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Article

Mathematical Analysis of a Navier Stokes Model with Mittag-Leffler Kernel

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Abstract: In this paper, we establish the existence and uniqueness results of the fractional Navier-Stokes evolution equation using the Banach fixed point theorem, where the fractional order β is in the form of the Atangana-Baleanu Caputo fractional order. The iterative method combined with the Laplace transform and Sumudu transform are employed to find the exact and approximate solutions of the fractional Navier-Stokes equation of a one-dimensional problem of unsteady flow of a viscous fluid in a tube. Mathematica software is used to present the solutions graphically.

Keywords: Atangana-Baleanu Caputo fractional derivative; Navier-Stokes equation; Laplace transform; Sumudu transform; iterative method (IM)

1. Introduction

In this paper, we discuss the existence and the uniqueness of the solution of the time-fractional Navier-Stokes equation of a viscous fluid in unsteady flow through a tube applied to Atangana-Baleanu Caputo fractional derivative (fractional derivatives without singular kernel). The Navier-Stokes equation is specified as the nonlinear partial differential equation that describes the motion of an incompressible Newtonian fluid and it was named in honor of French engineer Claude-Louis Navier (1785-1836) and English physicist and mathematician Sir George Gabriel Stokes (1819-1903). Is referred to as Newtonian fluid because it was derived using Newton's second law of motion by considering the forces acting on the fluid elements so that the stress tensor appears in the form of the usual Cauchy momentum equation. This Navier-Stokes equation is the generalization of the equation of motion pioneered by the famous Swiss mathematician Leonhard Euler (1707-1783) to describe the flow of incompressible and frictionless fluids. Navier-Stokes equations are used to model water flow in a pipe, weather forecasting, ocean currents, and airflow around a wing [1]. Furthermore, they assist with the design of cars and aircraft, the study of blood flow, the analysis of pollution, the design of power stations, and a lot of other things. Together with Maxwell's equations, they may be utilized to model and study the magneto-hydrodynamics [1].

The fractional Navier-Stokes equation has been handled by many researchers, such as in [2–8]. In [7] the Adomian decomposition method (ADM) was utilized by applying the operator J^{α} , the inverse of the operator D^{α} on both sides of the fractional Navier-Stokes equation, where D^{α} is the Caputo time-fractional differential operator of order $\alpha > 0$. The Caputo time fractional Navier-Stokes equation, which describes the motion of a viscous fluid in a tube, has been solved in [4] by combining the Laplace transform with the Adomian decomposition approach. In [2], the Caputo time fractional Navier-Stokes equation describing the motion of a viscous fluid in a tube was solved using the homotopy perturbation transform method (HPTM). In [3], the Caputo-Fabrizio time-fractional Navier-Stokes equation was solved utilizing the iterative Laplace transform method (ILTM). The existence and uniqueness of the Navier-Stokes equation solutions with fractional time derivatives were examined in [5]. The improved Navier-Stokes (N-S) equation with fractional derivative to

explore the unsteady translational motion of a rigid sphere in an incompressible viscous fluid was handled in [6].

In [2], the Navier-Stokes equation is determined as the essential condition of computational liquid elements, relating pressure and external forces following up on a liquid to the reaction of the liquid stream.

In this study, we model the fractional Navier-Stokes equation. The fractional Navier-Stokes and continuity equation are given as [2]

$$\begin{cases} {}^{CFD}D_t^{\beta}\mathbf{u} + (\mathbf{u} \cdot \nabla)\mathbf{u} = -\frac{1}{\rho}\nabla \mathbf{p} + \nu \nabla^2 \mathbf{u}, \ 0 < \beta \le 1, t > 0, \\ \nabla \cdot \mathbf{u} = 0, \end{cases}$$
(1)

where, **u** is the fluid velocity, **p** is the fluid pressure, ν is the fluid viscosity, ρ is the fluid density, $^{CFD}D_t^{\beta}$ is the Caputo fractional derivative, ∇ is the gradient differential operator and ∇^2 is the Laplacian operator. It is important to mention that, if the viscosity (ν) is set equal to zero, then the Navier-Stokes equation (1) reduces to Euler's equation of motion of incompressible and frictionless fluids.

Because our objective is to access the impact of the Mittag-Leffler kernel on the Navier-Stokes system, hence, we replace ${}^{CFD}D_t^{\beta}\mathbf{u}$ with ${}^{ABCFD}D_t^{\beta}\mathbf{u}$ in Eq. (1), so that the resulting equation is the fractional Navier-Stokes equation in Atangana-Baleanu Caputo sense. Therefore, we consider the new fractional Navier-Stokes equation in the Atangana-Baleanu Caputo sense and its initial condition as

$$\begin{cases} {}^{ABCFD}D_t^{\beta}\mathbf{u} + (\mathbf{u} \cdot \nabla)\mathbf{u} = -\frac{1}{\rho}\nabla \mathbf{p} + \nu \nabla^2 \mathbf{u}, & 0 < \beta \le 1, t > 0, \\ \nabla \cdot \mathbf{u} = 0, \end{cases}$$
 (2)

Then we intend to find the solution using the Laplace or Sumudu transform of the ABCFD coupled with the iterative method (IM) applied to a one-dimensional problem of unsteady flow of a viscous fluid in a tube. The advantage of using this method is that we combine the two methods, namely: the Laplace or Sumudu transform and the iterative method (IM) which are very useful for finding the exact and approximate solutions of linear and nonlinear differential equations, moreover the method helps with avoiding many and complicated computational tasks as compared to the normal technique. Another advantage is that the ABCFD applied in Equation (2) is non-local, meaning that when modeling a real physical phenomenon, the state of the system does not only depend on the present time but also the history.

The fractional Navier-stokes equation (2) along with its initial condition can be written in terms of cylindrical coordinates as follows (see [2–4])

$$\frac{\partial^{\beta} \mathbf{u}}{\partial t^{\beta}} = -\frac{1}{\rho} \frac{\partial \mathbf{p}}{\partial z} + \nu \left[\frac{\partial^{2} \mathbf{u}}{\partial r^{2}} + \frac{1}{r} \frac{\partial \mathbf{u}}{\partial r} \right], \tag{3}$$

subject to the following initial condition

$$\mathbf{u}(r,0) = g(r),\tag{4}$$

where $\frac{\partial^{\beta}\mathbf{u}}{\partial t^{\beta}} = \frac{ABCFD}{a}D_{t}^{\beta}u(t)$ is the Atangana-Baleanu fractional derivative in Caputo sense.

2. Preliminaries

In this section, we recall some definitions and theorems of fractional calculus which are very important for our study.

Definition 2.1. Let $u \in H^1(a, b)$, a < b, $\beta \in [0, 1]$, then Atangana-Baleanu Fractional Derivative in Caputo sense is given by [9-11]

$${}_{a}^{ABCFD}D_{t}^{\beta}u(t) = \frac{{}_{B}(\beta)}{(1-\beta)} \int_{a}^{t} \dot{u}(\tau) E_{\beta} \left(-\frac{\beta(t-\tau)^{\beta}}{1-\beta}\right) d\tau, \tag{5}$$

where $B(\beta)$ is a normalization function such that B(0) = B(1) = 1 and E_{β} is the Mittag-Leffler function (MLF) defined as:

$$E_{\beta}(\chi) = \sum_{k=0}^{\infty} \frac{\chi^k}{\Gamma(\beta k + 1)}, \ \beta > 0.$$
 (6)

Theorem 2.1. The Laplace transform of the ABCFD is specified as [9, 11]

$$\mathcal{L}\left[{}_{0}^{ABCFD}D_{t}^{\beta}u(t)\right](s) = \frac{{}_{B(\beta)}}{1-\beta} \frac{s^{\beta}\mathcal{L}[u(t)](s) - s^{\beta-1}u(0)}{s^{\beta} + \frac{\beta}{1-\beta}}$$
(7)

Definition 2.2 [11,12]. The Sumudu transform is obtained over the set of functions

$$A = \left\{ u(t) : \exists M, \eta_1, \eta_2 > 0, |u(t)| < Me^{\frac{|t|}{\eta_i}}, \quad \text{if } t \in (-1)^i \times [0, \infty) \right\}$$

and is given by

$$S[u(t)] = \int_0^\infty u(st)e^{-t}dt, \ s \in (-\eta_1, \eta_2).$$

Definition 2.3. The Sumudu transform of the ABCFD is defined as follows [11]:

$$S\left({}^{ABCFD}D_t^{\beta}u(t)\right) = \frac{{}^{B(\beta)}}{{}^{1-\beta(1-s^{\beta})}} \left(S(u) - u(0)\right). \tag{8}$$

Theorem 2.2. The ABCFD and its fractional integral of a function u(t) satisfy the Newton-Leibniz formula

$$u(t) - u_o = {}^{ABFI}I_t^{\beta} \left({}^{ABCFD}D_t^{\beta}u(t) \right)$$

where ^{ABFI}I is the Atangana-Baleanu fractional integral so that we have

$$u(t) = u_o + \frac{1-\beta}{B(\beta)}u(t) + \frac{\beta}{B(\beta)\Gamma(\beta)} \int_0^t (t-\tau)^{\beta-1} u(\tau) d\tau.$$
 (9)

3. Existence and Uniqueness of Nonlinear Fractional Derivatives with Respect to ABCFD

In this section, we apply Banach fixed-point theorem to establish the existence and uniqueness results of the fractional initial value problem and we further show that the results also hold for fractional Navier-Stokes equation (3) and the initial condition (4).

To continue we consider the following fractional initial value problem

$$\begin{cases} {}^{ABCDF}D_t^{\beta}u(t) = g(t, u(t)), \ 0 < \beta \le 1, t > 0, \\ u(0) = u_o. \end{cases}$$
 (10)

Theorem 3.1. Let $u \in H^1(0,1)$, then u is a solution to the fractional initial value problem (10), if and only if, it is a solution to the following integral equation

$$u(t) = u_0 + \frac{1-\beta}{B(\beta)}g(t, u(t)) + \frac{\beta}{B(\beta)\Gamma(\beta)} \int_0^{\tau} g(\tau, u(\tau))(t-\tau)^{\beta-1} d\tau, \tag{11}$$

Proof of Theorem 3.1. Applying the Atangana-Baleanu fractional integral ${}^{ABFI}I_t^{\beta}$ on both sides of Equation (10) and utilizing the properties of the inverse operator, will lead us to Equation (11). \Box

Theorem 3.2. Consider the fractional initial value problem (10), where g(t, u(t)) is a smooth function. If g(t, u(t)) is the Lipschitz function with Lipschitz constant

$$\frac{(1-\beta)\Gamma(\beta)+t^{\beta}}{\Gamma(\beta)B(\beta)}L < 1, \tag{12}$$

then the fractional initial value problem (10) has a unique solution in $H^1(0,1)$.

Proof of Theorem 3.2. Define the norm on [0, 1] by

$$||u|| = \sup_{t \in [0,1]} |u(t)|, \ \forall u \in H^1(0,1)$$

and consider the operator $T: H^1(0,1) \to H^1(0,1)$, defined by

$$(Tu)(t) = u_0 + \frac{1-\beta}{B(\beta)}g(t, u(t)) + \frac{\beta}{B(\beta)\Gamma(\beta)} \int_0^{\tau} g(\tau, u(\tau))(t-\tau)^{\beta-1} d\tau$$

According to Theorem 3.1, obtaining a solution to the initial value problem (10) is equivalent to finding a fixed point of T. Now, for all $u_1(t), u_2(t) \in H^1(0,1)$ and $t \in [0,1]$, we have

$$\begin{split} |T(u_1)(t) - T(u_2)(t)| &= \bigg| \frac{1-\beta}{B(\beta)} \Big(u(t,u_1(t)) - u(t,u_2(t)) \Big) \\ &+ \frac{\beta}{B(\beta)\Gamma(\beta)} \int_0^t \Big(g(\tau,u_1(\tau))(t-\tau)^{\beta-1} - g(\tau,u_2(\tau))(t-\tau)^{\beta-1} \Big) d\tau \bigg| \\ &\leq \frac{1-\beta}{B(\beta)} L \|u_1 - u_2\| + \frac{\beta}{B(\beta)\Gamma(\beta)} L \|u_1 - u_2\| \left| \int_0^t \ (t-\tau)^{\beta-1} d\tau \right| \\ &= \frac{1-\beta}{B(\beta)} L \|u_1 - u_2\| + \frac{\beta}{B(\beta)\Gamma(\beta)} L \|u_1 - u_2\| \frac{t^\beta}{\beta} \\ &\leq \frac{(1-\beta)\Gamma(\beta) + t^\beta}{\Gamma(\beta)B(\beta)} L \|u_1 - u_2\| \end{split}$$

Since $\frac{(1-\beta)\Gamma(\beta)+t^{\beta}}{\Gamma(\beta)B(\beta)}L < 1$, therefore T is contraction and according to Banach fixed point theorem, T has a unique fixed point. \Box

Now we apply theorem 3.1 and theorem 3.2 to fractional Navier-stokes equation (3). If we replace g(t,u(t)) of equation (10) with $-\frac{1}{\rho}\frac{\partial \mathbf{p}}{\partial z} + \nu \left[\frac{\partial^2 \mathbf{u}}{\partial r^2} + \frac{1}{r}\frac{\partial \mathbf{u}}{\partial r}\right]$ of the fractional Navier-stokes equation (3) and also the initial condition $u(0) = u_0$ replaced with $\mathbf{u}(r,0) = g(r)$, then according to theorem 3.1 and 3.2 the fractional Navier-stokes equation (3) with its initial condition has a unique solution in $H^1(0,1)$.

Remark 3.1. [13] For $0 < \beta < 1$, and $B(\beta) = 1$, we have

$$\frac{(1-\beta)\Gamma(\beta)+1}{\Gamma(\beta)B(\beta)} = 1 - \beta + \frac{1}{\Gamma(\beta)} \le 1 - \beta + 1 = 2 - \beta \le 2$$

Thus, if u is Lipschitz function with Lipschitz constant $L < \frac{1}{2}$, therefore the fractional initial value problem (10) has a unique solution in $H^1(0,1)$, for all $0 < \beta < 1$.

4. Analysis of the Fractional Navier-Stokes Equation with ABCFD

In this section, we consider the Navier-Stokes equation for the one-dimensional motion of a viscous fluid in a tube with an unsteady flow. We solve the fractional Navier-stokes equation applied to the ABCFD using the iterative Laplace transform method (ILTM).

Consider the following Navier-stokes equation in cylindrical coordinates

$$\frac{\partial \mathbf{u}}{\partial t} = -\frac{1}{\rho} \frac{\partial \mathbf{p}}{\partial z} + \nu \left[\frac{\partial^2 \mathbf{u}}{\partial r^2} + \frac{1}{r} \frac{\partial \mathbf{u}}{\partial r} \right] \tag{13}$$

subject to the following initial condition

$$\mathbf{u}(r,0) = g(r) \tag{14}$$

If we apply the fractional derivative of order β in Equation (13) at the extant time derivative term, we obtain:

$$\frac{\partial^{\beta} \mathbf{u}}{\partial t^{\beta}} = -\frac{1}{\rho} \frac{\partial \mathbf{p}}{\partial z} + \nu \left[\frac{\partial^{2} \mathbf{u}}{\partial r^{2}} + \frac{1}{r} \frac{\partial \mathbf{u}}{\partial r} \right] \quad 0 < \beta \le 1$$
 (15)

We can write Equation (15) in terms of the Atangana-Baleanu fractional derivative in the Caputo sense as follows:

$$^{ABCFD}D_t^{\beta}\mathbf{u} = \mathbf{P} + \nu \left[\frac{\partial^2 \mathbf{u}}{\partial r^2} + \frac{1}{r} \frac{\partial \mathbf{u}}{\partial r} \right] \quad 0 < \beta \le 1$$
 (16)

where $\mathbf{P} = -\frac{1}{\rho} \frac{\partial \mathbf{p}}{\partial z}$

Applying the Laplace transform (7) on both sides of Equation (16) and use the initial condition (14), we get

$$\mathcal{L}\left[A^{BCFD}D_t^{\beta}\mathbf{u}\right] = \mathcal{L}[\mathbf{P}] + \mathcal{L}\left[\nu\left[\frac{\partial^2\mathbf{u}}{\partial r^2} + \frac{1}{r}\frac{\partial\mathbf{u}}{\partial r}\right]\right]$$
(17)

$$\frac{B(\beta)}{1-\beta} \frac{s^{\beta} \mathcal{L}[\mathbf{u}(r,t)](s) - s^{\beta-1} u(r,0)}{s^{\beta} + \frac{\beta}{1-\beta}} = \mathcal{L}[\mathbf{P}] + \mathcal{L}\left[\nu \left[\frac{\partial^{2} \mathbf{u}}{\partial r^{2}} + \frac{1}{r} \frac{\partial \mathbf{u}}{\partial r}\right]\right]$$
(18)

$$\mathcal{L}[\mathbf{u}(r,t)] = \frac{g(r)}{s} + \left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)s^{\beta}} \right] \mathcal{L}[\mathbf{P}] + \left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)s^{\beta}} \right] \mathcal{L} \left[\nu \left[\frac{\partial^{2} \mathbf{u}}{\partial r^{2}} + \frac{1}{r} \frac{\partial \mathbf{u}}{\partial r} \right] \right]$$
(19)

Applying the inverse Laplace transform on both sides of Equation (19), we get

$$\mathbf{u}(r,t) = \mathbf{G}(r,t) + \mathcal{L}^{-1} \left[\left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)s^{\beta}} \right] \mathcal{L} \left[\nu \left[\frac{\partial^{2} \mathbf{u}}{\partial r^{2}} + \frac{1}{r} \frac{\partial \mathbf{u}}{\partial r} \right] \right] \right]$$
(20)

where $\mathbf{G}(r,t) = g(r) + \left[\frac{(1-\beta)}{B(\beta)} + \frac{t^{\beta}}{B(\beta)\Gamma(\beta)}\right] \mathbf{P}$.

The term $\mathbf{G}(r,t)$ represents the term arising from the source term and the given initial conditions. Then if we apply the iterative method, we obtain the solution as an infinite series:

$$\mathbf{u}(r,t) = \sum_{k=0}^{\infty} \mathbf{u}_k(r,t)$$
 (21)

substituting (21) in (20), we obtain:

$$\sum_{k=0}^{\infty} \mathbf{u}_{k}(r,t) = \mathbf{G}(r,t) + \mathcal{L}^{-1} \left[\left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)s^{\beta}} \right] \mathcal{L} \left[\nu \left[\frac{\partial^{2}}{\partial r^{2}} \sum_{k=0}^{\infty} \mathbf{u}_{k}(r,t) + \frac{1}{r} \frac{\partial}{\partial r} \sum_{k=0}^{\infty} \mathbf{u}_{k}(r,t) \right] \right] \right]$$
(22)

Comparing the coefficients of $\mathbf{u}_k(r,t)$, we get:

$$\mathbf{u}_0(r,t) = \mathbf{G}(r,t) \, k = 0,1,2,3,4,\dots \dots$$
 (23)

$$\mathbf{u}_{1}(r,t) = \mathcal{L}^{-1} \left[\left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)s^{\beta}} \right] \mathcal{L} \left[\nu \left[\frac{\partial^{2} \mathbf{u}_{0}}{\partial r^{2}} + \frac{1}{r} \frac{\partial \mathbf{u}_{0}}{\partial r} \right] \right]$$
(24)

$$\mathbf{u}_{2}(r,t) = \mathcal{L}^{-1} \left[\left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)s^{\beta}} \right] \mathcal{L} \left[\nu \left[\frac{\partial^{2} \mathbf{u}_{1}}{\partial r^{2}} + \frac{1}{r} \frac{\partial \mathbf{u}_{1}}{\partial r} \right] \right]$$
(25)

$$\mathbf{u}_{3}(r,t) = \mathcal{L}^{-1} \left[\left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)s^{\beta}} \right] \mathcal{L} \left[\nu \left[\frac{\partial^{2} \mathbf{u}_{2}}{\partial r^{2}} + \frac{1}{r} \frac{\partial \mathbf{u}_{2}}{\partial r} \right] \right]$$
 (26)

$$\mathbf{u}_{4}(r,t) = \mathcal{L}^{-1} \left[\left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)s^{\beta}} \right] \mathcal{L} \left[\nu \left[\frac{\partial^{2} \mathbf{u}_{3}}{\partial r^{2}} + \frac{1}{r} \frac{\partial \mathbf{u}_{3}}{\partial r} \right] \right]$$
(27)

Thus, series solution of (16)

$$\mathbf{u}(r,t) = \sum_{k=0}^{\infty} \mathbf{u}_k(r,t)$$
 (28)

4.1. Numerical Examples

We provide some numerical examples to demonstrate the proficiency and correctness of our solution of the Atangana-Baleanu fractional Navier-Stokes equation in Caputo sense utilizing the iterative Laplace transform method (ILTM) and iterative Sumudu transform method (ISTM).

Example 4.1. The time-fractional Navier-Stokes equation concerning the ABCFD with $\nu = 1$ is given as:

$${}^{ABCFD}D_t^{\beta}\mathbf{u} = \mathbf{P} + \frac{\partial^2 \mathbf{u}}{\partial r^2} + \frac{1}{r}\frac{\partial \mathbf{u}}{\partial r} \qquad 0 < \beta \le 1$$
 (29)

subject to the following initial condition

$$\mathbf{u}(r,0) = 1 - r^2$$

Applying the Laplace transform (7) on both sides of Equation (29) and using the above initial condition we obtain:

$$\mathcal{L}[\mathbf{u}(r,t)] = \frac{1-r^2}{s} + \left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)s^{\beta}}\right] \mathcal{L}[\mathbf{P}] + \left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)s^{\beta}}\right] \mathcal{L}\left[\frac{\partial^2 \mathbf{u}}{\partial r^2} + \frac{1}{r}\frac{\partial \mathbf{u}}{\partial r}\right]$$
(30)

Applying the Laplace inverse on both sides of Equation (30), we get

$$\mathbf{u}(r,t) = \mathcal{G}(r,t) + \mathcal{L}^{-1} \left[\left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)s^{\beta}} \right] \mathcal{L} \left[\frac{\partial^{2} \mathbf{u}}{\partial r^{2}} + \frac{1}{r} \frac{\partial \mathbf{u}}{\partial r} \right] \right]$$
(31)

where $\mathbf{G}(r,t) = 1 - r^2 + \left[\frac{(1-\beta)}{B(\beta)} + \frac{t^{\beta}}{B(\beta)\Gamma(\beta)}\right] \mathbf{P}$

$$\mathbf{u}(r,t) = \sum_{k=0}^{\infty} \mathbf{u}_k(r,t)$$
 (32)

Applying the iterative method coupled with the Laplace transform, we obtain:

$$\sum_{k=0}^{\infty} \mathbf{u}_{k}(r,t) = \mathbf{G}(r,t) + \mathcal{L}^{-1} \left[\left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)s^{\beta}} \right] \mathcal{L} \left[\frac{\partial^{2}}{\partial r^{2}} \sum_{k=0}^{\infty} \mathbf{u}_{k}(r,t) + \frac{1}{r} \frac{\partial}{\partial r} \sum_{k=0}^{\infty} \mathbf{u}_{k}(r,t) \right] \right]$$
(33)

Comparing the coefficients of $\mathbf{u}_k(r,t)$, we get:

$$\begin{split} \mathbf{u}_0(r,t) &= 1 - r^2 + \left[\frac{(1-\beta)}{B(\beta)} + \frac{t^\beta}{B(\beta)\Gamma(\beta)}\right] \mathbf{P} \qquad k = 0,1,2,3,4,\dots\dots, \\ \mathbf{u}_1(r,t) &= \mathcal{L}^{-1} \left[\left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)s^\beta}\right] \mathcal{L} \left[\frac{\partial^2 \mathbf{u}_0}{\partial r^2} + \frac{1}{r} \frac{\partial \mathbf{u}_0}{\partial r}\right] \right], \\ &= (-4) \left[\frac{(1-\beta)}{B(\beta)} + \frac{t^\beta}{B(\beta)\Gamma(\beta)}\right]. \\ \mathbf{u}_2(r,t) &= \mathcal{L}^{-1} \left[\left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)s^\beta}\right] \mathcal{L} \left[\frac{\partial^2 \mathbf{u}_1}{\partial r^2} + \frac{1}{r} \frac{\partial \mathbf{u}_1}{\partial r}\right] \right], \\ &= (0) \left[\frac{(1-\beta)}{B(\beta)} + \frac{t^\beta}{B(\beta)\Gamma(\beta)}\right]. \end{split}$$

so that

 $\mathbf{u}_k(r,t) = 0$, for all $k \ge 2$.

The series solution of Equation (29) is as follows:

$$\mathbf{u}(r,t) = \sum_{k=0}^{\infty} \mathbf{u}_k(r,t)$$
 (34)

$$\mathbf{u}(r,t) = 1 - r^2 + (\mathbf{P} - 4) \left[\frac{(1-\beta)}{B(\beta)} + \frac{t^{\beta}}{B(\beta)\Gamma(\beta)} \right]$$
(35)

and we see that with only the third order term, we obtain the exact solution, and if we let $\beta = 1$ we obtain the classical solution of the normal Navier-Stokes equation as

$$\mathbf{u}(r,t) = 1 - r^2 + (\mathbf{P} - 4)t \tag{36}$$

Figure 1 illustrates the graphical representation for the solution of Equation (29), for P = 1 when (a) $\beta = 0.3$, (b) $\beta = 0.5$, (c) $\beta = 0.8$ and (d) $\beta = 1$.

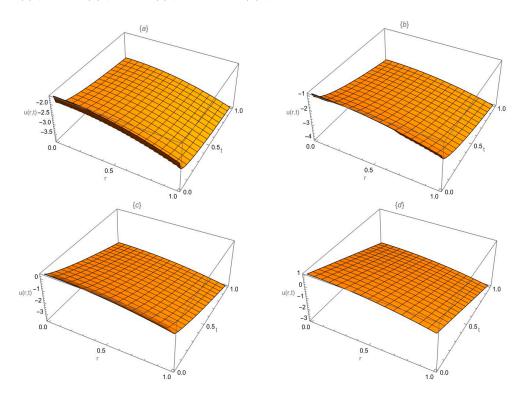


Figure 1. Exact solution of Equation (29) with the initial condition $\mathbf{u}(r,0) = 1 - r^2$ for $\beta = 0.3,0.5,0.8$ and 1.

Figure 2 illustrates the graphical representation for the solution of Equation (29), for P = 1 and t = 1 when $\beta = 0.5$, $\beta = 0.8$ and $\beta = 1$.

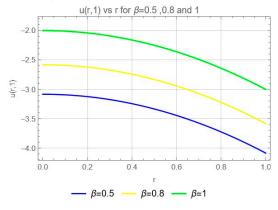


Figure 2. Solution of Equation (29) when t = 1 for $\beta = 0.5,0.8$ and 1.

Figure 3 illustrates the graphical representation for the solution of Equation (29), for P = 1 and r = 1 when $\beta = 0.5$, $\beta = 0.8$ and $\beta = 1$.

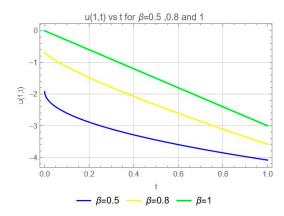


Figure 3. Solution of Equation (29) when r = 1 for $\beta = 0.5, 0.8$ and 1.

From the numerical results illustrated in Figures 1–3, is simple to conclude that the solution is continuously dependent on the time-fractional derivative.

Example **4.2**. Now we illustrate how to find the solution of Equation (29): (Example 4.1) subject to the same initial condition: $\mathbf{u}(r,0) = 1 - r^2$ via the iterative Sumudu transform method (ISTM).

Applying the Sumudu transform (8) on both sides of Equation (29) and using its initial condition, we obtain:

$$S[\mathbf{u}(r,t)] = S[1-r^2] + \left[\frac{1-\beta(1-s^{\beta})}{B(\beta)}\right]S[\mathbf{P}] + \left[\frac{1-\beta(1-s^{\beta})}{B(\beta)}\right]S\left[\frac{\partial^2 \mathbf{u}}{\partial r^2} + \frac{1}{r}\frac{\partial \mathbf{u}}{\partial r}\right]$$
(37)

where S is the Sumudu transform.

Applying the Sumudu inverse on both sides of Equation (37), we get

$$\mathbf{u}(r,t) = \mathbf{G}(r,t) + \mathcal{S}^{-1} \left[\left[\frac{1 - \beta(1 - s^{\beta})}{B(\beta)} \right] \mathcal{S} \left[\frac{\partial^{2} \mathbf{u}}{\partial r^{2}} + \frac{1}{r} \frac{\partial \mathbf{u}}{\partial r} \right] \right]$$
(38)

where
$$\mathbf{G}(r,t) = 1 - r^2 + \left[\frac{1 - \beta \left[1 - \left[\frac{t^{\beta}}{\Gamma(\beta+1)}\right]\right]}{B(\beta)}\right] \mathbf{P}$$

$$\mathbf{u}(r,t) = \sum_{k=0}^{\infty} \mathbf{u}_k(r,t)$$
 (39)

Applying the iterative method coupled with the Sumudu transform, we obtain:

$$\sum_{k=0}^{\infty} \mathbf{u}_{k}(r,t) = \mathbf{G}(r,t) + \mathcal{S}^{-1} \left[\left[\frac{1 - \beta \left(1 - s^{\beta} \right)}{B(\beta)} \right] \mathcal{S} \left[\frac{\partial^{2}}{\partial r^{2}} \sum_{k=0}^{\infty} \mathbf{u}_{k}(r,t) + \frac{1}{r} \frac{\partial}{\partial r} \sum_{k=0}^{\infty} \mathbf{u}_{k}(r,t) \right] \right]$$
(40)

Comparing the coefficients of $\mathbf{u}_k(r,t)$, we get:

$$\begin{split} \mathbf{u}_0(r,t) &= 1 - r^2 + \left[\frac{1 - \beta \left[1 - \left[\frac{t^\beta}{\Gamma(\beta+1)} \right] \right]}{B(\beta)} \right] \mathbf{P} \qquad k = 0,1,2,3,4, \dots \dots \dots \\ \mathbf{u}_1(r,t) &= \mathcal{S}^{-1} \left[\left[\frac{1 - \beta \left(1 - s^\beta \right)}{B(\beta)} \right] \mathcal{S} \left[\frac{\partial^2 \mathbf{u}_0}{\partial r^2} + \frac{1}{r} \frac{\partial \mathbf{u}_0}{\partial r} \right] \right] \\ &= -4 \left[\frac{1 - \beta \left[1 - \left[\frac{t^\beta}{\Gamma(\beta+1)} \right] \right]}{B(\beta)} \right] \\ \mathbf{u}_2(r,t) &= \mathcal{S}^{-1} \left[\left[\frac{1 - \beta \left(1 - s^\beta \right)}{B(\beta)} \right] \mathcal{S} \left[\frac{\partial^2 \mathbf{u}_1}{\partial r^2} + \frac{1}{r} \frac{\partial \mathbf{u}_1}{\partial r} \right] \right] \\ &= (0) \left[\frac{1 - \beta \left[1 - \left[\frac{t^\beta}{\Gamma(\beta+1)} \right] \right]}{B(\beta)} \right] \end{split}$$

so that

 $\mathbf{u}_k(r,t) = 0$, for all $k \ge 2$.

The series solution of Equation (29) is as:

$$\mathbf{u}(r,t) = \sum_{k=0}^{\infty} \mathbf{u}_k(r,t)$$
 (41)

$$\mathbf{u}(r,t) = 1 - r^2 + (\mathbf{P} - 4) \left[\frac{1 - \beta \left[1 - \left[\frac{t^{\beta}}{\Gamma(\beta + 1)} \right] \right]}{B(\beta)} \right]$$
(42)

Then if $\beta = 1$ we obtain the same classical solution of example 4.1.

Example **4.3.** Consider the following time-fractional Navier-Stokes equation with respect to the ABCFD

$$^{ABCFD}D_{t}^{\beta}\mathbf{u} = \frac{\partial^{2}\mathbf{u}}{\partial r^{2}} + \frac{1}{r}\frac{\partial\mathbf{u}}{\partial r} \qquad 0 < \beta \le 1$$

$$\tag{43}$$

subject to the following initial condition

$$\mathbf{u}(r,0) = r$$

Applying the Laplace transform (7) on both sides of Equation (43) and using the above initial condition we obtain:

$$\mathcal{L}[\mathbf{u}(r,t)] = \frac{r}{s} + \left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)s^{\beta}}\right] \mathcal{L}\left[\frac{\partial^{2}\mathbf{u}}{\partial r^{2}} + \frac{1}{r}\frac{\partial\mathbf{u}}{\partial r}\right]$$
(44)

Applying the Laplace inverse on both sides of Equation (44), we get

$$\mathbf{u}(r,t) = \mathcal{G}(r,t) + \mathcal{L}^{-1} \left[\left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)s^{\beta}} \right] \mathcal{L} \left[\frac{\partial^{2} \mathbf{u}}{\partial r^{2}} + \frac{1}{r} \frac{\partial \mathbf{u}}{\partial r} \right] \right]$$
(45)

where $\mathbf{G}(r,t) = r$

$$\mathbf{u}(r,t) = \sum_{k=0}^{\infty} \mathbf{u}_k(r,t)$$
 (46)

Applying the iterative method combined with the Laplace transform, we obtain:

$$\sum_{k=0}^{\infty} \mathbf{u}_{k}(r,t) = r + \mathcal{L}^{-1} \left[\left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)s^{\beta}} \right] \mathcal{L} \left[\frac{\partial^{2}}{\partial r^{2}} \sum_{k=0}^{\infty} \mathbf{u}_{k}(r,t) + \frac{1}{r} \frac{\partial}{\partial r} \sum_{k=0}^{\infty} \mathbf{u}_{k}(r,t) \right] \right]$$
(47)

Comparing the coefficients of $\mathbf{u}_k(r,t)$, we get:

$$\begin{aligned} \mathbf{u}_{0}(r,t) &= r & k = 0,1,2,3,4,\dots, \\ \mathbf{u}_{1}(r,t) &= \mathcal{L}^{-1} \left[\left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)s^{\beta}} \right] \mathcal{L} \left[\frac{\partial^{2} \mathbf{u}_{0}}{\partial r^{2}} + \frac{1}{r} \frac{\partial \mathbf{u}_{0}}{\partial r} \right] \right] \\ &= \left(\frac{1}{r} \right) \left[\frac{(1-\beta)}{B(\beta)} + \frac{t^{\beta}}{B(\beta)\Gamma(\beta)} \right], \\ \mathbf{u}_{2}(r,t) &= \mathcal{L}^{-1} \left[\left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)s^{\beta}} \right] \mathcal{L} \left[\frac{\partial^{2} \mathbf{u}_{1}}{\partial r^{2}} + \frac{1}{r} \frac{\partial \mathbf{u}_{1}}{\partial r} \right] \right] \\ &= \left(\frac{1}{r^{3}} \right) \left[\frac{(1-\beta)}{B(\beta)} + \frac{t^{\beta}}{B(\beta)\Gamma(\beta)} \right]^{2}, \\ \mathbf{u}_{3}(r,t) &= \mathcal{L}^{-1} \left[\left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta}{B(\beta)S^{\beta}} \right] \mathcal{L} \left[\frac{\partial^{2} \mathbf{u}_{2}}{\partial r^{2}} + \frac{1}{r} \frac{\partial \mathbf{u}_{2}}{\partial r} \right] \right] \\ &= \left(\frac{9}{r^{5}} \right) \left[\frac{(1-\beta)}{B(\beta)} + \frac{t^{\beta}}{B(\beta)S^{\beta}} \right] \mathcal{L} \left[\frac{\partial^{2} \mathbf{u}_{3}}{\partial r^{2}} + \frac{1}{r} \frac{\partial \mathbf{u}_{3}}{\partial r} \right] \right] \\ &= \left(\frac{225}{r^{7}} \right) \left[\frac{(1-\beta)}{B(\beta)} + \frac{t^{\beta}}{B(\beta)\Gamma(\beta)} \right]^{4}, \end{aligned}$$

so that

The series solution of Equation (43) is as:

$$\mathbf{u}(r,t) = r + \sum_{k=0}^{\infty} \frac{1^2 \times 3^2 \times \dots \times (2k-3)^2}{r^{2k-1}} \left[\frac{(1-\beta)}{B(\beta)} + \frac{t^{\beta}}{B(\beta)\Gamma(\beta)} \right]^k$$
(48)

If we use the gamma function property $\Gamma(\beta) = \frac{\Gamma(\beta+1)}{\beta}$, then we can write (48) as

$$\mathbf{u}(r,t) = r + \sum_{k=0}^{\infty} \frac{1^2 \times 3^2 \times \dots \times (2k-3)^2}{r^{2k-1}} \left[\frac{(1-\beta)}{B(\beta)} + \frac{\beta t^{\beta}}{B(\beta)\Gamma(\beta+1)} \right]^k$$
(49)

For $\beta = 1$ we obtain the following solution

$$\mathbf{u}(r,t) = r + \sum_{k=0}^{\infty} \frac{1^2 \times 3^2 \times \dots \times (2k-3)^2}{r^{2k-1}} \frac{t^k}{k!}$$
 (50)

which gives similar results obtained in [2-4].

The approximate solution for Equation (43), when k = 4 is given by $\mathbf{u}(r,t) = \mathbf{u}_0(r,t) + \mathbf{u}_1(r,t) + \mathbf{u}_2(r,t) + \mathbf{u}_3(r,t) + \mathbf{u}_4(r,t)$ and the graphical representation is provided in Figure 4.

Figure 4 illustrates the graphical representation for the solution of Equation (43), when k = 4 and (a) $\beta = 0.3$, (b) $\beta = 0.5$, (c) $\beta = 0.8$ and (d) $\beta = 1$.

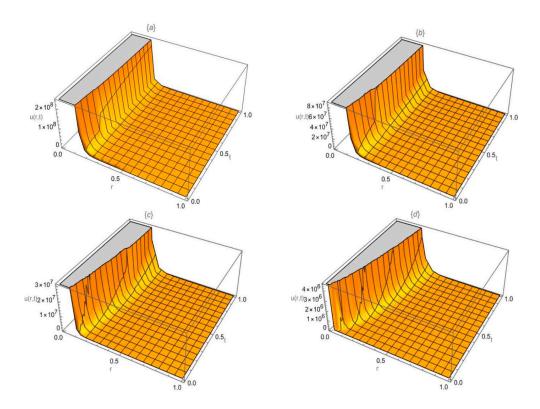


Figure 4. Approximate solution of Equation (43) with the initial condition $\mathbf{u}(r,0) = r$ for $\beta = 0.3, 0.5, 0.8$ and 1.

Remark 4.1. If we consider the Navier Stokes equation in example 4.1 with the viscosity $(\nu) = 0$, then the fractional Navier Stokes equation (29) will reduce to the Euler's equation of the incompressible and frictionless fluid of the form

$$^{ABCFD}D_t^{\beta}\mathbf{u} = \mathbf{P} \quad 0 < \beta \le 1 \tag{}$$

subject to the initial condition

$$\mathbf{u}(r,0) = r \tag{}$$

so that according to example 4.1 and 4.2, G(r,t) is the exact solution of the Euler's equation, if v = 0.

6. Conclusions

In this paper, the iterative method was utilized to solve time-fractional Navier-Stokes equations applied to a one-dimensional problem of unsteady flow of a viscous fluid in a tube along with the initial conditions. The fractional derivative was specified in terms of the Atangana-Baleanu Caputo sense. The method was coupled with the Laplace and Sumudu transform to assist with getting the exact and approximate solutions. The analytical results have been provided in terms of a power series with simple computable terms and it is observed that the solution found by this method rapidly converges to the exact solution. The results demonstrate that the solution continuously depends on the time-fractional derivative. We also provided the graphical representation of the solutions using Mathematica software. Finally, the iterative method coupled with the Laplace or Sumudu is a very powerful and efficient technique to be used to obtain analytical solutions for various types of fractional linear, nonlinear and partial differential equations and we hope that our work is heading in the right direction in term of solving the problems involving such equations.

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Abbreviations

The following abbreviations are used in this manuscript:

ABCDF Atangana-Baleanu Caputo fractional. Derivatives ABFI Atangana-Baleanu fractional integral. IM Iterative method.
MLF Mittag-Leffler function.
N-S Navier-Stockes.

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