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SURFACE FEATURES OF AS-BUILT METAL ADDITIVE ALSI7MG0.6

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ABSTRACT

Additive manufacturing (AM) technologies show potential for the development of functionally integrated lightweight designs, biomimetic structures and material savings. Typically, as-built surfaces show powder particle agglomerations and re-entrant features, leading to rough surfaces, are associated with poor performance. To benefit from the full range of advantages with special focus on aerospace applications, critical features for crack initiation when subjected to fatigue loading need to be identified and mitigated.

A first step toward achieving this goal is the surface texture characterisation based on the quantification of surface features.

In this paper, selected areal height, functional and feature parameters from ISO 25178-2:2022 are generated and process-specific features are examined for as-built AlSi7Mg0.6 from laser powder bed fusion (PBF-LB). A connection with the particle size distribution of the used powder is demonstrated.

It is shown that surface feature analysis opens up opportunities to use physically meaningful surface characteristics in future quality assurance and part qualification processes.

1. INTRODUCTION

Over the last two decades, additive manufacturing (AM) technologies evolved from rapid prototyping of porous structures to production of high-quality parts. AM enables design freedom, as well as reduction of material waste and cost [1, 2]. However, when qualifying an AM part for load-bearing aerospace applications, surface texture is of particular interest with respect to fatigue performance [1] and requires new approaches to quality assessment (QA).

In industrial QA, the generation of profile parameters such as *Ra* (arithmetic mean deviation of the assessed profile) or *Rt* (total height of profile), for data acquired using a contact stylus

measurement system, is the status quo [3]. Due to the low statistical relevance of individual profile measurements for the assessment of surface quality [4] and the increasing application of optical measurement systems, their areal equivalent parameters, Sa and Sz, have gained relative acceptance in recent years. However, Sa and Sz are still based on height variation with respect to a mean plane, rather than representing the actual size of a topography element. The restriction to height variation leads to the same value of Ra/Sa representing surfaces with different surface features, different material ratios [5] and different mechanical, adhesive and corrosive behaviours.

Areal measurements, as compared to profile measurements, offer a more representative depiction of surface topography and enable the extraction of characteristic surface features [3, 4, 6]. Several feature parameters describing various geometric properties of hills and dales are included in the latest version of ISO 25178 [7]. Beyond the consideration of hills and dales, process-related surface features can be evaluated. Frequently observed features in powder-based AM are particle agglomerations of different size. In recent years, extensive work has been done on developing methods for segmentation and feature detection and their application to AM surfaces [8-15].

In this work, we focus on the evaluation of surface properties related to powder particle agglomerations, such as size and quantity, as well as the area portion of the surface covered by attached particles and their relation to the particle size distribution of the powder used in the process. Furthermore, selected ISO 25178 [7] feature parameters derived from hill and dale properties after watershed segmentation are generated.

The surface topography is measured by focus variation (FV) microscopy, which is an optical non-contact method based on stacking images from different focal planes of the same location in *z*-direction. An advantage of this technology is its robustness to variation of optical surface properties such as reflectivity [16, 17].

Surfaces of fatigue specimens in as-built condition from a laser-beam powder bed fusion (PBF-LB) process made of AlSi7Mg0.6 material are examined in this study.



2. MATERIALS AND METHODS

2.1. Samples

The evaluated samples are fatigue specimens according to ASTM 466–15 (total height 80 mm, smallest cross section width 6 mm, and thickness 3 mm, shown in Figure 1) produced in a laser-based powder bed fusion (PBF-LB) process from AlSi7Mg0.6 material, manufactured on a Trumpf TruePrint 1000 system using the parameter settings specified in Table 1.

Bulk and contour parameter sets were previously optimised for density and surface texture, respectively [18]. The optimisation resulted in a layer thickness of 30 μ m and a hatch spacing of 0.12 mm for both, bulk and contour. The specimen bulk was produced with a laser power of 166 W at a scan speed of 1000 mm/s. For the contour scan, these settings were adjusted to 195 W and 300 mm/s.

The eight specimens examined in this work originate from a larger surface variation study and are part of the smoothest surface group produced (for details, see [18-20]).

Table 1: AlSi7Mg0.6 manufacturing parameters for bulk and contour.

Bulk	Contour
30	30
0.12	0.12
166	195
No	Yes
1000	300
	30 0.12 166 No

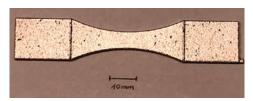


Figure 1: Fatigue specimen geometry according to ASTM 466-15.

2.2. Surface Measurement

The surfaces were measured using an Alicona Infinite Focus G5 focus variation (FV) instrument with unpolarised coaxial lighting at 10x magnification with an individual image field of view (FOV) of $1.62 \text{ mm} \times 1.62 \text{ mm}$. To measure the entire marked area of about 3 mm \times 20 mm on each sample, up to 3×14 images were stitched. All measurements were taken with a vertical resolution $< 0.1 \ \mu \text{m}$ and a lateral resolution of $2.5 \ \mu \text{m}$.

2.3. Surface Data Evaluation

The data evaluation was performed in MountainsMap® V9.2. To reduce calculation time, a 3 mm × 6 mm area portion centred within the measured area was extracted and a total number of

eight data sets from different samples (I to VIII) was used to obtain the results presented in this work.

For reference, height and functional parameters form ISO 25178 were generated. An overview of all parameters used is given in Table 2.

Feature parameter evaluation according to ISO 25178 and process-specific feature analysis were performed. Pruning threshold values were selected in accordance with powder characteristics, namely half the d10 diameter of the used AlSi7Mg0.6 powder [21], resulting in the applied height pruning value of 13.5 μ m.

Table 2: Overview of Parameters generated.

Parameter / Unit	Description
<i>Sz</i> /µm	Maximum total height of profile
<i>Sa</i> /μm	Arithmetic mean height of profile
<i>Sk</i> /µm	Core height
<i>Spk</i> /μm	Reduced peak height
<i>Svk</i> /µm	Reduced valley depth
Spd/mm ⁻²	No. of peaks per unit area
Svd/mm ⁻²	No. of valleys per unit area
<i>Shh</i> /µm	Mean local hill height
d _{max} /mm	Average max. particle diameter
<i>z_{max}</i> /µm	Average max. particle z-height
Area covered/%	Particle coverage
Particle density/mm ⁻²	No. of particles per unit area

2.3.1. Surface Feature Parameters from ISO 25178

Selected surface feature parameters were calculated after applying a Gaussian convolution S-filter of 5.3 μ m, a least-squares plane level operation and an L-filter of 0.25 mm.

The feature parameters specified in ISO 25178 describe hill and dale properties and are obtained from surface data after watershed segmentation and height pruning. For more information, refer to [4, 15].

The considered parameters are the density of valleys, *Svd*, the density of peaks, *Spd*, and the mean local hill height *Shh*. For details on the individual calculation of these parameters, refer to [4].

2.3.2. Process-specific Areal Surface Features

Particle agglomerations are significant processspecific features observed on PBF-LB surfaces. The circle detection method implemented in the MountainsMap® particle analysis module was used to isolate the specific features on the surfaces.

For this purpose, at first, a very small bandwidth was filtered to only maintain sharp edges (= particle boundaries), applying an L-filter of 0.0055 mm. Subsequently, the circle detection algorithm was applied, using limit values for detection diameters again, based on the particle size distribution values d10 = 27 μ m and d90 = 67 μ m. The minimum diameter for detection was set to 20 μ m, somewhat lower than d10, while the maximum was chosen as 200 μ m, roughly three times d90 to account for the possibility of clustered agglomerations.

In order to find the original height of the detected

particles, the previously obtained mask was applied to the initial (primary) surface (after application of S-filter and F-operation).

The evaluated characteristics are the average maximum particle diameter d_{max} , maximum particle z-height z_{max} , percentage area portion covered by detected particles and finally, the particle density.

3. RESULTS

The 3D representation of one of the examined surfaces and the corresponding focus variation microscopic image in Figure 2 show powder particle agglomerations as the dominant process-specific feature at the considered scale for this surface type. This upcoming results section is split in three subsections, where ISO 25178 height and functional parameters, standardised feature parameters, and finally, characteristic values derived from process-specific areal surface features are presented.

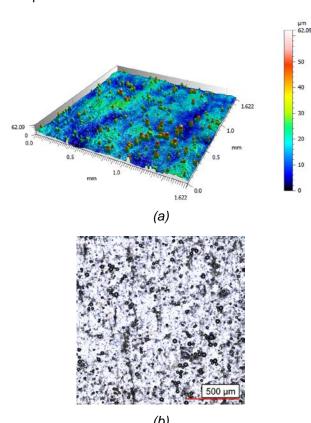


Figure 2: (a) 3D view, (b) Focus variation microscopy image; As-built AlSi7Mg0.6 surface, 1 FoV (1.62 mm × 1.62 mm), showing PBF-LB-typical particle agglomeration features.

3.1. Height and Functional Surface Texture Parameters from ISO 25178

For reference, the areal surface texture parameters Sa (arithmetic mean height of profile) and Sz (maximum total height of profile) were calculated. Furthermore, the material ratio curve parameters Sk (core height), Spk (reduced peak height) and Svk

(reduced valley depth) were generated. Numerical results including mean value and standard deviation (SD) for the listed parameters are given in Table 3.

Table 3: Common parameters Sa and Sz, Material ratio curve parameters Sk, Spk and Svk; L-filter = 0.25 mm, N = 8

N = 8	Sz/µm	Sa/µm	Sk/µm	S <i>pk</i> /µm	Svk/µm
Mean	61.74	1.76	4.87	5.21	2.12
SD	7.68	0.11	0.23	0.90	0.13

Figure 3 shows the exemplary material ratio curve of sample IV. From the curve, combined with the numerical values, a relatively flat core slope with steep decreases from the peak and toward the valley portion can be observed.

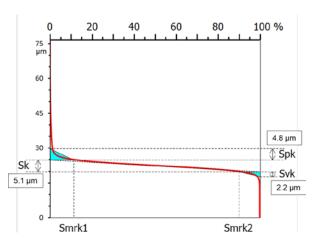


Figure 3: Material ratio curve (sample IV), L-filter 0.25 mm.

3.2. Surface Feature Parameters from ISO 25178

Figure 4 shows the watershed segmentation of the extracted 3 mm by 6 mm area of sample IV based on hill features; (+) denotes the location of the highest point of each segment. The colours are used to simplify the visual differentiation of adjacent particles. Due to the selected height pruning threshold of 13.5 μ m, features smaller than half the d10 diameter (d10 = 27 μ m) are merged with adjacent hill segments.

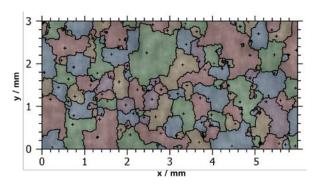


Figure 4: Example "watershed segmentation" (sample IV) with height pruning 13.5 μm; (+): highest point per segment.

In Table 4, Spd (peak density), Svd (valley density) and Shh (mean local hill height) are listed. It is notable, that Svd is equal for all the considered samples with 13.5 μ m height pruning. The value of $Svd = 0.06 \, \text{mm}^{-2}$ originates from the total valley count of one over the entire considered (3 × 6) mm² area.

Table 4: Feature parameters Spd, Svd and Shh; Height pruning 13.5×µm.

N = 8	Spd/mm ⁻²	Svd/mm ⁻²	<i>Shh</i> /μm
Mean	10.10	0.06	22.39
SD	3.48	0.00	1.42

3.3. Process-specific Areal Surface Features

The values presented in Table 5 were obtained from the MountainsMap® V9.2 particle analysis circle detection module. A variety of characteristic values on feature size, shape, distribution and quantity can be generated. The presented initial selection was based on possible relation to powder particle size and potential relevance for fatigue performance, which will be subject of future work.

Table 5: Process-specific feature characteristics, Height pruning 13.5 µm.

N = 8	d _{max} /mm	<i>z_{max}</i> /µm	area covered /%	particle density /mm ⁻²
Mean	27.74	33.64	1.35	21.80
SD	1.87	4.19	0.28	5.68

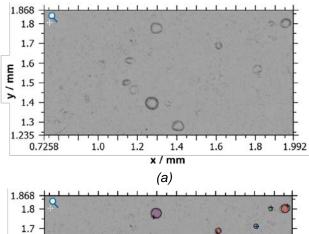
For clarity, the chosen parameters are explained in a bit more detail. d_{max} is the largest diameter of a detected particle, meaning, for a (near-) spherical agglomerated particle, and represents the (partial) sphere diameter. The z_{max} value gives the average of maximum particle z-heights with respect to the lowest point on the surface of all detected particles on the surface. Finally, the percentage of area covered by detected particles and the number of detected particles per unit area (particle density) are given.

Figure 5 shows an area portion on sample IV with circular and near-circular shaped features that could be detected. The top image is the S-L surface with an L-filter of 0.0055 mm. This very low value was chosen to only keep particle attachments and cut out other surface irregularities and waviness. In the bottom image, detected circular particles are marked. The (+) sign again, denotes the highest point on each individual particle.

4. DISCUSSION

From visual inspection, it is confirmed that the dominant process-specific feature on the considered surface condition is agglomeration of powder particles. Examining Table 3, it is clear from the material ratio curve that the peak portion represented by *Spk*, is considerably larger than the valley population on the surface. The core part of

the sample IV curve (Figure 3) is fairly flat and exhibits a steep slope toward the peaks and valleys, where the maximum peak size (e.g., Figure 3: above 75 µm) is significantly larger than the maximum valley size, which is related to attached particles on an otherwise presumably flat surface. Using Sa as a common and widely known parameter, the surface condition can be considered to be comparatively smooth to other PBF-LB parts (as-built PBF-LB parts can easily exceed an Sa/Ra of 20 µm under similar filtering conditions, depending on material and processing [17, 22]).



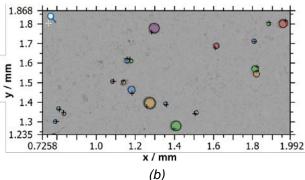


Figure 5: Example "circle detection" (sample IV), min. diameter 20 μm, max. diameter 200 μm; (a) Extracted area with (near) circular features, (b) Detected circular features (same area).

Correspondingly, the Svd value of 0.06 mm⁻² (see Table 4) over the extracted area on each of the considered samples (N = 8) counts one single dale, meaning, there are no significant dales present with a height pruning value of 13.5 μ m on the studied surface condition.

Considering the peak density Spd, there can be significant hills identified on the surface, which is again in agreement with the material ratio curve results (see Figure 3, Table 3). The mean local hill height Shh with 22.39 μm matches the order of magnitude of the d10 of 27 μm and is hence representative of the expected feature size.

Moving on toward the discussion of the process-specific feature characteristics, d_{max} and z_{max} are with 28 µm and 34 µm on average similarly close to the d10 size. Considering respective standard deviations (Table 5), it can be concluded that this is equally applying to all evaluated specimens. This

suggests that the strategy of using a small L-filter value to only retain sharp edges (i.e., particle boundaries) seems to have been effective.

At this point it is emphasised that the generated mean values are based on averages per sample and given standard deviations represent the difference in mean value among the eight assessed specimens.

The area of less than 2% covered with particles will supposedly be of interest in comparison with other as-built surfaces (e.g. those introduced in [18]) and in regard to correlation with mechanical properties. The final feature characteristic value to be discussed is the particle density. While the description itself may suggest similarities to the peak density Spd, the mean value is more than twice as high. This considerable deviation is owing differences in the detection/segmentation methods and reference surfaces. Firstly, the circle detection is based on an S-L surface with small bandwidth to reliably filter smooth height variations with continuous slopes (waviness or similar) and particles are detected based on their shape rather than height. The peaks are counted based on the original surface (levelled and S-filtered) after watershed segmentation, where it is likely that two adjacent particles are part of the same segment and due to height pruning (combination of smaller features), only the highest of both is counted as segment peak.

Secondly, even though identical height pruning values are applied, the pruning is performed with respect to different reference points. While for the ISO 25178 parameters, the height of a hill feature is defined with respect to the highest saddle point on its course line [4] and is merged with the adjacent taller hill if below the threshold value, detected circular particles will only be merged when overlapping. This being addressed, Figure 4 and 5 clarify the large difference in particle and peak density.

5. CONCLUSIONS AND FUTURE PROSPECTS

This work provides an insight into the opportunities for novel approaches to quality assurance concepts using feature parameters and process-specific surface features for surface texture characterisation of metal additive parts, specifically of AlSi7Mg0.6 specimens from PBF-LB.

In summary, for the examined surface type with the selected measurement method, configuration and software tool settings, the following conclusions are drawn:

- Evaluated feature parameters correspond with the (qualitative) implications of heightbased parameters from the material ratio curve (hills/dales, peak/valley portion).
- Mean values of the surface feature characteristics and parameters can be

linked with particle size of the powder used in the manufacturing process.

In comparison to common height variation-based parameters such as *Sa* and *Sz*, feature parameters and characteristics describe properties of physical topography elements rather than being based on deviation from a mean line or individual extreme values. The material ratio curve parameters on the other hand, could provide an insight on the height distribution, identifying a smaller valley than peak portion, which matched well with the feature parameter results.

However, the material ratio curve only provides information about the height distribution, while the characterisation of surface features can provide an understanding of present feature shapes, size distribution or quantity. This approach can be of interest when trying to understand relationships between surface quality and mechanical performance (e.g. fatigue), corrosion or adhesion. The presented results give a first idea of the prospects of quantifying the PBF-LB-specific powder particle agglomeration features based on mean values per specimen. Ongoing work includes more detailed examinations of distribution and frequency of detected particle sizes on individual samples.

Additional aspect to be considered in future work are the challenges imposed on optical metrology systems regarding the accurate representation of surface features and on evaluation software concerning their comprehensive detection.

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