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Article

About The Calculus by Transfer-Matrix Method of a Beam with Intermediate Support with Applications in Dental Restorations

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Abstract: This work presents a new, original and very interesting approach to a calculus problem of beams with intermediate supports by Transfer-Matrix Method, a very easy method to program to quickly obtain good results. To exemplify the applicability of this approach is given in dentistry, the calculus of a dental bridge on three poles. The dental restorations are very important for improving the general state of health as a result of improving mastication and aesthetic appearance. The approach of this study consists of to present a theoretical study about an indeterminate beam with intermediate support and after, to particularize for an application of a dental restoration case, with a dental bridge on three poles and with two missing teeth between the three poles, assimilated to a simple static indeterminate beam. The results obtained in the presented case study were validated with those obtained by the classical calculation of the Resistance of Materials, with the equation of the three moments of Clapeyron. Due to the ease and elegance of solving various problems with TMM, their approach will continue with other new and original case studies with different modeling and requests, and they will be presented in future research.

Keywords: beam with intermediate support; Transfer-Matrix Method; charge density; Dirac's function and operators; Heaviside's function and operators; dental restoration; dental bridge; dental crown

MSC: 74-10

1. Introduction

Interdisciplinary studies and research in many fields are very topical. This work presents a new, original and very interesting approach to a calculus problem of beams with intermediate supports by Transfer-Matrix Method (TMM), a very easy method to program to quickly obtain good results. To exemplify the applicability of this approach is given in dentistry, the calculus of a dental bridge on three poles. The dental restorations are very important for improving the general state of health as a result of improving mastication and aesthetic appearance. The approach of this study consists of to present a theoretical study about an indeterminate beam with intermediate support and after, to particularize for an application of a dental restoration case, with a dental bridge on three poles and with two missing teeth between the three poles, assimilated to a simple static indeterminate beam, resting on three supports - the three poles and with two openings, corresponding to the two missing teeth. The results obtained in the presented case study were validated with those obtained by the

classical calculation of the Resistance of Materials, with the equation of the three moments of Clapeyron.

TMM is a method used in many fields as will be presented below.

Structure calculus with TMM is presented in [1] and the classical analytical calculus for beams with different applications is given in [2] and [3]. Using the TMM we can calculate different pieces as in [4] and [10]. The TMM is used in orthodontics and are presented in [8] and [17]. For the dental restauration are more papers: for dental bridges with TMM as [12–16,18] and for dental implants as [11] and [15]. They will be taken as starting studies [5–7] and [9]. A histopathological study about osseointegration of zirconium dental implants three months after insertion in rabbit femur is presented in [19]. An essential guide to oral pathology is [20,26] is a guide to the diagnosis and treatment of conditions in the field of oral pathology and [25] presents notions on dental preparations for fixed uni-dental prostheses. [21] give us an in-vitro comparative study about the marginal adaptation assessment for two composite layering techniques using dye penetration, AFM, SEM and FTIR and [24] presents an in-vitro comparative adhesion evaluation of bio-ceramic and dual-cure resin endodontic sealers using SEM, AFM, Push-Out and FTIR. [22] presents a comparative apical sealing evaluation of two bio-ceramic endodontic sealers. [23] we have an oral health-related knowledge about the attitude and practice among patients in rural areas around Cluj-Napoca, Romania. [30] give us a study for ten-year survival of bridges placed in the General Dental Services in England and Wales. [27] presents coronary reconstructions and [28] gives a case report about enamel-lopasty in interdisciplinary treatment of dental injuries. [29] shows figures of graph partitioning by counting, sequence and layer matrices. [31] and [32] presents studies about bending fracture of Co-Cr dental bridges. [33] shows an integrated construction and simulation of tool paths for milling dental crowns and bridges. [34] and [35] gives studies about the influence of fatigue of zirconia for dental bridge design. Research on the surface of the dental alloys with cobalt-crom base is presented in [36]. Effects of small grit grinding and glazing on mechanical behaviors and ageing resistance of a super translucent dental zirconia show in [37]. Other new and original case studies with different modeling and requests will be presented in the future through TMM.

2. Materials and Methods

2.1. Materials

Dental restorations for missing one or two teeth can be done by dental crowns or dental bridges on one, two or more pivots or abutments, depending on what the dentist found to exist in situ, following a specialist consultation.

Dental crowns can be made of the following materials: full zirconia, stratified zirconia - i.e. zircon and ceramic, metal and ceramic - i.e. with a metal base and a ceramic coating, or composite - used especially during prosthetic treatment as a temporary crown. Dental crowns can also be fixed on implants, which must be made of biocompatible materials.

The most suitable biocompatible materials for implants are titanium, zirconium and ceramic, materials resistant to pressure and daily wear and, at the same time, have a pleasant aesthetic appearance.

Dental bridges can be fixed or mobile. They can be semi-physiognomic or totally physiognomic. Fixed bridges can be made entirely of zirconium, ceramic, acrylic or metallic materials. Removable dentures can be made of metal - for additional structural support or acrylic resins, which can incorporate ceramic - for better aesthetics.

2.2. Methods

Some beams with intermediate support can be studied as statically indeterminate continuous beams. It is considered as a statically indeterminate continuous beam, articulate at the left edge, with simple support at the right edge and with intermediate supports, as in Figure 1. The calculus is done with TMM.

2.2.1. Work Hypotheses

The beam with intermediate support that will be studied is considered as a statically indeterminate continuous beam, articulate at the left edge, with a simple support at the right edge and with i ($i=1, n-1$) intermediate simple supports (Figure 1).

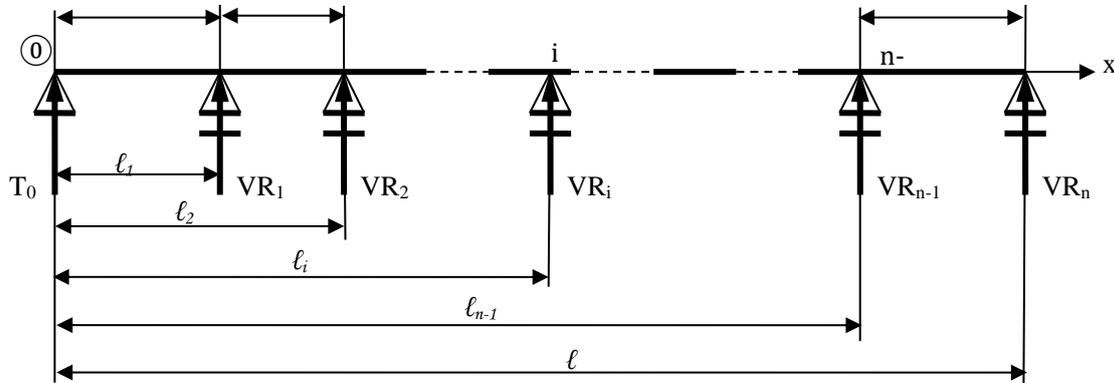


Figure 1. Beam with i ($i=1, n-1$) intermediate supports.

The lengths of all parts of the beam are known.

The constant inertia of the entire beam is also considered.

It is considered a reference system with the origin in the left edge, the edge 0.

External vertical forces are considered to act on the beam, which can be characterized by a charge density $q'(x)$ for the vertical concentrated loads and $q''(x)$ is the charge density for the force uniformly distributed over the entire beam.

Due to the external forces, unknown vertical reactions arise at each edge, that are $(n+1)$ vertical reactions. Further, these reactions will be considered as external forces with the charge density as $q'''(x)$.

2.2.2. Total Charge of Density for a Continuous Beam

It is considered as a statically indeterminate continuous beam, articulate at the left edge, with a simple support at the right edge and with n intermediate supports (Figure 1).

Thus, the total charge density $q(x)$ can be written as (1):

$$q(x) = q'(x) + q''(x) + q'''(x), \quad (1)$$

where:

- $q(x)$ is the total charge density;
- $q'(x)$ is the charge density for the exterior vertical concentrated loads;
- $q''(x)$ is the charge density for the force uniformly distributed over the entire beam;
- $q'''(x)$ is the density of charge corresponding of the vertical reaction in the edges.
- The density of charge corresponding of the exterior concentrated loads $q'(x)$, for a number j of exterior loads F_j , $j=1, k$, acting in the point a_j , $j=1, k$, can be written, with Dirac's and Heaviside's functions and operators, as (2):

$$q'(x) = - \sum_{j=1}^k F_j \delta(x - a_j). \quad (2)$$

- The charge density for the force uniformly distributed over the entire beam $q''(x)$ can be written, with Dirac's and Heaviside's functions and operators, as (3):

$$q''(x) = -p(x)\delta(x), \quad (3)$$

- and the density of charge corresponding for the Vertical Reaction, ($VR_i, i=0, n$) in the edges, $q''(x)$, with Dirac's and Heaviside's functions and operators too, can be written as (4):

$$q''(x) = \sum_{i=0}^n VR_i \delta(x - l_i), \quad (4)$$

when:

- j refers to the point where act the concentrated vertical force F_j ;
- $F_j, j=1, k$, are the exterior vertical concentrated loads;
- k is the total number of the concentrated vertical force;
- i refers to the edge with number i ;
- $n+1$ is the total number of edges;
- $p(x)$ is the force uniformly distributed over the entire beam;
- VR_i is the Vertical Reaction in the edge i .

Applying the mathematical calculus with Dirac's and Heaviside's functions and operators for (2), we can obtain successively the relations (5):

$$\begin{cases} q'_1(x) = -\sum_{j=1}^k F_j Y(x - a_j) \\ q'_2(x) = -\sum_{j=1}^k F_j (x - a_j) Y(x - a_j) \\ q'_3(x) = -\sum_{j=1}^k F_j \frac{(x - a_j)^2}{2} Y(x - a_j) \\ q'_4(x) = -\sum_{j=1}^k F_j \frac{(x - a_j)^3}{6} Y(x - a_j) \end{cases}, \quad (5)$$

In the same way, the mathematical formalism will be applied to expressions (1) and relations (6) are obtained:

$$\begin{cases} q_1(x) = -\sum_{j=1}^k F_j Y(x - a_j) - p(x)xY(x) + \sum_{i=1}^n VR_i Y(x - l_i) \\ q_2(x) = -\sum_{j=1}^k F_j (x - a_j) Y(x - a_j) - p(x) \frac{x^2}{2} Y(x) + \sum_{i=1}^n VR_i (x - l_i) Y(x - l_i) \\ q_3(x) = -\sum_{j=1}^k F_j \frac{(x - a_j)^2}{2} Y(x - a_j) - p(x) \frac{x^3}{6} Y(x) + \sum_{i=1}^n VR_i \frac{(x - l_i)^2}{2} Y(x - l_i) \\ q_4(x) = -\sum_{j=1}^k F_j \frac{(x - a_j)^3}{6} Y(x - a_j) - p(x) \frac{x^4}{24} Y(x) + \sum_{i=1}^n VR_i \frac{(x - l_i)^3}{6} Y(x - l_i) \end{cases}, \quad (6)$$

2.2.3. The State Vectors for Different Sections of the Continuous Beam

The state vectors for different sections of the continuous beam can be defined as follows.

It is noted with $\{SV(x)\}$ the State Vector corresponding at the section x , at a point on the x -axis, the abscissa measured from the origin of the reference system, which is in the left edge 0 , as (7):

$$\{SV(x)\} = \{y(x), \omega(x), M(x), T(x)\}^{-1}, \quad (7)$$

Elements of the state vector (7) are:

- $y(x)$ is the arrow in the section x ;
- $\omega(x)$ is the rotating in the section x ;
- $M(x)$ is the bending moment in the section x ;
- $T(x)$ is the cutting force in section x .

The state vector at the origin $\{SV(0)\}=\{SV\}_0$, in the section 0 is as (8):

$$\{SV(0)\} = \{y(0), \omega(0), M(0), T(0)\}^{-1} = \{SV\}_0 = \{y_0, \omega_0, M_0, T_0\}^{-1}, \quad (8)$$

The total length l of continuous beam is as (9):

$$l = \sum_{i=1}^n a_i, \quad (9)$$

when $a_i, i=1, n$ is the distance between two consecutive supports.

The state vector at the last section, in the section n , $\{SV(l)\} = \{SV\}_l$, for $x=l$, is as (10):

$$\{SV(l)\} = \{y(l), \omega(l), M(l), T(l)\}^{-1} = \{SV\}_l = \{y_l, \omega_l, M_l, T_l\}^{-1}, \quad (10)$$

2.2.4. The Transfer-Matrix for the Section x of the Continuous Beam

The connection between the state vector from the origin, the section 0 , and the state vector from some section x , is made with relation (11):

$$\begin{Bmatrix} y(x) \\ \omega(x) \\ M(x) \\ T(x) \end{Bmatrix} = [TM]_x \begin{Bmatrix} y(0) \\ \omega(0) \\ M(0) \\ T(0) \end{Bmatrix} + \{VEF(x)\}, \quad (11)$$

when:

- $[TM]_x$ is the *Transfer-Matrix* corresponding at section x ;
- $\{VEF(x)\}$ is the *Vector for Exterior Forces* at section x .

The Transfer-Matrix $[TM]_x$ is as (12), after [1]:

$$[TM]_x = \begin{bmatrix} 1 & x & \frac{x^2}{2EI} & -\frac{x^3}{6EI} \\ 0 & 1 & \frac{x}{EI} & -\frac{x^2}{2EI} \\ 0 & 0 & 1 & -x \\ 0 & 0 & 0 & 1 \end{bmatrix}, \quad (12)$$

The vector for exterior forces at the section x is as (13):

$$\{VEF(x)\} = \left\{ \begin{array}{l} -\sum_{j=1}^k F_j \frac{(x-a_j)^3}{6} Y(x-a_j) - p(x) \frac{x^4}{24} Y(x) + \sum_{i=1}^n VR_i \frac{(x-l_i)^3}{6} Y(x-l_i) \\ -\sum_{j=1}^k F_j \frac{(x-a_j)^2}{2} Y(x-a_j) - p(x) \frac{x^3}{6} Y(x) + \sum_{i=1}^n VR_i \frac{(x-l_i)^2}{2} Y(x-l_i) \\ -\sum_{j=1}^k F_j (x-a_j) Y(x-a_j) - p(x) \frac{x^2}{2} Y(x) + \sum_{i=1}^n VR_i (x-l_i) Y(x-l_i) \\ -\sum_{j=1}^k F_j Y(x-a_j) - p(x) x Y(x) + \sum_{i=1}^n VR_i Y(x-l_i) \end{array} \right\}, \quad (13)$$

The matrix relation (11) can be developed as (14):

$$\begin{Bmatrix} y(x) \\ \omega(x) \\ M(x) \\ T(x) \end{Bmatrix} = \begin{bmatrix} 1 & x & \frac{x^2}{2EI} & -\frac{x^3}{6EI} \\ 0 & 1 & \frac{x}{EI} & -\frac{x^2}{2EI} \\ 0 & 0 & 1 & -x \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{Bmatrix} y(0) \\ \omega(0) \\ M(0) \\ T(0) \end{Bmatrix} + \quad (14)$$

$$+ \left\{ \begin{array}{l} - \sum_{j=1}^k F_j \frac{(x-a_j)^3}{6} Y(x-a_j) - p(x) \frac{x^4}{24} Y(x) + \sum_{i=1}^n VR_i \frac{(x-l_j)^3}{6} Y(x-l_i) \\ - \sum_{j=1}^k F_j \frac{(x-a_j)^2}{2} Y(x-a_j) - p(x) \frac{x^3}{6} Y(x) + \sum_{i=1}^n VR_i \frac{(x-l_j)^2}{2} Y(x-l_i) \\ - \sum_{j=1}^k F_j (x-a_j) Y(x-a_j) - p(x) \frac{x^2}{2} Y(x) + \sum_{i=1}^n VR_i (x-l_i) Y(x-l_i) \\ - \sum_{j=1}^k F_j Y(x-a_j) - p(x) x Y(x) + \sum_{i=1}^n VR_i Y(x-l_i) \end{array} \right\},$$

For the last section, for $x=l$, the expression (12) can be written as (15):

$$\begin{Bmatrix} y(l) \\ \omega(l) \\ M(l) \\ T(l) \end{Bmatrix} = [TM]_l \begin{Bmatrix} y(0) \\ \omega(0) \\ M(0) \\ T(0) \end{Bmatrix} + \{VEF(l)\}, \quad (15)$$

The relation (15) with the developed Transfer-Matrix can be written as (16):

$$\begin{Bmatrix} y(l) \\ \omega(l) \\ M(l) \\ T(l) \end{Bmatrix} = \begin{bmatrix} 1 & l & \frac{l^2}{2EI} & -\frac{l^3}{6EI} \\ 0 & 1 & \frac{l}{EI} & -\frac{l^2}{2EI} \\ 0 & 0 & 1 & -l \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{Bmatrix} y(0) \\ \omega(0) \\ M(0) \\ T(0) \end{Bmatrix} + \left\{ \begin{array}{l} - \sum_{j=1}^k F_j \frac{(l-a_j)^3}{6} Y(l-a_j) - p(x) \frac{l^4}{24} + \sum_{i=1}^n VR_i \frac{(l-l_j)^3}{6} Y(l-l_i) \\ - \sum_{j=1}^k F_j \frac{(l-a_j)^2}{2} Y(l-a_j) - p(x) \frac{l^3}{6} + \sum_{i=1}^n VR_i \frac{(l-l_j)^2}{2} Y(l-l_i) \\ - \sum_{j=1}^k F_j (l-a_j) Y(l-a_j) - p(x) \frac{l^2}{2} + \sum_{i=1}^n VR_i (l-l_i) Y(l-l_i) \\ - \sum_{j=1}^k F_j Y(l-a_j) - p(x) l + \sum_{i=1}^n VR_i Y(l-l_i) \end{array} \right\}, \quad (16)$$

In matrix relation (16), the conditions on the extreme edges can be placed, in section 0, as (17):

$$\begin{cases} y_0 = 0 \\ M_0 = 0 \end{cases}, \quad (17)$$

and in section n for $x=l$, conditions are as (18):

$$\begin{cases} y(l) = 0 \\ M(l) = 0 \end{cases}, \quad (18)$$

With the conditions (17) and (18), the matrix relation (16) can be written as (19):

$$\begin{Bmatrix} 0 \\ \omega(l) \\ 0 \\ T(l) \end{Bmatrix} = \begin{bmatrix} 1 & l & \frac{l^2}{2EI} & -\frac{l^3}{6EI} \\ 0 & 1 & \frac{l}{EI} & -\frac{l^2}{2EI} \\ 0 & 0 & 1 & -l \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{Bmatrix} 0 \\ \omega_0 \\ 0 \\ T_0 \end{Bmatrix} + \quad (19)$$

$$+ \left\{ \begin{array}{l} - \sum_{j=1}^k F_j \frac{(l-a_j)^3}{6} Y(l-a_j) - p(x) \frac{l^4}{24} + \sum_{i=1}^n VR_i \frac{(l-l_j)^3}{6} Y(l-l_i) \\ - \sum_{j=1}^k F_j \frac{(l-a_j)^2}{2} Y(l-a_j) - p(x) \frac{l^3}{6} + \sum_{i=1}^n VR_i \frac{(l-l_j)^2}{2} Y(l-l_i) \\ - \sum_{j=1}^k F_j (l-a_j) Y(l-a_j) - p(x) \frac{l^2}{2} + \sum_{i=1}^n VR_i (l-l_i) Y(l-l_i) \\ - \sum_{j=1}^k F_j Y(l-a_j) - p(x)l + \sum_{i=1}^n VR_i Y(l-l_i) \end{array} \right\}$$

Also, the conditions for the arrows in each intermediate supports must be set, they must be null in each intermediate supports as (20):

$$y_i = 0, \text{ for } i = 1, n-1, \quad (20)$$

or, (21):

$$\left\{ \begin{array}{l} y_1 = 0 \Rightarrow l_1 \omega_0 - l_1^3 \frac{T_0}{6EI} = - \frac{q'_4(l_1)}{6EI} - \frac{q''_4(l_1)}{24EI} \\ y_2 = 0 \Rightarrow l_2 \omega_0 - l_2^3 \frac{T_0}{6EI} + (l_2 - l_1)^3 \frac{VR_1}{6EI} = - \frac{q'_4(l_2 - l_1)}{6EI} - \frac{q''_4(l_2 - l_1)}{24EI} \\ \dots \\ y_i = 0 \Rightarrow l_i \omega_0 - l_i^3 \frac{T_0}{6EI} + \sum_{i=1}^k (l_i - l_1)^3 \frac{VR_i}{6EI} = - \sum_{i=1}^{n-1} \frac{q'_4(l_i - l_1)}{6EI} - \sum_{i=1}^{n-1} \frac{q''_4(l_i - l_1)}{24EI} \\ \dots \\ y_{n-1} = 0 \Rightarrow l_{n-1} \omega_0 - l_{n-1}^3 \frac{T_0}{6EI} + \sum_{i=1}^{n-1} (l_i - l_1)^3 \frac{VR_i}{6EI} = - \sum_{i=1}^{n-1} \frac{q'_4(l_{n-1} - l_1)}{6EI} - \sum_{i=1}^{n-1} \frac{q''_4(l_{n-1} - l_1)}{24EI} \end{array} \right. \quad (21)$$

The conditions for the right end of the beam, for $x=l$, are (18) and

give (22):

$$\left\{ \begin{array}{l} y_n = 0 \Rightarrow l \omega_0 - l^3 \frac{T_0}{6EI} + \sum_{i=1}^n (l - l_i)^3 \frac{VR_i}{6EI} = - \frac{q'_4(l)}{6EI} - \frac{q''_4(l)}{24EI} \\ M_n = 0 \Rightarrow -lT_0 + \sum_{i=1}^n (l - l_i)^3 VR_i = -q'_2(l) - q''_2(l) \end{array} \right. \quad (22)$$

The relations (21) and (22) can be written in a matrix relation like (23), considering that ω_0 , $\frac{T_0}{6EI}$ and $\sum_{i=1}^{n-1} \frac{VR_i}{EI}$ are the unknowns:

$$\begin{bmatrix} l_1 & -l_1^3 & 0 & 0 & 0 & \dots & 0 \\ l_2 & -l_2^3 & (l_2 - l_1)^3 & 0 & 0 & \dots & 0 \\ l_3 & -l_3^3 & (l_3 - l_1)^3 & (l_3 - l_2)^3 & 0 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ l_i & -l_i^3 & (l_i - l_1)^3 & (l_i - l_2)^3 & (l_i - l_3)^3 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ l & -l^3 & (l - l_1)^3 & (l - l_2)^3 & (l - l_3)^3 & \dots & (l - l_{n-1})^3 \\ 0 & -l & l - l_1 & l - l_2 & l - l_3 & \dots & l - l_{n-1} \end{bmatrix} \begin{bmatrix} \omega_0 \\ \frac{T_0}{6EI} \\ \frac{VR_1}{6EI} \\ \vdots \\ \frac{VR_{n-2}}{6EI} \\ \frac{VR_{n-1}}{6EI} \end{bmatrix} = \begin{bmatrix} - \frac{q'_4(l_1)}{6EI} - \frac{q''_4(l_1)}{24EI} \\ - \frac{q'_4(l_2 - l_1)}{6EI} - \frac{q''_4(l_2 - l_1)}{24EI} \\ \vdots \\ - \sum_{i=1}^{n-1} \frac{q'_4(l_i - l_1)}{6EI} - \sum_{i=1}^{n-1} \frac{q''_4(l_i - l_1)}{24EI} \\ \vdots \\ - \frac{q'_4(l)}{6EI} - \frac{q''_4(l)}{24EI} \\ -q'_2(l) - q''_2(l) \end{bmatrix} \quad (23)$$

Solving the system of equations given by the matrix relation (23) leads to the calculus of all unknowns. It can be also programmed very easily, thus quickly obtaining the values of the unknowns, and then, all the efforts and deformations in any section of the beam can be calculated.

3. Application and Results

3.1. Application for a Dental Restoration Case: Dental Bridge Assimilated as a Continuous Beam with Three Poles and Two Edentulous, Edentulous Are Between the Three Pole

It is considered a case of double missing teeth, as in Figure 2.

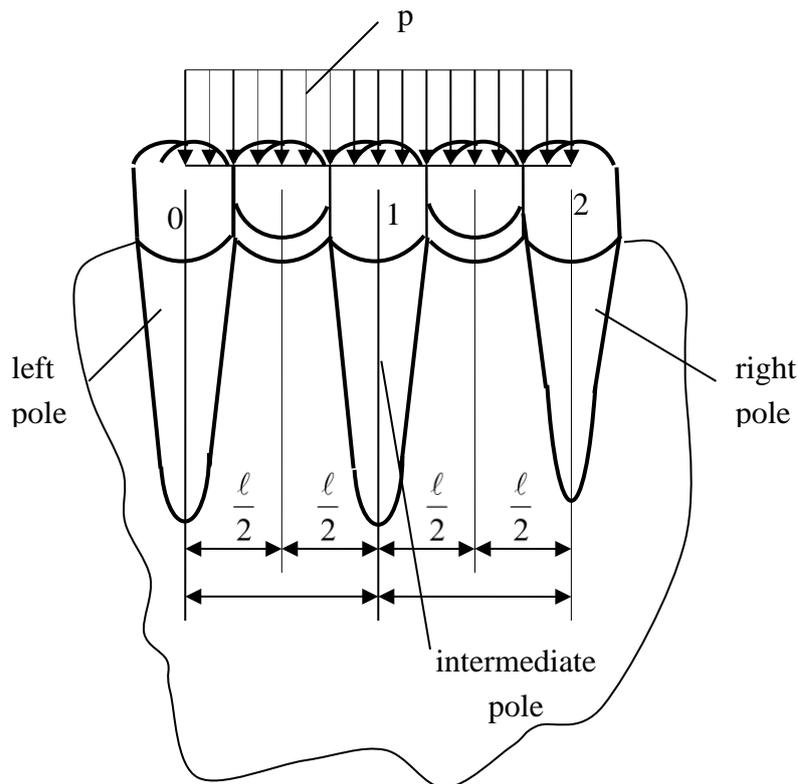


Figure 2. A dental bridge with three poles and two edentulous between the three poles.

3.1.1. Conditions of Work

A dental restoration with the following characteristics was proposed:

- the lengths of the two parts of the beam are known and are equal each other and are equal to l ;
- the constant inertia of the entire beam is also considered;
- it is considered a reference system with the origin in the left edge, the edge 0.
- the dental bridge should consist of three poles are the supports for the beam;
- the three poles can be natural teeth, prepared to dental bridge as poles, or implants;
- the left pole must be on a stronger tooth be one degree than the second pole;
- between the three poles there are two missing teeth;
- the distances between the middle of the left pole and the middle of the first missing tooth, between the middle of first missing tooth and the middle of the second pole, between the middle of the second pole and the middle of the second missing tooth, between the middle of the second missing tooth and the middle of the third pole are considered equal each other;
- it is considered that the uniform distributed vertical force act on the dental bridge, as a result of the action of the antagonistic teeth on the jaw, as in Figure 2 and Figure 3.

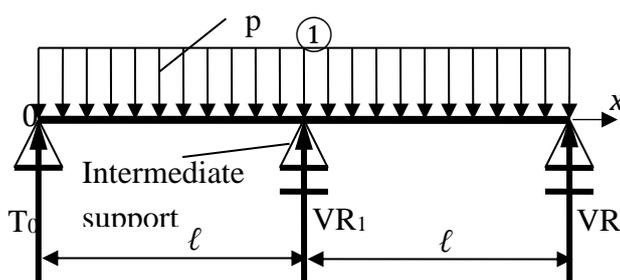


Figure 3. A dental bridge with three poles and two edentulous between the three poles, assimilated as an indeterminate beam with an intermediate support.

The dental bridge shown in Figure 3 can be assimilated as a continuous beam, with the following characteristics:

- the continuous beam is a statically indeterminate beam;
- the beam is considered in the left edge articulated (in the left pole), with a simple support in the right edge (in the right pole) and with an intermediate support on the middle (as the middle pole of the bridge);
- the continuous beam is once statically indeterminate, or simply statically indeterminate beam;
- the uniform distributed vertical load act as in Figure 2 and Figure 3;
- the distances between the supports are noted with l .

3.1.2. Approach of Continuous Beam with an Intermediate Support by TMM

The dental bridge from Figure 2 is assimilated as a continuous beam from Figure 3, that is considered for this study.

It is a continuous beam, articulate at the left edge, with a simple support at the right edge and with a simple intermediate support. The simple support is considered as an intermediate support because it is between the two ends of the continuous beam, between the articulate edge of the left side and the simple support at the right side, as in Figure 3.

The left edge is noted as 0 , i.e. the articulate edge will be called the origin section, considering 0 as the origin of the reference system Ox . The second edge, the simple intermediate support, is noted with 1 and the right edge is noted with 2 .

The density charge $q''(x)$ corresponding of exterior uniform distributed vertical load for the continuous beam from Figure 3, is as (24):

$$q''(x) = -p, \quad (24)$$

and applying the mathematical calculus with Dirac's and Heaviside's functions and operators and the matrix calculus presented in § 2.2.4., for the case of Figure 3, can be obtain the matrix relation (25):

$$\begin{bmatrix} l & -l^2 & 0 \\ 2l & -(2l)^3 & l^3 \\ 0 & -2l & l \end{bmatrix} \begin{Bmatrix} \omega_0 \\ \frac{T_0}{6EI} \\ \frac{VR_1}{6EI} \end{Bmatrix} = \begin{Bmatrix} \frac{pl^4}{24EI} \\ \frac{p(2l)^4}{24EI} \\ \frac{p(2l)^2}{12EI} \end{Bmatrix}, \quad (25)$$

or, (26):

$$\begin{bmatrix} l & -l^2 & 0 \\ 2l & -8l^3 & l^3 \\ 0 & -2l & l \end{bmatrix} \begin{Bmatrix} \omega_0 \\ \frac{T_0}{6EI} \\ \frac{VR_1}{6EI} \end{Bmatrix} = \begin{Bmatrix} \frac{pl^4}{24EI} \\ \frac{2pl^4}{3EI} \\ \frac{pl^2}{3EI} \end{Bmatrix}, \quad (26)$$

It can be writing the matrix relation (26) developed in the form (27):

$$\begin{cases} l\omega_0 - l^2 \frac{T_0}{6EI} = \frac{pl^4}{24EI} \\ 2l\omega_0 - 8l^3 \frac{T_0}{6EI} + l^3 \frac{VR_1}{6EI} = \frac{2pl^4}{3EI}, \\ -2l \frac{T_0}{6EI} + l \frac{VR_1}{6EI} = \frac{pl^2}{3EI} \end{cases} \quad (27)$$

or, (28):

$$\begin{cases} \omega_0 - l \frac{T_0}{6EI} = \frac{pl^3}{24EI} \\ 2\omega_0 - 4l^2 \frac{T_0}{3EI} + l^2 \frac{VR_1}{6EI} = \frac{2pl^3}{3EI}, \\ -T_0 + \frac{VR_1}{2} = pl \end{cases} \quad (28)$$

3.2. Results

(28) is a linear system of three equations with three unknowns. After calculus, the system solution is (29):

$$\begin{cases} T_0 = \frac{3pl}{8} \\ VR_1 = \frac{5pl}{4} \\ \omega_0 = \frac{pl^2}{3EI} \end{cases} \quad (29)$$

The values for T_0 and the reaction in the intermediate support VR_1 are identical to those obtained by solving the problem as a statically indetermined beam from Figure 3, with Clapeyron's equation of the three moments, [2].

The results (29) can be used to calculate moments and shear forces in any section of the beam, as well as deformations y and ω and after then, the stresses in any section of the beam.

4. Discussion

This work presents a new, original and very interesting approach to a calculus problem of beams with intermediate supports by TMM. TMM is a very easy method to program to quickly obtain good results. Some beams with intermediate support can be studied as statically indeterminate continuous beams. It is considered as a statically indeterminate continuous beam, articulate at the left edge, with simple support at the right edge and with intermediate supports. The theoretical approach is presented as in § 2.2. The applicability of this approach is presented for an example in dentistry, the calculus of a dental bridge on three poles. After, that is particularized for an application of a dental restoration case, with a dental bridge on three poles and with two missing teeth between the three poles, assimilated to a simple static indeterminate beam, resting on three supports - the three poles and with two openings, corresponding to the two missing teeth, as in § 3.1. and with the results from § 3.2. The results obtained in the presented case study were validated with those obtained by the classical calculation of the Resistance of Materials, with the equation of the three moments of Clapeyron, [2].

5. Conclusions

This study is a new, original and interesting approach about the problem of intermediate supports of a statically indeterminate beam with TMM. That is very important for many fields, both in industry and in other fields, such as medicine, in occurrence, in dentistry, in dental restorations. The application of TMM calculus can be done very easily in the case of iterative problems, i.e. those problems that require a large volume of repetitive calculus. TMM lends itself very well to its programming, which gives immediate results with fast applicability in practice.

An interesting practical application is the study of a dental crowns and bridges, such as the example presented in § 3.1.2. Due to the ease and elegance of solving various problems with TMM, their approach will continue with other new and original case studies with different modeling and requests, and they will be presented in future research.

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