathcal{S}(\mathcal{U}(\epsilon, F''_r, \omega), \psi) = \mathcal{S}'(\epsilon, F''_r) = \mathcal{S}' \quad (4.2.5)$$

$$\sup_{\omega \in \Omega} \sup_{\psi \in \Psi_\omega} \overline{|\mathcal{S}(\mathcal{U}(\epsilon, F''_r, \omega), \psi)|} = \overline{|\mathcal{S}'(\epsilon, F''_r)|} = \overline{|\mathcal{S}'|} \quad (4.2.6)$$

$$\sup_{\omega \in \Omega} \sup_{\psi \in \Psi_\omega} \underline{|\mathcal{S}(\mathcal{U}(\epsilon, F''_r, \omega), \psi)|} = \underline{|\mathcal{S}'(\epsilon, F''_r)|} = \underline{|\mathcal{S}'|} \quad (4.2.7)$$

where, using absolute value function $||\cdot||$, we have:

$$S(r) = \left(\sup(F''_{r+1}) - \sup(F''_r) \right) \left(\inf(F''_r) - \inf(F''_{r+1}) \right) \left\| \left(\inf(F''_r) - \inf(F''_{r+1}) \right) \left(\sup(F''_{r+1}) - \sup(F''_r) - 1 \right) \right\| \quad (4.2.8)$$

such that

$$\begin{aligned} T(r) = & \left(\sup(F''_{r+1}) \inf(F''_r) - \sup(F''_r) \inf(F''_{r+1}) \right) \left(\left(\inf(F''_r) - \inf(F''_{r+1}) \right) - \left(\sup(F''_{r+1}) - \sup(F''_r) \right) - 1 \right) \\ & \left(\inf(F''_r) - \inf(F''_{r+1}) \right) \left(\sup(F''_{r+1}) - \sup(F''_r) \right) \end{aligned} \quad (4.2.9)$$

and, using Equations (4.2.5)–(4.2.9) with the nearest integer function $[\cdot]$, we want:

$$K(\epsilon, F''_r) = ||1 - S(r)|| \left\| \frac{\left(||\mathcal{S}'|| \left(1 + \left[\frac{|\mathcal{S}'|(|\mathcal{S}'|+2|\mathcal{S}'|)}{1} \right] (|\mathcal{S}'| + |\mathcal{S}'|) (|\mathcal{S}'| + |\mathcal{S}'| + |\mathcal{S}'|) \right) \right) (1 + \lceil |\mathcal{S}'|/|\mathcal{S}'| \rceil)}{(1 + \lceil |\mathcal{S}'|/|\mathcal{S}'| \rceil) (1 + \lfloor |\mathcal{S}'|/|\mathcal{S}'| \rfloor)} - |\mathcal{S}'| + |\mathcal{S}'| \right\| - T(r) \quad (4.2.10)$$

such, using Equation (4.2.10), if set $S''(A) \subseteq S'(A)$ and $\mathcal{P}(\cdot)$ is the power-set, then set $C(A)$ is the largest element of:

$$\left\{ S''(A) \subseteq S'(A) : \forall(\epsilon_1 > 0) \exists(M \in \mathbb{N}) \forall(\epsilon \in \text{range}(U')) \exists(j \in \mathbb{N}) \forall(r \in \mathbb{N}) \forall(\{F_r''\} \in S''(A)) \right. \\ \left. \left(\inf(\text{range}(U')) < \epsilon \leq M, r \geq j \Rightarrow |S'(\epsilon, F_r'') - K(\epsilon, F_r'') - \inf_{\{F_g\} \in S'(A)} (S'(\epsilon, F_g) - K(\epsilon, F_g))| < \epsilon_1 \right) \right\} \subseteq \mathcal{P}(S'(A)) \quad (4.2.11)$$

w.r.t to inclusion, such the **choice function** is $C(A)$ if the following contains just one element.

Otherwise, for $k \in \mathbb{N}$, suppose we say $C^k(A)$ represents the k -th iteration of the choice function of A , e.g. $C^3(A) = C(C(C(A)))$, where the infinite iteration of $C(A)$ (if it exists) is $\lim_{k \rightarrow \infty} C^k(A) = C^\infty(A)$. Therefore, when taking the following:

$$C'(A) = \begin{cases} C(A) & \text{if } C(A) \text{ contains one element} \\ C^j(A) & \text{if } j \in \mathbb{N}, \text{ such for all } k \geq j, C^k(A) \text{ contains one element} \\ C^\infty(A) & \text{if it exists, and } C^\infty(A) \text{ contains one element} \end{cases} \quad (4.2.12)$$

we say $C'(A)$ is the *choice function* and the expected value, using Definition 4.2.1, is $\ddot{\mathbb{E}}_{U'}''[f]$.

4.3. Questions on Choice Function

- Suppose we define function $f : A \rightarrow \mathbb{R}$. What unique pre-structure would $C'(A)$ contain (if it exists) for:
 - $A = \mathbb{Z}$ where if $\{F_r''\}_{r \in \mathbb{N}} \in C'(\mathbb{Z})$ and $f = \text{id}_{\mathbb{Z}}$, we want $\{F_r''\}_{r \in \mathbb{N}} = \{m \in \mathbb{Z} : -r \leq m \leq r\}_{r \in \mathbb{N}}$
 - $A = \mathbb{Q}$ where if $\{F_r''\}_{r \in \mathbb{N}} \in C'(\mathbb{Q})$ and $f = \text{id}_{\mathbb{Q}}$, we want $\{F_r''\}_{r \in \mathbb{N}} = \{s/r! : s \in \mathbb{Z}, -r \cdot r! \leq s \leq r \cdot r!\}_{r \in \mathbb{N}}$
 - $A = \mathbb{R}$ where we're not sure what $\{F_r''\}_{r \in \mathbb{N}} \in C'(\mathbb{R})$ would be if $f = \text{id}_{\mathbb{R}}$. What would $\{F_r''\}_{r \in \mathbb{N}}$ be if it's unique?

4.4. Increasing Chances of an Unique and Finite Expected Value

In case $C'(A)$, in equation 4.2.12, does not exist; if there exists a unique and finite $\ddot{\mathbb{E}}_{U'}''[f]$ (see Section 4.1) where:

$$\forall \left(\{F_r''\}_{r \in \mathbb{N}} \in C(A) \right) \left(\ddot{\mathbb{E}}_{U'}''[f] \text{ is unique \& finite} \right) \quad (4.4.1)$$

Then $\ddot{\mathbb{E}}_{U'}''[f]$ is the **generalized expected value w.r.t choice function** C , which answers criteria (1), (2), (3), (4), (perhaps (5)) of the question in Section 3; however, there is still a chance that the Equation (4.4.1) fails to give an unique $\ddot{\mathbb{E}}_{U'}''[f]$. Hence; if $k \in \mathbb{N}$, we take the k -th iteration of the choice function C in 4.2.11, such there exists a $j \in \mathbb{N}$, where for all $k \geq j$, if $\ddot{\mathbb{E}}_{U'}''[f]$ is unique and finite then the following is the **generalized expected value w.r.t finitely iterated C** .

In other words, if the k -th iteration of C is represented as $C^{[k]}$ (where e.g. $C^3(A) = C(C(C(A)))$), we want a unique and finite $\mathbb{E}_{U'}''[f]$ where:

$$\exists (j \in \mathbb{N}) \forall (k \in \mathbb{N}) \left(k \geq j \Rightarrow \forall \left(\{F_r''\}_{r \in \mathbb{N}} \in C^{[k]}(A) \right) \left(\mathbb{E}_{U'}''[f] \text{ is unique \& finite} \right) \right) \quad (4.4.2)$$

If this still does not give a unique and finite expected value, we then take the **most generalized expected value w.r.t an infinitely iterated C** where if the *infinite iteration* of C is stated as $\lim_{k \rightarrow \infty} C^{[k]}(f[A]) = C^\infty(f[A])$, we then want a unique $\mathbb{E}_{U'}''[f]$ where:

$$\forall \left(\{F_r''\}_{r \in \mathbb{N}} \in C^\infty(A) \right) \left(\mathbb{E}_{U'}''[f] \text{ is unique \& finite} \right) \quad (4.4.3)$$

However, in such cases, $\mathbb{E}_{U'}''[f]$ should only be used for functions where *the expected value is infinite or undefined* or for **worst-case functions**—badly behaved $f : A \rightarrow \mathbb{R}$ (where for $n \in \mathbb{N}$, $A \subseteq \mathbb{R}^n$, and f is a function) defined on infinite points covering an infinite expanse of space. For example:

1. For a worst-case f defined on countably infinite A (e.g. countably infinite "pseudo-random points" non-uniformly scattered across the real plane), one may need just one iteration of C (since most function on countable sets need just one iteration of C for $\mathbb{E}_{U'}''[f]$ to be unique); otherwise, one may use Equation (4.4.2) for finite iterations of C .
2. For a worst-case f defined on uncountable A , we might have to use Equation (4.4.3) as averaging such a function might be nearly impossible. We can imagine this function as an uncountable number of "pseudo-random" points non-uniformly generated on a subset of the real plane (see Section 5.1 for a visualization.)

Note, however, that no matter how generalized and "meaningful" the extension of an expected value is, there will always be an f where the expected value does not exist.

4.5. Questions Regarding the Answer

1. Using [prevalence and shyness](#) [11,15], can we say the set of f where either Equations (4.4.1)–(4.4.3) have an unique and finite $\mathbb{E}_{U'}''[f]$ which forms either a **prevalent** or *neither prevalent nor shy* subset of \mathbb{R}^A ? (If the subset is *prevalent*, this implies either one of the generalized expected values can be unique and finite for a "large" subset of \mathbb{R}^A ; however, if the subset is *neither prevalent nor shy* we need more precise definitions of "size" which takes "an exact probability that the expected values are unique & finite"—some examples (which are shown in [this answer](#) [9]) being:
 - (a) Fractal Dimension notions
 - (b) Kolmogorov Entropy
 - (c) Baire Category and Porosity
2. There may be a total of 120 variables in the choice function C (excluding quantifiers). Is there a choice function (ignoring quantifiers) which answers criteria (1), (2), (3) & (4) of the main question in Section 3 for a "larger" subset of \mathbb{R}^A ? (This might be impossible to answer since such a solution cannot be shown with [prevalence or shyness](#) [11,15])—therefore, we need a more precise version of "size" with some examples, again, shown in [9].
3. If question (2) is correct, what is the choice function C using either Equations (4.4.1)–(4.4.3) fully answers the question in Section 3?
4. Can either Equations (4.4.1)–(4.4.3) (when A is the set of all [Liouville numbers](#) [6] and $f = \text{id}_A$) give a finite value? What would the value be?

5. Similar to how definition 11 in Section 5 approximates the expected value in definition 1, how do approximate Equations (4.4.1)–(4.4.3)?
6. Can programming be used to estimate Equations (4.4.1)–(4.4.3) respectively (if an unique/finite result of either of the expected values exist)?

4.6. Applications

1. In Quanta magazine [3], Wood writes on Feynman Path Integrals: “No known mathematical procedure can *meaningfully average* (Meaningful Average—The average answers the main question in Section 3) an infinite number of objects covering an infinite expanse of space in general. The path integral is more of a physics philosophy than an exact mathematical recipe.”—despite Wood’s statement, mathematicians Bottazzi E. and Eskew M. [5] found a constructive solution to the statement using integrals defined on filters over families of finite sets; however, the solution was not unique as one has to choose a value in a partially ordered ring of infinite and infinitesimal elements.
 - (a) Perhaps, if Bottazzi’s and Eskew’s Filter integral [5] is not enough to solve Wood’s statement, could we replace the path integral with expected values from Equations (4.4.1)–(4.4.3) respectively (or a complete solution to section 3)? (See, again, Section 5.1 for a visualization of Wood’s statement.)
2. As stated in Section 2.1, “when the Lebesgue measure of A , measurable in the Caratheodory sense, has zero or infinite volume (or undefined measure), there may be multiple, conflicting ways of defining a “natural” uniform measure on A .” This is an example of [Bertand’s Paradox](#) which shows, “the [principle of indifference](#) (that allows equal probability among all possible outcomes when no other information is given) may not produce definite, well-defined results for probabilities if applied uncritically, when the domain of possibilities is infinite [17].

Using Section 4.1, perhaps if we take (from Definition 4.2.12):

$$C'(A) = \begin{cases} C(A) & \text{if } C(A) \text{ contains one element} \\ C^j(A) & \text{if } j \in \mathbb{N}, \text{ such for all } k \geq j, C^k(A) \text{ contains one element} \\ C^\infty(A) & \text{if it exists, and } C^\infty(A) \text{ contains one element} \end{cases}$$

then for $\{F_r''\}_{r \in \mathbb{N}} \in C'(A)$, if we want $S \subseteq A$ and we get the following:

$$\exists(\mathbf{U}(S) \in \mathbb{R}) \forall(\epsilon > 0) \exists(N \in \mathbb{N}) \forall(r \in \mathbb{N}) \left(r \geq N \implies \frac{U'(S \cap F_r'')}{U'(F_r'')} - \mathbf{U}(S) < \epsilon \right) \quad (4.6.1)$$

Then $\mathbf{U}(S)$ might serve as a solution to [Bertand’s Paradox](#) (unless there’s a better $C'(A)$ and $\{F_r''\}_{r \in \mathbb{N}} \in C'(A)$ which completely solves the main question in Section 3).

Now consider the following:

- (a) How do we apply $\mathbf{U}(S)$ (or a better solution) to the usual example which demonstrates the [Bertand’s Paradox](#) as follows: for an equilateral triangle (inscribed in a circle), suppose a chord of the circle is chosen at random—what is the probability that the chord is longer than a side of the triangle? [4] (According to [Bertand’s Paradox](#) there are three arguments which correctly use the principle of indifference yet give different solutions to this problem [4]:
 - i. The “random endpoints” method: Choose two random points on the circumference of the circle and draw the chord joining them. To calculate the probability in question imagine the triangle rotated so its vertex coincides with one of the chord endpoints. Observe that if the other chord endpoint lies on the arc between the endpoints of the

- triangle side opposite the first point, the chord is longer than a side of the triangle. The length of the arc is one-third of the circumference of the circle, therefore the probability that a random chord is longer than a side of the inscribed triangle is $1/3$.
- ii. The "random radial point" method: Choose a radius of the circle, choose a point on the radius, and construct the chord through this point and perpendicular to the radius. To calculate the probability in question imagine the triangle rotated so a side is perpendicular to the radius. The chord is longer than a side of the triangle if the chosen point is nearer the center of the circle than the point where the side of the triangle intersects the radius. The side of the triangle bisects the radius, therefore the probability a random chord is longer than a side of the inscribed triangle is $1/2$.
 - iii. The "random midpoint" method: Choose a point anywhere within the circle and construct a chord with the chosen point as its midpoint. The chord is longer than a side of the inscribed triangle if the chosen point falls within a concentric circle of radius $1/2$ the radius of the larger circle. The area of the smaller circle is one-fourth the area of the larger circle, therefore the probability a random chord is longer than a side of the inscribed triangle is $1/4$.

5. Glossary

5.1. Example of Case (2) of Worst Case Functions

(If the explanation below is difficult to understand, [see this visualization to accompany the explanation \[1\]](#), where when changing the sliders each time, wait a couple of seconds for the graph to load.)

We wish to create a function that appears to be a "pseudo-randomly" distributed but has infinite points that are non-uniform (i.e. does not have [complete spatial randomness \[13\]](#)) in the sub-space of \mathbb{R}^2 , where the expected value or integral of the function w.r.t [uniform probability measure \[18\]](#) [p.32-37] is non-obvious (i.e. not the center of the space the function covers nor the area of that space).

Suppose for real numbers x_1, x_2, y_1 and y_2 , we generate an uncountable number of "nearly pseudo-random" points that are non-uniform in the subspace $[x_1, x_2] \times [y_1, y_2] \subseteq \mathbb{R}^2$.

We therefore define the function as $f : [x_1, x_2] \rightarrow [y_1, y_2]$.

Now suppose $b \in \{2, 3, \dots, 10\}$ where the base- b expansion of real numbers, in interval $[x_1, x_2]$, have infinite decimals that approach x from the right side so when $x_1 = x_2$ we get $f(x_1) = f(x_2)$.

Furthermore, for $\mathbb{N} \cup \{0\} = \mathbb{N}_0$, if $r \in \mathbb{N}_0$ and $\text{digit}_b : \mathbb{R} \times \mathbb{Z} \rightarrow \{0, 1, \dots, b-1\}$ is a function where $\text{digit}_b(x, r)$ takes the digit in the b^r -th decimal fraction of the base- b expansion of x (e.g. $\text{digit}_{10}(1.789, 2) = 8$), then $\{g_r'\}_{r \in \mathbb{N}_0}$ is a sequence of functions such that $g_r' : \mathbb{N}_0 \rightarrow \mathbb{N}_0$ is defined to be:

$$g_r'(x) = \left\lfloor \frac{10}{b} \sin(rx) + \frac{10}{b} \right\rfloor \quad (5.1.1)$$

then for some large $k \in \mathbb{N}$ and $x_1, x_2 \in \mathbb{R}$, the intermediate function (before f) or $f_1 : [x_1, x_2] \rightarrow \mathbb{R}$ is defined to be

$$f_1(x) = \left| \left(\sum_{r=0}^{\infty} g_{r+1}' \left(\sum_{p=r}^{r+k} \text{digit}_b(x, p) \right) \right) / b^r - 10 \right| = \left| \left(\sum_{r=0}^{\infty} \left[\frac{10}{b} \sin \left((r+1) \left(\sum_{p=r}^{r+k} \text{digit}_b(x, p) \right) \right) + \frac{10}{b} \right] / b^r - 10 \right) \right| \quad (5.1.2)$$

where the points in f_1 are "almost pseudo-randomly" and non-uniformly distributed on $[x_1, x_2] \times [0, 10]$. What we did was convert every digit of the base- b expansion of x to a pseudo-random number that is non-equally likely to be an integer, including and in-between, 0 and $(10 \cdot 10^s)/b$. Furthermore, we also make the function appear truly "pseudo-random", by adding the b^r -th decimal fraction with the next k

decimal fractions; however, we want to control the end-points of $[0, 10^{s+1}]$ such if $y_1, y_2 \in \mathbb{R}$, we convert $[x_1, x_2] \times [0, 10]$ to $[x_1, x_2] \times [y_1, y_2]$ by manipulating Equation (5.1.2) to get:

$$f(x) = y_2 - \frac{y_2 - y_1}{10} f_1(x) \quad (5.1.3)$$

$$y_2 - \left(\frac{y_2 - y_1}{10} \right) \left| \left(\sum_{r=0}^{\infty} \left[\frac{10}{b} \sin \left((r+1) \left(\sum_{p=r}^{r+k} \text{digit}_b(x, p) \right) \right) + \frac{10}{b} \right] \right) / b^r - 10 \right|$$

such the larger k is, the more pseudo-random the distribution of points in f in the space $[x_1, x_2] \times [y_1, y_2]$, but unlike most distributions of such points, f is uncountable.

5.2. Question Regarding Section 4.1

Let us give a specific example, suppose for the function in Equation (5.1.3) of Section 5.1, we have:

- $b = 3$
- $[x_1, x_2] \times [y_1, y_2] = [0, 1] \times [0, 1]$
- $k = 100$

(one can try simpler parameters); what is the expected value using either Equations (4.4.2) and (4.4.3) (or a more complete solution to section 3) if the answer is finite and unique?

What about for f in general (i.e. in terms of b, x_1, x_2, y_1, y_2 and k)?

(Note if $x_1, y_1 \rightarrow -\infty$ and $x_2, y_2 \rightarrow \infty$, then the function is an explicit example of the function that Wood (Wood wrote on Feynman Path Integrals: “No known mathematical procedure can *meaningfully average* 1 an infinite number of objects covering an infinite expanse of space in general.”) describes in Quanta Magazine)

5.3. Approximating the Expected Value

Definition 11 (Approximating the Expected Value). *In practice, the computation of this expected value may be complicated if the set A is complicated. If analytic integration does not give a closed-form solution then a general and relatively simple way to compute the expected value (up to high accuracy) is with **importance sampling**. To do this, we produce values $\mathbf{X}_1, \mathbf{X}_2, \dots, \mathbf{X}_M \sim \text{IID } g$ for some density function g with support $A \subseteq \text{support}(g) \subseteq \mathbb{R}^n$ (hopefully with support fairly close to A) and we use the estimator:*

$$\hat{\mu}_M \equiv \frac{\sum_{i=1}^M \mathbb{I}(\mathbf{X}_i \in A) \cdot f(\mathbf{X}_i)/g(\mathbf{X}_i)}{\sum_{i=1}^M \mathbb{I}(\mathbf{X}_i \in A)/g(\mathbf{X}_i)} \quad (5.3.1)$$

From the law of large numbers, we can establish that $\mathbb{E}[f(\mathbf{X})] = \lim_{M \rightarrow \infty} \hat{\mu}_M$ so if we take M to be large then we should get a reasonably good computation of the expected value of interest.

Note importance sampling requires three things:

1. We need to know when point x is in set A or not
2. We need to be able to generate points from a density g that is on a support that covers A but is not too much bigger than A
3. We have to be able to compute $f(x)$ and $g(x)$ for each point $x \in A$

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